# Programming Instruction Manual 

## ACPC

## Modular SCR Power Controller



CHROMALOX
Advanced Thermal Technologies

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## ATTENTION!

This manual is an integral part of the product, and must always be available to operators.

This manual must always accompany the product, including if it is transferred to another user.
Installation and/or maintenance workers MUST read this manual and precisely follow all of the instructions in it and in its attachments. Chromalox will not be liable for damage to persons and/or property, or to the product itself, if the following terms and conditions are disregarded.

## Important Safeguards

## aWarning

HIGH VOLTAGE (up to 690 VAC) is used in the operation of this equipment; DEATH ON CONTACT may result if personnel fail to observe safety precautions.
Learn the areas containing high-voltage connections when installing or operating this equipment.

## AWARNING

Be careful not to contact high-voltage connections when installing or operating this equipment.
Before working inside the equipment, turn power off and ground all points of high potential before touching them.

## ACAUTION

The owner/installer must provide all necessary safety and protection devices and follow all current electrical wiring standards and regulations. Failure to do so may compromise the integrity of the controller and/or cause product failure resulting in a safety risk to operational and service personnel.

The Customer is obligated to respect trade secrets. Therefore, this manual and its attachments may not be tampered with, changed, reproduced, or transferred to third parties without Chromalox's authorization.

## ACAUTION

This controller utilizes a heat sink which is designed to cool the unit during operation. Under no circumstance should air flow around the controller be compromised in any way. Failure to do so may result in the overheating of the controller, product failure, product temperatures and even fire.

## AWARNING

During continuous operation, the heat sink can reach very high temperatures, and keeps a high temperature even after the unit is turned off due to its high thermal inertia.
Higher voltages may be present. DO NOT work on the power section without first cutting out electrical power to the panel. Failure to do so may cause serious injury or death.

## AWARNING

ELECTRIC SHOCK HAZARD: Any installation involving control equipment must be performed by a qualified person and must be effectiveIy grounded in accordance with the National Electrical Code to eliminate shock hazard.

## Introduction

The modular power controller described in this manual and shown on the cover is a separate unit for the independent control of a maximum of 3 zones. It offers high applicative flexibility thanks to the extended configurability and programmability of its parameters.

Instrument configuration and programming must be performed with a ACPC-OP or a PC connected in USB/RS232/RS485, with specific C-PWR application soft-ware.

Since it is impossible to foresee all of the installations and environments in which the instrument may be applied, adequate technical preparation and complete knowledge of the instrument's potentials are necessary.


Chronalox declines all liability if rules for correct installation, configuration, and/ or programming are disregarded, as well as all liability for systems upline and/or downline of the instrument.

## Field of Use

The modular power controller is the ideal solution for applications in heat treatment furnaces, in thermoformers, in packaging and packing machines and, in general, in standard temperature control applications. Nevertheless, because it is highly programmable, the controller can also be used for other applications provided they are compatible with the instrument's technical data.

Although the instrument's flexibility allows it to be used in a variety of applications, the field of use must always conform to the limits specified in the technical data supplied.


Chromalox declines all liability for damage of any type deriving from installations, configurations, or programmings that are inappropriate, imprudent, or not conforming to the technical data supplied.

## Prohibited Use

It is absolutely prohibited:

- to utilize the instrument or parts of it (including software) for any use not conforming to that specified in the technical documentation supplied;
- to modify working parameters inaccessible to the operator, decrypt or transfer all or part of the software;
- to utilize the instrument in explosive atmospheres;
- to repair or convert the instrument using non-original replacement parts;
- to utilize the instrument or parts of it without having read and correctly understood the technical documentation supplied;
- to scrap or dispose of the instrument in normal dumps; components that are potentially harmful to the environment must be disposed of in conformity to the regulations of the country of installation..


## Characteristics of Personnel

This manual is intended for technical personnel, who commission the instrument by connecting it to other units, and for service and maintenance personnel.

It is assumed that such persons have adequate technical knowledge, especially in the fields of electronics and automation.

The instrument described in this manual may be operated only by personnel who are trained for their assigned task, in conformity to the instructions for such task and, specifically, to the safety warnings and precautions contained in such instructions.
Thanks to their training and experience, qualified personnel can recognize the risks inherent to the use of these products/systems and are able to avoid possible dangers.

## Structure of this Manual

The instructions in this manual do not replace the safety instructions and the technical data for installation, configuration and programming applied directly to the product or the rules of common sense and safety regulations in effect in the country of installation.
For easier understanding of the controller's basic functions and its full potentials, the configuration and programming parameters are grouped according to function and are described in separate chapters.
Each chapter has from 1 to 3 sections:

- the first section presents a general description of the parameters described in detail in the following zones;
- the second section presents the parameters needed for the controller's basic applications, which users and/or installers can access clearly and easily, immediately finding the parameters necessary for quick use of the controller;
- the third section (ADVANCED SETTINGS ) presents parameters for advanced use of the controller:
this section is addressed to users and/or installers who want to use the controller in special applications or in applications requiring the high performance offered by the instrument.

Some sections may contain a functional diagram showing interaction among the parameters described;

- terms used on other pages of the manual (related or supplemental topics) are shown in underlined italics and listed in the index (linked to IT support).
In each section, the programming parameters are shown as follows:
For reference:

1. ACPC-M refers to master module. A ACPC1 is by de-fault ACPC-M.
2. ACPC-E1 refers to expansion module 1. A ACPC2 would include ACPC-M (as module 1) and ACPC-E1 (as module 2)
3. ACPC-E2 refer to two expansion modules. A ACPC3 would include ACPC-M (as module 1) and ACPC-E2 (as module 2 and 3).


## Communications

The modular power controller's flexibility permits replacement of previous-version such as Chromalox (ACPC), C 4 and $\mathrm{C} 4-\mathrm{IR}$ instruments without changing the control software in use.

Based on the chosen work mode (see MODBUS SERIAL COMMUNICATION), you can use the instrument in 2 different modes:

- ACPC compatible mode: as if there were at most 3 separate instruments (recommended for retrofitting projects and/ or replacement of damaged instruments);
- CF4/ACPC mode: as a single instrument with the same functions as at most 3 separate instruments, but with pos-sibility of interaction among the various parameters, inputs and outputs (recommended for new projects).
New shared parameters, are accessible for both modes and permit more advanced functions such as:
604
FLT.E
R/W
Digital Filter for Auxiliary Input
0.0...20.0 sec
0.1

In addition to having a CUSTOM group of parameters for dynamic addressing, ACPC mode lets you use a single communication network node in-stead of 4 nodes as in Compatible mode.
NOTE! When programming, keep in mind that the addresses (parameters) described in this manual exist 4 times, specified by address node (ID).

ACPC Compatible Mode Diagram


## Serial Communication (Modbus)

There are two Modbus addressing modes for variables and configuration parameters:

- C4 compatible mode
- C4

The modes are selected with dip-switch-7.

## C4 Compatible Mode (Dip-Switch—ON)

This lets you use supervision programs created for C4 modules.
Memory is organized into 4 groups:

- Zone 1 for the variables of the module ACPC-M
- Zone 2 for the variables of the module ACPC-E1
- Zone 3 for the variables of the module ACPC-E2

In each zone, the variables and parameters have the same address as a Geflex instrument; the value (Cod) set on the rotary switches corresponds to that of Zone 1 ; the values in the other zones, if expansions are present, are sequential.

## Examples:

if the rotary switches have value 14 , node 14
addresses Zone 1 (ACPC-M), node 15 Zone 2 (CFWE1), node 16 Zone 3 (ACPC-E2).
The power Ou.P for Zone 1 has address Cod 2, the Ou.P for Zone 2 has address Cod+1, 2, etc...
Parameter out.5, which defines the function of output OUT 5 on the ACPC, has address Cod 611.

## C4/ACPC Mode (Dip-Switch—OFF)

This lets you optimize the efficiency of serial communication by integrating 3 zones in the C4. Memory is organized into 4 groups: 3 already in C4-compatible mode, plus one group defined as custom:

- Custom (additional memory map for dynamic addresses)
- Zone 1 for the variables of the mudule ACPC-M
- Zone 2 for the variables of the mudule ACPC-E1
- Zone 3 for the variables of the mudule ACPC-E2

The custom group contains variables and parameters for a maximum of 120 words. The meaning of these words can be changed.
There is a single value (Cod) set on the rotary switches; i.e., one for each C4/ACPC instrument. To access the data in each zone, simply add an offset to the address (+1024 for Zone 1, +2048 for Zone 2, +4096 for Zone 3).

Words in the custom group have addresses $0, \ldots, 119$. The variables and parameters are defined by default. At addresses 200,...,319 we have words containing the value of the address of the corresponding variables or parameters. These addresses can be changed by the user, offering the ability to read/write data with multiword messages structured according to various supervision requirements.

NOTE: Protection of Maps 1-2. You have to write the value 99 on addresses 600 and 601 to enable change of the custom group (addresses 200... 319). This value is reset at each switch-on.
Examples:
you can access the Ou.P variable in Zone 1 with address Cod, $1+1024$ or address Cod, 11 custom variable 12 (address Cod, 211 has value $2+1024$ );
you can access the Ou.P variable in Zone 2 with address Cod, 2+ 2048 or address Cod, 40 custom variable 41 (address Cod, 240 has value $2+2048$ );
if you want to read the 3 powers in sequence at the first 3 addresses, set Cod, $200=1026$, Cod. $201=2050$, Cod,202 $=4098$.

## Connection

Each ACPC has an optically isolated serial port RS485 (PORT 1) with standard Modbus protocol via connectors J8 and J9 (type RJ10).
You can insert a serial interface (PORT 2). There are various models based on the field bus required: Modbus, Profibus DP, CANopen and Ethernet.
This communication port (PORT 2) has the same Cod address as PORT 1.
The parameters for PORT 2 are bAu. 2 (select baudrate) and Par. 2 (select parity).
The Cod parameter (read only) shows the value of the node address, settable from 00 to 99 with the 2 rotary switches; the hexadecimal settings are reserved.
A parameter can be read or written from both communication ports (PORT 1 and PORT 2).

## AWARNING

Changing the bAu (select baud-rate) and/or PAr (select parity) parameters may cause communication failure.
To set the bAu and PAr parameters, you have to run the Autobaud procedure described in the "Instruction and warnings" manual.

## Installation of the "MODBUS" Serial Network

A network typically has a Master that "manages" communication by means of "commands" and Slaves that interpret these commands.
ACPC are considered Slaves to the network master, which is usually a supervision terminal or a PLC.
They are positively identified by means of a node ad-dress (ID) set on the rotary switches (tens + ones).
ACPC have a ModBus serial (Serial 1) and optional Fieldbus (Serial 2) serial (see order code) with one of the following
protocols: ModBus, Profibus, CANopen, Ethernet, EtherCAT and EthernetIP.

The following procedures are indispensable for the Modbus protocol.
For the remaining protocols, see the specific manuals.
ACPC modules have the following default settings:

- node address $=0(0+0)$
- speed Serial $1=19200$ bit/s
- parity Serial 1 = none
- speed Serial $2=19200 \mathrm{bit} / \mathrm{s}$
- parity Serial 2 = none

You can install a maximum of 99 ACPC modules in a serial network, with node address selectable from "01" to "99" in standard mode, or create a mixed ACPC/C4 network in C4 compatible mode in which each ACPC identifies 3 zones with sequential node address start-ing from the code set on the rotary switches.
In short, the valid rotary switch settings (tens + ones) are:

- $(0+0)=$ Autobaud Serial 1
- $(B+0)=$ Autobaud Serial 2



## Communication Error

If Modbus communication between ACPC and Master node goes into timeout (settable in C.E.t parameter), you can force an output power value (C.E.P parameter of each zone) and transmit the alarm state to a relay output (rL.x parameters).


## Inputs

## INA ANALOG INPUT

The modular power controller has an analog input with the functionality of power control.

| 573 | T明 | R/W | Analog Input 1 | Table of Analog Input |  | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | 0 | Disable |  |
| 837* | TpRe | R/W | Analog Input 2 | 1 | 0...10V | 1 |
| *For models 400-600A Only |  |  |  | 2 | 0...5V / Potentiometer |  |
| 844* | TP93 | R/W | Analog Input 3 | 3 | 0... 20 mA | 1 |
| *For models 400-600A Only |  |  |  | 4 | 4...20mA |  |

## Scale Limits



## Examples of LS.A and HS.A parameter settings

The default values (LS.A = 0.0 and $H S . A=100.0$ ) can be changed to obtain the required scale of the PV in engineering value corresponding to the minimum and maximum of the physical input $(\mathrm{V} / \mathrm{mA})$.
In automatic mode, the engineering value (PV) is attributed to power Ou.P for values between 0.0 and 100.0.

Since the 0...10V input range is reduced $80 \%$ above, the scale interval (HS.A - LS.A) must be extended downward so that the useful interval (100.0-0.0) is $80 \%(100.0 / 125.0=0.8)$.

Since the $0 . .10 \mathrm{~V}$ input range is reduced $90 \%$ below, the scale interval (HS.A - LS.A) must be extended upward so that the useful interval (100.0-0.0) is 90\% (100.0/111.1 $=0.9$ ).

## Example:

$\mathrm{V}_{\mathrm{IN}}=0 . . .10 \mathrm{~V}$
tyP. $=1$
LS.A $=0.0$
$H S . A=100.0$


Example:
$\mathrm{V}_{\mathrm{IN}}=2 \ldots 10 \mathrm{~V}$
tyP. $=1$
LS. $A=-25.0$
$H S . A=100.0$


## Example:

$\mathrm{V}_{\text {IN }}=0 . . .9 \mathrm{~V}$
tyP. $=1$
LS.A $=0.0$ HS.A $=111.1$


Offset Adjustment

| 577 | OFGR | R/W | Offset connection for analog Input 1 | -99.9...99.9 |  | 0.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 841 | DFGRO | R/W | Offset connection for analog Input 2 | -99.9...99.9 |  | 0.0 |
| 848 | NFC日3 | R/W | Offset connection for analog Input 3 | -99.9...99.9 |  | 0.0 |

## Read State

| 572 | Inf | R | Value of the ingegneristico <br> reading analog input 1 |
| :---: | :---: | :---: | :---: |
| 836 | Infl | R | Value of the ingegneristico <br> reading analog input 2 |
| 843 | InR3 | R | Value of the ingegneristico <br> reading analog input 3 |

## Advanced Settings

## Input Filter

| 576 | FTR | R/W | Low pass digital filter analog input 1 | 0.0...20.0 sec. |  | 0.1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 840 | FTRO | R/W | Low pass digital filter analog input 2 | 0.0.. 20.0 sec. |  | 0.1 |
| 847 | FTR3 | R/W | Low pass digital filter analog input 3 | 0.0...20.0 sec. |  | 0.1 |

## Functional Diagram



## Current Value In Load

The RMS current value is read in variable Ld.A of each zone.

If zone 1 has a 3 -phase load, variable Ld.At contains the average value of the three RMS currents. The Ld.A of the first three zones contain the RMS current value on lines L1, L2 and L3, respectively.
Accuracy is better than $1 \%$ in start modes ZC, BF and HSC.

Accuracy is better than $3 \%$ in PA mode with conduction angle $>90^{\circ}$, and better than $10 \%$ for lower conduc-tion angles.
The circulating current in the load is acquired with a 0.2 ms sampling time.
In addition, there are the following parameters for a zone with single-phase load:
I.tA1 instantaneous ammeter value

I1on current with active control
o.tA1 ammeter input offset correction

Ft.tA ammeter input digital filter
There are also the following parameters if zone 1 has a three-phase load:
I.tA1, I.tA2 and I.tA3 instantaneous ammeter value on line L1, L2 and L3
I1on, I2on and I3on current with active control o.tA1, o.tA2 and o.tA3 ammeter input offset correction on line L1, L2 and L3

Ft.tA ammeter input digital filter
If diagnostics detects a fault condition on the load, the red ER LED will flash in synch with yellow LED O1 or O 2 or O 3 for the zone in question.

The condition POWER FAULT in OR with HB alarm can be assigned to an alarm or identified in the state of a bit in variables STATUS, STATUS1, STATUS2 and STATUS3.
In STATUS3 you can identify the condition that activated the POWER_FAULT alarm.
POWER_FAULT diagnostics is configurable with parameter hd.2, with which even just a part may be enabled

SSR SHORT SSR module in short circuit
NO VOLTAGE power failure or interrupted fuse
NO CURRENT due to SSR module open or fuse or load interrupted
For alarm HB (load partially interrupted), refer to the specific section of this manual.
The default value of the maximum limit or ammeter fullscale depends on the model:

| Model | H.tA |
| :---: | :---: |
| 40 A | 80.0 |
| 60 A | 120.0 |
| 100 A | 200.0 |
| 150 A | 300.0 |
| 200 A | 400.0 |
| 250 A | 500.0 |
| 300 A | 600.0 |
| 400 A | 800.0 |
| 600A | 1200 |
| External CT | 1000.0 |

## Scale Limits

| 746 | LTH | R | Minimum limit of CT ammeter input scale（phase 1） |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 747 | LTRE | R | Minimum limit of CT ammeter input scale（phase 2） | with 3－Phase Load |  |
| 748 | LTR3 | R | Minimum limit of CT ammeter input scale（phase 3） | with 3－Phase Load |  |
| 405 | HTR | R | Minimum limit of CT ammeter input scale（phase 1） |  |  |
| 413 | HTRE | R | Minimum limit of CT ammeter input scale（phase 2） | with 3－Phase Load |  |
| 414 | HTらき | R | Minimum limit of CT ammeter input scale（phase 3） | with 3－Phase Load |  |

## Setting the Offset

| 220 | 日TR | R／W | Offset correction CT input （phase 1） | －99．9 ．．．99．9 <br> Scale points |  | $\begin{gathered} 0.0 \\ \text { zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { zone } 3 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 415 | gThe | R／W | Offset correction CT input （phase 2） | －99．9 ．．．99．9 <br> Scale points | With 3－Phase Load | 0.0 |  |  |
| 416 | 9703 | R／W | Offset correction CT input （phase 3） | $-99.9 \ldots 99.9$ <br> Scale points | With 3－Phase Load | 0.0 |  |  |

External CT

| 339 | RT明 | R／W | Offset correction for external CT input | 1．．． 655 | $\begin{gathered} 200 \\ \text { zone } 1 \end{gathered}$ | $\begin{gathered} 200 \\ \text { zone } 2 \end{gathered}$ | $\begin{gathered} 200 \\ \text { zone } 3 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Read State

| $\begin{gathered} 227 \\ 473-139-755 \end{gathered}$ | ITRH | R | Instantaneous CT ammeter input value（phase 1） |  |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & 490 \\ & 494 \end{aligned}$ | TRE | R | Instantaneous CT ammeter input value（phase 2） | With 3－Phase Load |
| $\begin{aligned} & 491 \\ & 495 \end{aligned}$ | 1743 | R | Instantaneous CT ammeter input value（phase 3） | With 3－Phase Load |
| 468 | I！ E月 $^{\text {a }}$ | R | CT filtered ammeter input value with output activated（phase 1） |  |
| 498 | 12［日f | R | CT filtered ammeter input value with output activated（phase 2） | With 3－Phase Load |
| 499 | 1307 | R | CT filtered ammeter input value with output activated（phase 3） | With 3－Phase Load |
| 709 | TTRP | R | Peak ammeter input during phase softstart ramp |  |
| 716 | ［05F | R | Power factor in hundredths |  |
| 753 | L | R | Current RMS on load |  |
| 754 | LnRT | R | Current RMS on 3－phase load |  |

## Advanced Settings

## Input Filter

| 219 FT.TR R/W CT input digital filter |
| :--- |
| Sets a low pass filter on the CT auxiliary input, running |
| the average of values read in the specified time interval. |
| If $=0$, excludes the average filter on sampled values. |

## Functional Diagrams

Monophase load


Threephase load

$\left(^{*}\right)$ with 3-Phase, 2-Leg command the LdA value of zone 3 is gained like average of the Ld.A values of zones 1 and 2

## Voltage Value on Load

RMS voltage is read in variable Ld.V of each zone. If zone 1 has a 3-phase load, variable Ld.V.t in the first zone contains the average RMS value of voltages on three load L1, L2 and L3.
Voltage on the load is acquired with sampling on each cycle, 20 ms at $50 \mathrm{~Hz}(16.6 \mathrm{~ms}$ at 60 Hz ). Accuracy is better than $1 \%$.

The istantaneous RMS voltage value and with activated output,for single zone can be read in the variables Ld.VIS and Ld.Von; Ld.Von values are filtered by Ft.tVL (with option VLOAD) or Ft.tV (without option VLOAD).
If the option VLOAD is not present, the Load RMS voltage value is calculated from the line voltage and from the output power values.

## Read State

| 751 | L. V. V | R | Voltage on load |
| :---: | :---: | :---: | :---: |
| 710 | L.E. V. | R | Load voltage instantaneous |
| 711 | L. VEA | R | Load voltage with <br> output activated |
| 752 | LEV | R | R Voltage on 3-phase load |

if the option VLOAD is present there are available the following parameters:

## Scale Limit

| 439 | LT. VL | R | Minimum limit of TV_LOAD <br> voltmeter input scale |
| :---: | :---: | :---: | :---: |
| 443 | HT. VL | R | Maximum limit of TV_LOAD <br> voltmeter input scale |

## Setting the Offset

| 444 | OT. VL | R/W | Offset correction for TV_LOAD input | -99.9 ...99.9 scale points | $\begin{gathered} 0.0 \\ \text { zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { zone } 3 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

## Advanced Settings

Input Filter

| 442 | FT.T VL. | RW | Digital filter ingress trans- <br> former voltmetrics TV_LOAD | $0.0 . .20 .0 \mathrm{sec}$ |  | 0.1 | 0.1 | 0.1 |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: |
| zone 1 | zone 2 | zone 3 |  |  |  |  |  |  |

## Functional Diagram

Single-Phase Load without VLOAD option


Single-Phase Load with VLOAD option


## Functional Diagram

Three-Phase Load without VLOAD option


Three-Phase Load with VLOAD option


## Line Voltage Value

There are the following parameters if zone 1 has a sin-gle-phase load:
I.tV1 instantaneous voltmeter value of line
I.VF1 filtered voltmeter value
o.tV1 voltmeter input offset correction

Ft.tV voltmeter input digital filter

There are the following parameters if zone 1 has a 3-phase load:
I.tV1, I.tV2 and I.tV3, the instantaneous voltmeter value on line L1, L2 and L3, respectively.
RMS voltage values refer to voltage between 1/L1 and 3/L2 terminals.
I.VF1, I.VF2 and I.VF3 filtered voltmeter value on line L1, L2 and L3
o.tV1, o.tV2 and o.tV3 voltmeter input offset correction on line L1, L2 and L3.
Each phase has a voltage presence check that shuts off the module in case of incorrect values.
3-phase loads have an imbalance diagnostic, with consequent shut-down of the load and signal via LEDs.

A "voltage status" parameter contains information on the status of line voltage, including mains frequency identified $50 / 60 \mathrm{~Hz}$.

3-phase loads have diagnostics for correct phase connection, lack of a voltage, or imbalance of the three line voltages.

Scale Limits

| 453 | LTV | R | Minimum limit of TV voltmeter <br> input scale (phase 1) |  |  |  |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| 454 | LTVE | R | Minimum limit of TV voltmeter <br> input scale (3-phase, 2-leg) |  | with 3-Phase Load |  |
| 455 | LTVE | R | Minimum limit of TV voltmeter <br> input scale (3-phase, 3-leg) |  | with 3-Phase Load |  |
| 410 | HT V | R | Maximum limit of TV voltmeter <br> input scale (phase 1) |  |  | with 3-Phase Load |

## Setting the Offset

| 411 | OTH | R/W | Offset correction TV input <br> (phase 1) | $-99.9 \ldots 99.9$ <br> Scale points |  | 0.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| zone 1 |  |  |  |  |  |  | | 0.0 |
| :---: |
| zone 2 |$\quad$| 0.0 |
| :---: |
| zone 3 |

Read State

| $\begin{array}{r} 232 \\ 485 \end{array}$ | ITH | R | Value of voltmeter input (phase 1) |  |
| :---: | :---: | :---: | :---: | :---: |
| 492 | TTH2 | R | Value of voltmeter input (3-phase, 2-leg) | With 3-Phase Load |
| 493 | 1743 | R | Value of voltmeter input (3-phase, 3-leg) | With 3-Phase Load |
| 322 | ! VFI | R | Value Filtered of voltmeter input (phase 1) |  |
| 496 | ! VFE | R | Value Filtered of voltmeter input (3-phase, 2-leg) | With 3-Phase Load |
| 497 | ! VFI | R | Value Filtered of voltmeter input (3-phase, 3-leg) | With 3-Phase Load |


| 702 |  |  | Voltage status | Table Voltage Status |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Bit |  |
|  |  |  |  | 0 | frequency_warning |
|  |  |  |  | 1 | 10\% umbalanced_line_warning |
|  |  |  |  | 2 | 20\% umbalanced_line_warning |
|  |  |  |  | 3 | 30\% umbalanced_line_warning |
|  |  |  |  | 4 | rotation 123_error |
|  |  |  |  | 5 | triphase_missing_line_error |
|  |  |  |  | 6 | 60 Hz |
| 315 | FREG | E | Voltage frequnecy in tenths of Hz |  |  |

## Advanced Settings

## Input Filter

| 412 | FTT I! | R/W | Digital filter for voltmeter transformer TV input | 0.0 .. 20.0 sec | $\begin{gathered} 2.0 \\ \text { zone } 1 \end{gathered}$ | $\begin{gathered} 2.0 \\ \text { zone } 2 \end{gathered}$ | $\begin{gathered} 2.0 \\ \text { zone } 3 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Sets a low pass filter on the auxiliary TV input, running the average of values read in the specified time interval. If $=0$, excludes the average filter on sampled values.

## Functional Diagram

Line Voltage Value Single Phase


Line Voltage Value 3-Phase


Variable I.tV1


Variable I.tV2


## Power On Load

Power on the load in each zone is read in variable Ld.P and the corresponding energy value in variables Ld.E1 and Ld.E2.

These energy values show the value accumulated since the first power on or since the last reset (commands at bits 114 and 115); non-volatile memory is updated every two hours and the disconnection of the power off.

Load impedance in each zone is read in variable Ld.I.
If zone 1 has a 3-phase load, variable Ld.P.t shows power and Ld.I.t total impedance, the corresponding energy value in variables Ld.E1.t and Ld.E2.t.
Note that for loads such as IR lamps, impedance can vary greatly based on the power transferred to the load.

| $\begin{gathered} 880 \\ 719 \text { LSW } \\ \text { only } \end{gathered}$ | LDP | R | Power on load | Data in DWORD (32 bit) format for address 880* LSW data in WORD (16 bit) format for address 719* |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 882 \\ \begin{array}{c} 720 \text { LSW } \\ \text { only } \end{array} \end{gathered}$ | L-APT | R | Power on Load 3-Phase | Data in DWORD (32 bit) format for address 882 LSW data in WORD (16 bit) format for address 720 |
| 749 | L | R | Impedance on load |  |
| 750 | LDT | R | Impedance on load 3-phase |  |
| 531 | LDEt | R | Energy on load | Data in DWORD (32 bit) format |
| 541 | L84T | R | Energy on 3-phase load | Data in DWORD (32 bit) format |
| 510 | LDEC | R | Energy on load | Data in DWORD (32 bit) format |
| 541 | L 18 | R | Energy on 3-phase load | Data in DWORD (32 bit) format |
| 114 bit | LREI | R/W | $\begin{aligned} & \text { OFF = - } \\ & \text { ON = Reset Ld.E1 } \end{aligned}$ |  |
| 115 bit | LHED | R/W | $\begin{aligned} & \text { OFF = - } \\ & \text { ON = Reset Ld.E1 } \end{aligned}$ |  |

## Functional Diagram

## Single-phase load



## Functional Diagram

## 3-phase load


(*) with BI-PHASE command the Ld.A value of zone 3 is gained like average of the Ld.A values of zones 1 and 2


## Digital Inputs (40-300A Models)

There are always two inputs. Each input can perform various functions based on the setting of the following parameters:


## Read State

| $\begin{aligned} & 68 \\ & \text { bit } \end{aligned}$ | State of Digital Input 1 | R | OFF = Digital input 1 off R ON = Digital input 1 on |  |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & 92 \\ & \text { bit } \end{aligned}$ | State of Digital Input 2 | R | OFF = Digital input 2 off <br> R ON = Digital input 2 on |  |
| $\begin{aligned} & 67 \\ & \text { bit } \end{aligned}$ | State of Digital Input 3 | R | OFF = Digital input 3 off R ON = Digital input 3 on |  |
| 317 |  | R | Sate of INPUT DIG digital inputs | bit. 0 = state INDIG1 <br> bit. 1 = state INDIG2 <br> bit. 2 = state INDIGB |
| 518 | In.PWM | R | PWM input value | 0.0...100.0\% |

## Functions Related to Digital Inputs

- MAN / AUTO controller $\qquad$
- LOC / REM.................................................... see SETTING THE SETPOINT
- HOLD ............................................................. see HOLD FUNCTION
- Reset memory latch...................................... see GENERIC ALARMS AL1 .. AL4
- Select SP1 / SP2
see SETTINGS - Multiset
- Software OFF / ON
see SOFTWARE SHUTDOWN
- START / STOP Selftuning
see SELFTUNING
- START / STOP Autotuning
see AUTOTUNING
- Calibration of feedback reference
see FEEDBACK
- Calibration of HB alarm setpoint
see HB ALARM


## Digital Inputs (400-600A Models)

There are always two inputs. Each input can perform various functions based on the setting of the following parameters:


| 385 | TP聂 | R/W | Defining type of digital inputs |
| :--- | :--- | :--- | :--- |


| Table defining type of digital inputs |  |  |
| :---: | :--- | :---: |
| 0 | PNP Digital Inputs |  |
| 1 | NPN or voltage-free contact digital inputs |  |

## Advanced Settings

NOTE: if the digital input is used to command the power \% (Ou.P) on the load (PWM input function, diG = 7), it is important to set Timeout parameter PWm.t to a value equal to or higher than the period of the PWM control signal used to guarantee this reaction time even in static conditions of low input (Ou.P=0\%) or high input (Ou.P=100\%).

Timeout for PWM Input

| 356 | PWMt 1 | R/W | Timeout for PWM input 1 | $0.01 \ldots 10.00$ sec. | 1.00 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 357 | PWMt 2 | R/W | Timeout for PWM input 2 | $0.01 \ldots 10.00$ sec. | 1.00 |
| 362 | PWMt 3 | R/W | Timeout for PWM input 3 | $0.01 \ldots 10.00$ sec. | 1.00 |

Input Filter - PWM Input


## Read State

| $\begin{aligned} & 68 \\ & \text { Bit } \end{aligned}$ | State of Digital Input 1 | R | OFF = Digital input 1 off <br> R ON = Digital input 1 on |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & 92 \\ & \text { Bit } \end{aligned}$ | State of Digital Input 2 | R | OFF = Digital input 2 off <br> R ON = Digital input 2 on |
| $\begin{aligned} & 67 \\ & \text { Bit } \end{aligned}$ | State of Digital Input 3 | R | OFF = Digital input 3 off <br> R ON = Digital input 3 on |
| $\begin{aligned} & 66 \\ & \text { Bit } \end{aligned}$ | State of Digital Input 4 | R | OFF = Digital input 4 off R ON $=$ Digital input 4 on |

$\left.\begin{array}{|c|c|c|c|c|}\hline 317 & & \text { R } & \begin{array}{l}\text { bit.0 }=\text { state INDIG1 } \\ \text { bit.1 }=\text { state INDIG2 }\end{array} \\ \text { bit.2 }=\text { state INDIG3 } \\ \text { bit.2 }=\text { state INDIG4 }\end{array}\right]$

## Functions Related to Digital Inputs

- MAN / AUTO controller. see AUTO/MAN CONTROL
- Reset memory latch see GENERIC ALARMS AL1 .. AL4
- Software OFF / ON see SOFTWARE SHUTDOWN
- Calibration of feedback reference ................. see FEEDBACK
- Calibration of HB alarm setpoint see HB ALARM


## Using a Function Associated with Digital Input and Via Serial

At power-on or on the leading edge of digital input 1 or 2, all zones assume the state set by the digital input. For each zone, this state can be changed by writing via serial.
The setting via serial is saved in eeprom (STATUS_W_EEP, address 698).

| State A/B | Setting dIG. or dIG. 2 | Address for writing via serial |  |
| :---: | :---: | :---: | :---: |
|  |  | Access at 16 bit | access at 1 bit |
| AUTO/MAN controller | 1 | word 305 bit 4 | bit 1 |
| LOC/REM setpoint (**) | 2 | word 305 bit 6 | bit 10 |
| SP1/SP2 setpoint (**) | 5 | word 305 bit 1 | bit 75 |
| ON/OFF software | 6 | word 305 bit 3 | bit 11 |
| STOP/START selftuning (**) | 8 | word 305 bit 2 | bit 3 |
| STOP/START autotuning (*) (**) | 9 | word 305 bit 5 | bit 29 |

(*) continuous or one-shot
${ }^{* *}$ ) only for zone 1 (ACPC-
M)


## Using a Function of Digital Input 1 to Enable at Software ON

Software ON can be configured either by enabling a digital input or by writing via serial. Enabling by digital input 1 (diG) is common to all zones, whereas enabling via serial is specific for each individual zone.

The ON/OFF setting via serial is saved in eeprom (STATUS_W_EEP, address 698 bit 3) for resetting of the condition at the next hardware power-on; use parameter P.On.t. to force software always ON or software always OFF at next power-on.

|  | Setting | Address for writing via serial |  |
| :--- | :---: | :---: | :---: |
|  |  | dIG | Access at 16 bit |
|  | 13 | word 305 bit 3 | access at 1 bit |



## Alarms

## Generic Alarms AL1, AL2, AL3 and AL4

Four generic alarms are always available and can perform various functions.
Typically, alarm AL. 1 is defined as minimum and AL. 2 as maximum.
These alarms are set as follows:

- select the reference variable to be used to monitor the value (parameters A1.r, A2.r, A3.r and A4.r): the origin of the variable can be chosen from the process variable PV (generally linked to the main input), the ammeter input, the voltmeter input, the auxiliary analog input, or the active setpoint.
- set the value of the alarm setpoint (parameters AL.1, AL.2, AL. 3 and AL.4).
This value is used for comparison with the reference variable value: it can be absolute or indicate a shift from the variable in case of deviation alarm.
- set the hysteresis value for the alarm (parameters Hy.1, Hy.2, Hy. 3 and Hy.4):
the hysteresis value defines a band for safe re-entry of the alarm condition: without this band, the alarm would be deactivated as soon as the reference variable re-entered the setpoint limits, with the possibility of generating another alarm signal in the presence of oscillations of the reference signal around the setpoint value.


For AL1 reverse absolute alarm (low) with positive Hyst1, AL1 $\mathrm{t}=1$ (*) $=$ OFF
if disabled at switch on
For AL2 direct absolute alarm (high) with negative Hyst2, AL2 $\mathrm{t}=0$


For AL1 $=$ normal inverse deviation alarm with negative Hyst 1, AL1 $t=3$ For AL1 = normal direct deviation alarm with negative Hyst 1, AL1 $t=2$

- select alarm type:
- absolute/deviation: if the alarm refers to an absolute value or to another variable (for example, to the setpoint).
- direct/reverse: if the reference variable exceeds the alarm setpoint in the "same direction" as the control action or not. For example, the alarm is direct if the reference variable exceeds the upper setpoint value during heating or assumes values below the lower setpoint during cooling. In the same manner, the alarm is reverse if the reference variable assumes values below the lower setpoint during heating or exceeds the setpoint during cooling.
- normal/symmetrical: if band value is subtracted or added, respectively, to/from the upper and lower limit of the alarm setpoints or indicates a higher and lower band compared to the alarm setpoint.
- with/without disabling at switch-on: if you want to check the reference variable value at system switch-on or wait until the variable enters the control window.
- with/without memory: if the alarm signal persists even when the cause has been eliminated or stops when the variable returns to normal values.
The above concepts are better explained in the following figures:


For AL1 $=$ symmetrical inverse absolute alarm with Hyst1, AL1 $t=5$
For AL1 $=$ symmetrical direct absolute alarm with Hyst1, AL1 $\mathrm{t}=4$
Minimum hysteresis $=2$ scale points
Allarme relativo al setpoint di tipo simmetrico


For AL1 = Symmetrical inverse deviation alarm with Hyst 1, AL1 $t=7$ For AL1 $=$ Symmetrical direct deviation alarm with Hyst 1, AL1 $t=6$

Reference Variables

| 215 | RHR | R/W | Select Reference Variable Alarm 1 | Table of Alarm Reference Setpoints |  |  | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Type | Variable to be Compared | Reference Setpoint |  |
|  |  |  |  | 0 | PV (process variable) | AL |  |
| 216 | HPR | R/W | Select Reference Variable Alarm 2 | 1 | in.tA1 (In.tA1 OR <br> In.tA2 OR In.tA3 With <br> 3-phase load) | AL | 0 |
| 217 |  |  |  | 2 | In.tV1 (In.tV1 OR In.tV2 OR In.tV3 With 3-phase load) | AL |  |
|  | QIR | R/W | Select Reference Variable Alarm 3 | 3 | SPA (active setpoint) | AL (absolute only) |  |
| 218 |  |  |  | 4 | PV (variabile di processo) | AL (absolute only, refer to SP1 (with functional multiset) | 0 |
|  | R4R | R/W | Select Reference Variable Alarm 4 | 5 | In. 2 auxiliary input | AL |  |
|  |  |  |  | 6 | In. 3 auxiliary input | AL |  |
|  |  |  |  | 7 | In. 4 auxiliary input | AL | 0 |
|  |  |  |  | 8 | In. 5 auxiliary input | AL |  |
|  |  |  |  | 9 | In.A analg input | AL |  |
|  |  |  |  | 10 | In.Pwm PWM input | AL |  |
|  |  |  |  | N.B. for codes $1,2,5,6,7,8,9$ and 10 the reference to the alarm is in scale points and not to the decimal point (dP.x) |  |  |  |

## Alarm Setpoints

| $\begin{gathered} 12 \\ 475-177 \end{gathered}$ | Pt- | R/W | Alarm setpoint 1 (scale points) | -999... 999 if alarm symetrical <br> $0 . . .999$ if alarm relative and symetrical | 500 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 13 \\ 476-178 \end{gathered}$ | PL己 | R/W | Alarm setpoint 2 (scale points) | -999... 999 if alarm symetrical $0 . . .999$ if alarm relative and symetrical | 100 |
| $\begin{gathered} 14 \\ 52-479 \end{gathered}$ | Rţ | R/W | Alarm setpoint 3 (scale points) | -999... 999 if alarm symetrical <br> 0... 999 if alarm relative and symetrical | 700 |
| $\begin{aligned} & 58 \\ & 480 \end{aligned}$ | PH4 | R/W | Alarm setpoint 4 (scale points) | -999... 999 if alarm symetrical $0 . . .999$ if alarm relative and symetrical | 800 |

## Alarm Hysteresis

| $\begin{aligned} & 27 \\ & 187 \end{aligned}$ | HUH | R/W | Hysterisis for Alarm 1 | $\pm 999$ <br> Scale points | $0 . . .999$ sec. $\mathrm{Se}+32$ in A1.t <br> 0... 999 min. Se +64 in A1.t | -1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 30 \\ 188 \end{gathered}$ | HUP | R/W | Hysterisis for Alarm 2 | $\pm 999$ <br> Scale points | $0 . . .999$ sec. Se +32 in A1.t <br> 0... 999 min. Se +64 in A1.t | -1 |
| $\begin{aligned} & 53 \\ & 189 \end{aligned}$ | Hリ3 | R/W | Hysterisis for Alarm 3 | $\pm 999$ <br> Scale points | $\begin{aligned} & \text { 0... } 999 \text { sec. Se }+32 \text { in A1.t } \\ & 0 . .999 \text { min. Se }+64 \text { in A1.t } \end{aligned}$ | -1 |
| 59 | H44 | R/W | Hysterisis for Alarm 4 | $\pm 999$ <br> Scale points | $0 . . .999$ sec. Se +32 in A1.t <br> $0 . . .999$ min. Se +64 in A1.t | -1 |

Alarm Type

| 406 | 明. | R/W | Alarm Type 1 |
| :---: | :---: | :---: | :---: |
| 407 | RE. 7 | R/W | Alarm Type 2 |
| $\begin{aligned} & 408 \\ & (54) \end{aligned}$ | R3. 7 | R/W | Alarm Type 3 |
| 409 | 84 | R/W | Alarm Type 4 |


| Table of Alarm behavior |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| AL.x.t | Direct (High Limit) <br> Inverse (Low Limit) | Absolute <br> Relative | Normal <br> Symmetrical <br> (Window) |  |
| 0 | direct | absolute | normal | 0 |
| 1 | inverse | absolute | normal | 0 |
| 2 | direct | relative | normal |  |
| 3 | inverse | relative | normal | 0 |
| 4 | direct | absolute | symmetrical | 0 |
| 5 | inverse | absolute | symmetrical |  |
| 6 | direct | relative | symmetrical | 0 |
| 7 | inverse | relative | symmetrical | 0 |
| 8 |  |  |  |  |

- 8 to disable at switch-on until first setpoint
- 16 to enable memory latch
- 32 Hys becomes delay time for activation of alarm (0... 999 sec.) (excluding absolute symmetrical)
- 64 Hys becomes delay time for activation of alarm (0... 999 min.) (excluding absolute symmetrical)
- 136 to disable at switch-on or at change of setpoint until first setpoint
- 256 only for alarms with memory and delay time: the delay time becomes a timed hysteresis (with time stopped in case of SBR condition: when SBR condition disappears the delay time starts counting from zero)

| 46 bit | AL1 Direct/Inverse | R/W |
| :---: | :---: | :---: |
| 47 bit | AL1 Absolute/Relative | R/W |
| 48 bit | AL1 Normal/Symmetrical | R/W |
| 49 bit | AL1 Disabled at Switch-On | R/W |
| 50 bit | AL1 with Memory | R/W |
| 54 bit | AL2 Direct/Inverse | R/W |
| 55 bit | AL2 Absolute/Relative | R/W |
| 56 bit | AL2 Normal/Symmetrical | R/W |
| 57 bit | AL2 Disabled at Switch-On | R/W |
| 58 bit | AL2 With Memory | R/W |
| 36 bit | AL3 Direct/Inverse | R/W |
| 37 bit | AL3 Absolute/Relative | R/W |
| 38 bit | AL3 Normal/Symmetrical | R/W |
| 39 bit | AL3 Disabled at Switch-On | R/W |
| 40 bit | AL3 With Memory | R/W |
| 70 bit | AL4 Direct/Inverse | R/W |
| 71 bit | AL4 Normal/Symmetrical | R/W |
| 72 bit | AL4 Normal/Symmetrical | R/W |
| 73 bit | AL4 Disabled at Switch-On | R/W |
| 74 bit | AL4 With Memory | R/W |

## Enable Alarms

| 195 | H2. | R/W | Select Number of Enabled Alarms | Table of Enabled Alarms |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | AL.nr | Alarm 1 | Alarm 2 | Alarm 3 | Alarm 4 | 0 |
|  |  |  |  | 0 | disabled | disabled | disabled | disabled |  |
|  |  |  |  | 1 | enabled | disabled | disabled | disabled |  |
|  |  |  |  | 2 | disabled | enabled | disabled | disabled |  |
|  |  |  |  | 3 | enabled | enabled | disabled | disabled |  |
|  |  |  |  | 4 | disabled | disabled | enabled | disabled |  |
|  |  |  |  | 5 | enabled | disabled | enabled | disabled |  |
|  |  |  |  | 6 | disabled | enabled | enabled | disabled |  |
|  |  |  |  | 7 | enabled | enabled | enabled | disabled |  |
|  |  |  |  | 8 | disabled | disabled | disabled | enabled |  |
|  |  |  |  | 9 | enabled | disabled | disabled | enabled |  |
|  |  |  |  | 10 | disabled | enabled | disabled | enabled |  |
|  |  |  |  | 11 | enabled | enabled | disabled | enabled |  |
|  |  |  |  | 12 | disabled | disabled | enabled | enabled |  |
|  |  |  |  | 13 | enabled | disabled | enabled | enabled |  |
|  |  |  | +16 to enable HB alarm | 14 | disabled | enabled | enabled | enabled |  |
|  |  |  | +32 to enable LBA alarm | 15 | enabled | enabled | enabled | enabled |  |

## Reset Memory Latch



## Read State



Functional Diagram


## Loop Break Alarms

This alarm identifies incorrect functioning of the control loop due to a possible load break or to a short circuited or reversed probe.
With the alarm enabled (parameter AL.n), the instrument checks that in condition of maximum power delivered for a settable time (Lb.t) greater than zero,
the value of the process variable increase in heating or decreases in cooling: if this does not happen, the LBA alarm trips. In these conditions, power is limited to value (Lb.P).
The alarm condition resets if the temperature increases in heating or decreases in cooling.

Enable Alarm


## Read State

| 8 |  |  |  |
| :---: | :---: | :---: | :---: |
| bit | State of LBA Alarm | R | OFF = LBA Alarm off <br> ON = LBA Alarm on |

## Functional Diagram



## HB Alarm (Heater Break Alarm)

This type of alarm identifies load break or interruption by measure the current delivered by means of a current transformer.
The following three fault situations may occur:

- delivered current is lower than nominal current: this is the most common situation, and indicates that a load element is breaking.
- delivered current is higher than nominal current: this situation occurs, for example, due to partial short circuits of load elements.
- delivered current remains significant even during periods in which it should be zero: this situation occurs in the resence of pilot circuits for the shortcircuited load or due to relay contacts soldered together. In these cases, prompt action is very important to prevent greater damage to the load and/ or to the pilot circuits.
In standard configuration, output SSR is associated to heating control in zone 1, obtained by modulating electrical power with the ON/OFF control based on the set cycle time.
The current read performed during the ON phase identifies an anomalous shift from the rated value due to a load break (first two fault situations described above), while the current read performed during the OFF phase identifies a break in the control relay, with consequent output always active (third fault situation).
The alarm is enabled by means of parameter AL.n; select the type of function you want by means of parameter Hb.F:
Hb.F=0: alarm activates if the current load value is below the setpoint value set in A.Hbx while the SSR control output is ON.
Hb.F=1: alarm activates if the current load value is above the setpoint value set in A.Hbx while the SSR control output is OFF.
Hb.F=2: alarm activates by combining functions 0 and 1, considering the setpoint of function 1 as $12 \%$ of the ammeter full scale defined in H.tAx.
Hb.F=3 or Hb.F=7 (continuous alarm): alarm activates due to a load current value below the setpoint value set in A.Hbx; this alarm does not refer to the cycle time and is disabled if the heating (cooling) output value is below 3\%.
Setting A.Hbx = 0 disables both types of HB alarm by forcing deactivation of the alarm state.
The alarm resets automatically if its cause is eliminated.
An additional configuration parameter for each zone, related to the HB alarm is:
Hb.t = delay time for activation of HB alarm, understood as the sum of times for which the alarm is considered active.

For example, with:

- Hb.F $=0$ (alarm active with current below setpoint value),
- Hb.t $=60$ sec and cycle time of control output $=10$ sec,
- power delivered al 60\%,
the alarm will activate after 100 sec (output ON for 6 sec each cycle);
if power is delivered at $100 \%$, the alarm will activate after 60 sec .
If the alarm deactivates during this interval, the time sum is reset.
The delay time set in Hb.t must exceed the cycle time of the SSR output.
If zone 1 has a 3-phase load, you can set three different setpoints for the HB alarm:
A.Hb1 = alarm setpoint for line L1
A.Hb2= alarm setpoint for line L2
A.Hb3= alarm setpoint for line L3


## Function: HB Alarm Setpoint Self-Learning

This function permits self-learning of the alarm setpoint.
To use this function, you first have to set parameter Hb.P, which defines the percentage of current compared to rated load below which the alarm trips.
The function can be activated via control from serial line, digital input (see parameter dIG or dIG.2) or by key (see HW/SW Information-Key Features).
When the Teach-in function is activated in modes ZC, BF and HSC, the RMS current value in conduction ON multiplied by parameter Hb.P determines the HB alarm setpoint.
When the Teach-in function is activated in mode PA NO infrared lamps, the existing RMS current value is shown at $100 \%$ of power, which, multiplied by parameter Hb.P, determines the HB alarm setpoint. Before activating the function, it is necessary that the ACPC is switched on with power, it is recommended, above 50\%.
In the case of HSC mode or PA for IR lamps (see parameter Hd. 5 option +128 ), the function activates automatic reading of the power/current curve useful for determining the HB alarm setpoint.

Automatic reading of the power/current curve takes place with the following sequence:

- softstart at maximum power (default 100\%), 5 sec. delay
- reduction of power to $50 \%, 30 \%, 20 \%, 15 \%, 10 \%$, $5 \%, 3 \%, 2 \%, 1 \%$, between every value 5 sec . delay
- return to normal operation.

Maximum conduction value in this phase can be limited by means of the PS. Hi parameter.

If requested, MUST be activated only with Hd.6=0 (the required Hd .6 value can be set only after calibration).
In case of HSC firng mode, the Heater Break alarm teach-in function doesn't calibrate at $5 \%, 3 \%, 2 \%$ and $1 \%$ in order to avoid
high peak currents due to the low impedence at very low temperature of the IR lamp filament.

## Enable Alarm

| 195 | Plif | R/W | Select number of enabled alarms |  |  |  |  | See Table of Enabled Alarms | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 57 | HBF | R/W | HB Alarm Functions |  |  |  |  | Table of HB Alarm Functions | 0 |
| Default: <br> SINGLE-PHASE LOAD: each A.HbX refers to its respective phase. 2-PHASE LOAD: single reference setpoint A.Hb1 and OR between phases 1, 2 and phases 3, 4. <br> 3-PHASE LOAD: single reference setpoint A.Hb1 and OR among phases 1, 2 and 3. <br> +8 HB reverse alarm <br> +16 relates to single setpoints and singled phases WITH <br> 3-PHASE LOAD |  |  |  |  |  |  | Val. <br> 0 <br> 0 <br> 1 <br> 2 <br> 3 <br> 7 | Description of functions <br> Relay, logic output: alarm active at a load current value below set point for control output ON time. <br> Relay, logic output: alarm active at a load current value above set point for control output OFF time. <br> Alarm active if one of functions 0 and 1 is active (OR logic between functions 0 and 1) (*) <br> Continuous heating alarm <br> Continuous cooling alarm <br> nimum setpoint is set at $12 \%$ of ammeter full scale |  |
| 56 | HB.T | R/W | Delay | time f of HB | activation arm |  |  | The value must exceed the cycle time of the 0 ... 999 sec output to which the HB alarm is associated. | 25.0 |
| $\begin{aligned} & 112 \\ & \text { bit } \end{aligned}$ | Calib setp | $\begin{aligned} & n \mathrm{HB} \\ & \mathrm{t} \text { for } \mathrm{Zc} \end{aligned}$ | alarm ne | R/W | Delay time of HB | activa <br> rm |  | NB: In case of 3-phase load, you can set a differ ue for parameter A.Hb1, A.Hb2, A.Hb3 for each (ex.: to control an unbalanced 3-phase load | ent zone |

Alarm Setpoints

| 55 | HHE | R／W | HB alarm setpoint（scale points ammeter input－Phase 1） |  | $\begin{gathered} 10.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 10.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 10.0 \\ \text { Zone } 3 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 502 | FHOE | R／W | HB alarm setpoint（scale points ammeter input－Phase 2） | With 3－p | 10.0 |  |  |
| 503 | 9483 | R／W | HB alarm setpoint（scale points ammeter input－Phase 3） | With 3－ | 10.0 |  |  |
| 737 | Hop | R／W | Percentage HB alarm setpoint of current read in HB calibration | 0．0 ．．．100．0\％ | $\begin{gathered} 80.0 \\ \text { Zone } 1 \end{gathered}$ | $80.0$ $\text { Zone } 2$ | $\begin{gathered} 80.0 \\ \text { Zone } 3 \end{gathered}$ |
| 742 | HRTR | R／W | CT read in HB calibration |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 452 | HETV | R／W | TV read in HB calibration |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 743 | Hep w | R／W | Ou．P power in calibration |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 758 | RTR日 | R／W | HB calibration with IR lamp current at 100\％conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 759 | 促忶 | R／W | HB calibration with IR lamp current at $50 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 760 | IRTRE | R／W | HB calibration with IR lamp current at $30 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 761 | RTR3 | R／W | HB calibration with IR lamp current at 20\％conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 767 | IRTRU | R／W | HB calibration with IR lamp current at $15 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 768 | RTR5 | R／W | HB calibration with IR lamp current at 10\％conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 769 | IRTHE | R／W | HB calibration with IR lamp （only in mode PA） current at 5\％conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 382 | RTR7 | R／W | HB calibration with IR lamp （only in mode PA） current at 3\％conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 383 | $1 \mathrm{RTH8}$ | R／W | HB calibration with IR lamp <br> （only in mode PA） current at 2\％conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 384 | RTR9 | R／W | HB calibration with IR lamp <br> （only in mode PA） current at 1\％conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 445 | 保 V V | R／W | HB calibration with IR lamp Voltage at $100 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 446 | 促 V | R／W | HB calibration with IR lamp Voltage at $50 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 447 | RT Ve | R／W | HB calibration with IR lamp Voltage at $30 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 448 | 片TV3 | R／W | HB calibration with IR lamp Voltage at $20 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |


| 449 | RT WH | R/W | HB calibration with IR lamp Voltage at $15 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | 0.0 Zone 2 | $\left\lvert\, \begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}\right.$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 450 | IRT VS | R/W | HB calibration with IR lamp Voltage at $10 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | 0.0 Zone 2 | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 451 | RTVE | R/W | HB calibration with IR Iamp <br> (only in mode PA) <br> Voltage at 5\% conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | 0.0 Zone 2 | 0.0 Zone 3 |
| 390 | RT Vi | R/W | HB calibration with IR lamp (only in mode PA) <br> Voltage at $100 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 391 | RT VB | R/W | HB calibration with IR lamp (only in mode PA) <br> Voltage at $100 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 392 | RT V9 | R/W | HB calibration with IR lamp <br> (only in mode PA) <br> Voltage at $1 \%$ conduction |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |

## Read State




|  | Table of HB Alarm States |
| :---: | :--- |
| Bit |  |
| 0 | HB TA2 time ON |
| 1 | HB TA2 time OFF |
| 2 | HB alarm TA2 |
| 3 | HB TA3 time ON |
| 4 | HB TA3 time OFF |
| 5 | HB alarm TA3 |


| 512 | R | States of alarm ALSTATE (for single-phase loads) |  |  | Table of alarm states ALSTATE |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | Bit |  |
|  |  |  |  |  | 4 | HB alarm time ON |
|  |  |  |  |  | 5 | HB alarm time OFF |
|  |  |  |  |  | 6 | HB alarm |
| 318 | R | States of alarm ALSTATE IRQ | States of alarm table |  |  |  |
|  |  |  | Bit |  |  |  |
|  |  |  | 0 | State AL. 1 |  |  |
|  |  |  | 1 | State AL. 2 |  |  |
|  |  |  | 2 | State AL. 3 |  |  |
|  |  |  | 3 | State AL. 4 |  |  |
|  |  |  | 4 | State AL.HB (if 3-phase or phase 1/2/3) or Power Fault |  |  |
|  |  |  | 5 | State AL.HB PHASE 1 (if 3-phase) |  |  |
|  |  |  | 6 | State AL.HB PHASE 2 (if 3-phase) |  |  |
|  |  |  | 7 | State AL.HB PHASE 3 (if 3-phase) |  |  |

## Functional Diagram



NOTE:
the value of setpoint Hb .tr for the HB alarm is calculated in two dferent ways, depending on the selected function mode:

```
if ZC, BF, HSC mode:
```

$\qquad$

```
\[
\mathrm{Hb} . \operatorname{tr}=\mathrm{A} . \mathrm{Hb}
\]
if PA mode
``` \(\qquad\)
``` \(\mathrm{Hb} . \operatorname{tr}=\mathrm{A} . \mathrm{Hb} * \sqrt{(\text { Ou. } \mathrm{P})}\)
```

HB Calibration in modes ZC - BF - HSC


HB Calibration in mode PA


Power Fault Alarms (SSR Short, No_Voltage, SSR_Open and No_Current)

| 660 | H23 | R/W | Enable POWER_FAULT | Table of Power Fault Alarms |  |  |  | Zone 1 | $\begin{gathered} 0 \\ \text { Zone } 2 \end{gathered}$ | Zone 3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | HLE |  |  | Hd. 2 | SSR Short | NO_VOLTAGE | NO_CURRENT |  |  |  |
|  |  |  |  | 0 |  |  |  |  |  |  |
|  |  |  |  | 1 | X |  |  |  |  |  |
|  |  |  |  | 2 |  | X |  |  |  |  |
|  |  |  |  | 3 | X | X |  |  |  |  |
|  |  |  |  | 4 |  |  |  |  |  |  |
|  |  |  |  | 5 | X |  |  |  |  |  |
|  |  |  |  | 6 |  | X |  |  |  |  |
|  |  |  |  | 7 | X | X |  |  |  |  |
|  |  |  |  | 8 |  |  | X |  |  |  |
|  |  |  |  | 9 | X |  | X |  |  |  |
|  |  |  |  | 10 |  | X | X |  |  |  |
|  |  |  |  | 11 | X | X | X |  |  |  |
|  |  |  |  | 12 |  |  | X |  |  |  |
|  |  |  |  | 13 | X |  | X |  |  |  |
|  |  |  |  | 14 |  | X | X |  |  |  |
|  |  |  |  | 15 | X | X | X |  |  |  |


| 661 | D6. ${ }^{\text {T }}$ | R/W | Refresh rate <br> The alarm activate | SSR Short s after 3 faults. | 1... 999 sec |  |  |  | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 662 | 16.F | R/W | Time filter for $\mathrm{NO}_{-}$ OPEN and NO_CU | OLTAGE, SSR RRENT alarms. | $\begin{gathered} 1 . . .999 \\ \text { sec } \end{gathered}$ | Set a value not less than cycle time | $\begin{gathered} 10 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 10 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 10 \\ \text { Zone } 3 \end{gathered}$ |
| $\begin{aligned} & 105 \\ & \text { bit } \end{aligned}$ | Reset SSR SHORT / NO VOLTAGE <br> / NO_CURRENT alarms |  |  | R/W |  |  |  |  |  |

## Read State

| 96 bit | State of alarms SSR_SHORT phase 1 | R |
| :---: | :--- | :--- |
| 97 bit | State of alarms SSR_SHORT phase 2 | R |
| 98 bit | State of alarms SSR_SHORT phase 3 | R |
| 99 bit | State of alarms NO_VOLTAGE phase 1 | R |
| 100 bit | State of alarms NO_VOLTAGE phase 2 | R |
| 101 bit | State of alarms NO_VOLTAGE phase 3 | R |
| 102 bit | State of alarms NO_CURRENT phase 1 | R |
| 103 bit | State of alarms NO_CURRENT phase 2 | R |
| 104 bit | State of alarms NO_CURRENT phase 3 | R |

## Overheat Alarm

Each power module has one temperature sensor for the internal heat sink and two additional temperature sensors connected to the LINE and LOAD terminals.

Temperature levels are shown in variables INNTC_SSR, INNTC_LINE and INNTC_LOAD.

The over_heat alarm trips when at least one of the temperatures exceeds a set threshold.
Is also saved in INNTC_SSR_MAX the maximum temperature reached by INNTC_SSR.

This condition may be caused by obstructed ventilation slits or by a stopped cooling fan.
With the over_heat alarm active, the control disables control outputs OUT1, OUT2 and OUT3.
There is an additional maximum temperature protection that hardware disables the SSR controls.

| 655 | R | INNTC_SSR | $10.0 \ldots .120 .0^{\circ} \mathrm{C}$ | Overheat Alarm |
| :---: | :---: | :---: | :---: | :---: |
| 534 | R | INNTC_LINE | $10.0 \ldots .120 .0^{\circ} \mathrm{C}$ | Overheat Alarm |
| 535 | R | INNTC_LOAD | $10.0 \ldots .120 .0^{\circ} \mathrm{C}$ | Overheat Alarm |
| 679 | R | INNTC_SSR_MAX | $0.0 \ldots .120 .0^{\circ} \mathrm{C}$ |  |

## Fuse_Open and Short_Circuit_Current Alarms

The FUSE_OPEN alarm trips when the internal high-of Fr.n attempts, beyond which it remains deactivated speed fuse (optional) blows or, on ACPC-Xtra models, while awaiting manual reset with front panel key BUT or when the overcurrent protection device switches off.
The SHORT_CIRCUIT_CURRENT alarm trips when peak current on the load exceeds the maximum limit (corresponding to twice the rating) during the softstart ramp or at first power-on (with softstart ramp disabled).

If configured (parameter Fr.n other than zero), the device restarts automatically in softstart for a maximum
with the control via serial (bit 109).
For ACPC-Xtra models, the number of times the over-current protection device switches off is shown in FO.c1 and FO.c2
The FO count. c1 can be reset via the command via serial (bit116).

| 456 | FRT | R/W | Number of restarts in case of FUSE_OPEN / SHORT_CIRCUIT_CURRENT |  |  |  | 0.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 109 \\ \text { bit } \end{gathered}$ | RESET FUSE_OPEN /SHORT CIRCUIT_CURRENT ALARMS |  |  | R/W | OFF = - <br> ON = Reset FUSE | / SHORT_CIRCUIT_CURRENT alarms |  |
| $\begin{gathered} 116 \\ \text { bit } \end{gathered}$ | RESETTINGFOOI |  |  | R/W | OFF = - <br> ON = Reset count F |  |  |

*Address 116 bit is 40-300A Only
Read State

| 634 |  | R | State 4 (STATUS4) | Table of Instrument state 4 |
| :---: | :---: | :---: | :---: | :---: |
| $434^{*}$ | FOI | R | Counter 1: FUSE_OPEN events |  |
| $436^{*}$ | FGCD | R | Counter 2: FUSE_OPEN events |  |

[^0]
## Overcurrent Fault Protection - 40 to 300A Models

This function eliminates the need for an external extrarapid fuse to protect the device. In case of load shortcircuit, the internal IGBT device is instantaneously switched off and the alarm status is signaled.

- The overcurrent fault protection function DOES NOT replace any of the safeties on the system (such as magnetothermic switches, delay fuses, etc.).
- These caracteristic protects the controller (and therefore also the load) by replacing the high-speed fuse needed to protect the control SCRs against faults (without creating any additional cost to replace the fuse and reducing machine downtime).
- The overcurrent fault protection has 2 function states:
- Normal (On-Off control of load power)
- Fuse-Open: ACPC is open (a short occurred during normal operation).


## Outputs

The modular power controller has high flexibility in the assignment of functions to the physical outputs. As a result, the instrument can be used in sophisticated applications.
A function is assigned to each physical output in two steps: first assign the function to one of internal reference signals rL. 1 .. rL. 6 , and then attribute the reference signal to parameters out. 1 .. out. 10 (corresponding to physical outputs OUT1 ..OUT10).
In standard configuration, physical outputs Out1, Out2, Out3 perform the heating control function (Heat) for zone 1, zone 2 , and zone 3 , respectively; value 0 (function HEAT) is assigned to reference signals rL. 1 in each zone, and the following values to the output parameters: out. $1=1$ (output rL. 1 zone 1), out.2=2 (output rL. 1 zone 2), out.3=3 (output rL. 1 zone 3).
Physical outputs Out5, Out6, Out7, Out8 are optional, and the type (relay, logic, continuous or triac) is defined by the order code. In standard configuration, these outputs perform the cooling control function (Cool) for zone 1, zone 2, and zone 3, respectively. In this configuration, value 1 (function COOL) is assigned to reference signals rL. 2 in each zone, and the following values to the output parameters: out.5=5 (output rL. 2 zone 1), out. $6=6$ (output rL. 2 zone 2), out. $7=7$ (output rL. 2 zone 3).
Relay outputs Out9 and Out10 are always present, programmable by means of parameters out. 9 and out.10, to which available alarm signal functions are assigned by means of the four reference signals rL.3, rL.4, rL.5, rL. 6 in each zone.

Standard configuration has the following assignments: - reference signals: rL. $3=2$ (function AL1), rL. $4=3$ (function AL2), rL.5=4 (function AL3) and rL.6=5 (function AL.HB or POWER_FAULT with HB alarm).

- output parameters: out. $9=17$ and out. $10=18$.

In this way, the state of output physical Out9 is given by the logic OR of AL1, AL3 in each zone, and the state of output Out10 is given by the logic AND of AL2, AL.HB in each zone.
Each output can always be disabled by setting parameter out.x = 0 .
The state of outputs Out1, ..,Out10 can be acquired by serial communication by means of bit variables.
The following additional configuration parameters are related to the outputs:

Ct. 1 = cycle time for output rL. 1 for heating control (Heat) (see Settings section)
Ct. 2 = cycle time for output rL. 2 for cooling control (Cool) (see Settings section)
rEL = alarm states AL1, AL2, AL3, AL4 in case of broken probe, Err, Sbr (see Generic Alarms Section)

## Allocation of Reference Signals

| 160 | RL.! | R/W | Allocation of <br> reference signal |
| :---: | :---: | :---: | :---: |
| 163 | RL.E | R/W | Allocation of <br> reference signal |


| Table of Reference Signals |  | 0 Zone 1 | $\begin{gathered} 0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0 \\ \text { Zone } 3 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: |
|  | Function |  |  |  |
| 0 | HEAT (heating control output) / in case of continuous output $0 . . .20 \mathrm{~mA} / 0 . . .10 \mathrm{~V}$ | $\begin{gathered} 1 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 1 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 1 \\ \text { Zone } 3 \end{gathered}$ |
| 1 | COOL (cooling control output) / in case of continuous output $0 . . .20 \mathrm{~mA} / 0 . . .10 \mathrm{~V}$ |  |  |  |
| 2 | AL1 - alarm 1 |  |  |  |
| 3 | AL2 - alarm 2 |  |  |  |
| 4 | AL3-alarm 3 |  |  |  |
| 5 | AL.HB or POWER_FAULT with HB alarm (TA1 OR TA2 OR TA3) |  |  |  |
| 6 | LBA - LBA alarm |  |  |  |
| 7 | IN1 - repetition of logic input DIG1 |  |  |  |
| 8 | AL4 - alarm 4 |  |  |  |
| 9 | AL1 or AL2 |  |  |  |
| 10 | AL1 or AL2 or AL3 |  |  |  |
| 11 | AL1 or AL2 or AL3 or AL4 |  |  |  |
| 12 | AL1 and AL2 |  |  |  |
| 13 | AL1 and AL2 and AL3 |  |  |  |
| 14 | AL1 and AL2 and AL3 and AL4 |  |  |  |
| 15 | AL1 or AL.HB or POWER_FAULT with HB alarm (TA1 OR TA2 OR TA3) |  |  |  |
| 16 | AL1 or AL2 or (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3) |  |  |  |
| 17 | AL1 and (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3) |  |  |  |
| 18 | AL1 and AL2 and (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3) |  |  |  |
| 19 | AL.HB - HB alarm (TA2) |  |  |  |
| 20 | AL.HB - HB alarm (TA3) |  |  |  |
| 21 | Setpoint power alarm |  |  |  |
| 22 | AL.HB - HB alarm (TA1) |  |  |  |
| 23 | POWER_FAULT |  |  |  |
| 24 | IN2 - repetition of logic input DIG2 |  |  |  |
| 64 | HEAT (heating control output) with fast cycle time 0.1 ... 20.0sec. / in case of continuous output 4...20mA / 2...10V |  |  |  |
| 65 | COOL (cooling control output) with fast cycle time 0.1 ... 20.0sec. / in case of continuous output $4 . . .20 \mathrm{~mA}$ / 2... 10 V |  |  |  |



|  |  |  |  |  |  | $\begin{gathered} \text { DIP } 5=\text { OFF } \\ \text { (Resistive load) } \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 152^{*} \\ 9 \end{gathered}$ | [7] | R/W | OUT 1 (Heat) cycle time | $\begin{gathered} 1 . . .200 \mathrm{sec} \\ (0.1 . .20 .0 \mathrm{sec}) \end{gathered}$ | Set 0 for BF/HSC function See POWER CONTROL | $\begin{gathered} 0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0 \\ \text { Zone } 3 \end{gathered}$ |
|  |  |  |  |  |  | $\begin{gathered} \text { DIP } 5=\text { ON } \\ \text { (Inductive load) } \end{gathered}$ |  |  |
|  |  |  |  |  |  | $\begin{gathered} 4 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 4 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 4 \\ \text { Zone } 3 \end{gathered}$ |
| 159* | [T.E | R/W | OUT 2 (Cool) cycle time | $\begin{gathered} 1 . . .200 \mathrm{sec} \\ (0.1 . .20 .0 \mathrm{sec}) \end{gathered}$ |  | $\begin{gathered} 20 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 20 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 20 \\ \text { Zone } 3 \end{gathered}$ |

Read State


## Allocation of Physical Outputs

| 607 | 막․ | R/W | Allocation of physical output OUT 1 |
| :---: | :---: | :---: | :---: |
| 608 | OUT.E | R/W | Allocation of physical output OUT 2 |
| 609 | 0073 | R/W | Allocation of physical output OUT 3 |
| 610 | 안․․ | R/W | Allocation of physical output OUT 4 |
| 611 | 0075 | R/W | Allocation of physical output OUT 5 |
| 612 | 007.5 | R/W | Allocation of physical output OUT 6 |
| 613 | 917. | R/W | Allocation of physical output OUT 7 |
| 614 | OUTG | R/W | Allocation of physical output OUT 8 |
| 615 | 047.9 | R/W | Allocation of physical output OUT 9 |
| 616 | OUTH | R/W | Allocation of physical output OUT 10 |


|  | Table of output allocations | 1 |
| :---: | :---: | :---: |
| 0 | Output disabled | 2 |
| 1 | Output rL. 1 zone 1 |  |
| 2 | Output rL. 1 zone 2 | 3 |
| 3 | Output rL. 1 zone 3 |  |
| 4 | Output rL. 1 zone 4 | 4 |
| 5 | Output rL. 2 zone 1 |  |
| 6 | Output rL. 2 zone 2 | 5 |
| 7 | Output rL. 2 zone 3 |  |
| 8 | Output rL. 2 zone 4 | 6 |
| 9 | Output rL. 3 OR rL. 5 zone 1 |  |
| 10 | Output rL. 3 OR rL. 5 zone 2 | 7 |
| 11 | Output rL. 3 OR rL. 5 zone 3 |  |
| 12 | Output rL. 3 OR rL. 5 zone 4 | 8 |
| 13 | Output rL. 4 AND rL. 6 zone 1 |  |
| 14 | Output rL. 4 AND rL. 6 zone 2 | 9 |
| 15 | Output rL. 4 AND rL. 6 zone 3 |  |
| 16 | Output rL. 4 AND rL. 6 zone 4 | 17 |
| 17 | Output (rL. 3 OR rL.5) zone 1...zone 4 |  |
| 18 | Output (rL. 4 AND rL.6) zone 1...zone 4 |  |
| +32 to reverse output status only for Logic and Relay output |  |  |
| NOTE: In 3-phase configuration, the state of physical output OUT1 is copied to OUT2 and OUT3. <br> In case of auxiliary continuous outputs, the same output functions can not be used on other outputs. |  | 18* |
|  |  | $50^{* *}$ |

## Read State

| $\begin{aligned} & 82 \\ & \text { Bit } \end{aligned}$ | State of output OUT 1 | R | OFF = Output off ON = Active Output |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & 83 \\ & \text { Bit } \end{aligned}$ | State of output OUT 2 | R | OFF = Output off ON = Output on |
| $\begin{aligned} & 84 \\ & \text { Bit } \end{aligned}$ | State of output OUT 3 | R | OFF = Output off ON = Output on |
| $\begin{aligned} & 85 \\ & \text { Bit } \end{aligned}$ | State of output OUT 4 | R | OFF = Output off ON = Output on |
| $\begin{aligned} & 86 \\ & \text { Bit } \end{aligned}$ | State of output OUT 5 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| $\begin{aligned} & 87 \\ & \text { Bit } \end{aligned}$ | State of output OUT 6 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| $\begin{aligned} & 88 \\ & \text { Bit } \end{aligned}$ | State of output OUT 7 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| $\begin{aligned} & 89 \\ & \text { Bit } \end{aligned}$ | State of output OUT 8 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| $\begin{aligned} & 90 \\ & \text { Bit } \end{aligned}$ | State of output OUT 9 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| $\begin{aligned} & 91 \\ & \text { Bit } \end{aligned}$ | State of output OUT 10 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |



Functional Diagram


## Analog Outputs - 400 to 600A Models

The 3 optional analog outputs let you retransmit the value of analog quantities. The engineering value of the quantity is limited to the set scale values and a reparameterization is applied based on the type of output selected.

## Example 1:

To retransmit the current of the ACPC-M load with range 0-600 A with output Analog1 (0-10V), set: tP.AO1=2, rF.AO1=17, LS.AO1 = 0,0 A, HS.AO1 = 600,0 A

## Example 2:

To retransmit the power of the single-phase load of the ACPC-M with range $0-500 \mathrm{~kW}$ with output Analog1 ( $0-20 \mathrm{~mA}$ ), set: tP.AO1=0, rF.AO1=21, LS.AO1 $=0.0 \mathrm{~kW}, \mathrm{HS} . \mathrm{AO} 1=500.0 \mathrm{~kW}$

| 865 | TPRH | R/W | Output type analog 1 |
| :---: | :---: | :---: | :---: |
| 866 | TPROE | R/W | Output type analog 2 |
| 867 | TPP昭 | R/W | Output type analog 3 |


| Table of Analog output types |  | 1 |
| :---: | :---: | :---: |
| 0 | 0... 20 mA output |  |
| 1 | 4 ... 20 mA output |  |
| 2 | $0 . . .10 \mathrm{~V}$ output |  |
| 3 | 2... 10 V output |  |
|  | +16 Inverse output |  |


| 868 | RFPG | R/W | Attribution reference output analog 1 |
| :---: | :---: | :---: | :---: |
| 869 | RFPGE | R/W | Attribution reference output analog 2 |
| 870 | RFRH3 | R/W | Attribution reference output analog 3 |


| Table of Reference Signals |  | Scale Setting limits |  |  | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Max | Limit of Meas. |  |
| 0 | NONE | 0 | 65535 | - | 0 |
| 1 | Ou.P (control output) of ACPC-M | 0.0 | 100.0 | \% |  |
| 2 | Ou.P (control output) of ACPC-E1 | 0.0 | 100.0 | \% | 0 |
| 3 | Ou.P (control output) of ACPC-E2 | 0.0 | 100.0 | \% |  |
| 4 | In.A1 (analog input 1) | 0.0 | 100.0 | \% |  |
| 5 | In.A2 (analog input 2) | 0.0 | 100.0 | \% |  |
| 6 | In.A3 (analog input 3) | 0.0 | 100.0 | \% |  |
| 7 | In.PWM1 (PWM 1 input) | 0.0 | 100.0 | \% |  |
| 8 | In.PWM2 (PWM 2 input) | 0.0 | 100.0 | \% |  |
| 9 | In.PWM3 (PWM 3 input) | 0.0 | 100.0 | \% |  |
| 10 | I.VF1 (line voltage) of ACPC-M | 0.0 | 6553.5 | V |  |
| 11 | I.VF1 (line voltage) of ACPC-E1 | 0.0 | 6553.5 | V |  |
| 12 | I.VF1 (line voltage) of ACPC-E2 | 0.0 | 6553.5 | V |  |
| 13 | Ld.V (voltage on load) of ACPC-M | 0.0 | 6553.5 | V |  |
| 14 | Ld.V (voltage on load) of ACPC-E1 | 0.0 | 6553.5 | V |  |
| 15 | Ld.V (voltage on load) of ACPC-E2 | 0.0 | 6553.5 | V |  |
| 16 | Ld.V.t (voltage on 3-phase load) | 0.0 | 6553.5 | V |  |
| 17 | Ld.A (current on load) of ACPC-M | 0.0 | 6553.5 | A |  |
| 18 | Ld.A (current on load) of ACPC-E1 | 0.0 | 6553.5 | A |  |
| 19 | Ld.A (current on load) of ACPC-E2 | 0.0 | 6553.5 | A |  |
| 20 | Ld.A.t (current on 3-phase load) | 0.0 | 6553.5 | A |  |
| 21 | Ld.P (power on load) of ACPC-M | 0.0 | 6553.5 | kW |  |
| 22 | Ld.P (power on load) of ACPC-E1 | 0.0 | 6553.5 | kW |  |
| 23 | Ld.P (power on load) of ACPC-E2 | 0.0 | 6553.5 | kW |  |
| 24 | Ld.P.t (power on 3-phase load) Serial | 0.0 | 6553.5 | kW |  |
| 25 | line value | 0.0 | 6553.5 | - |  |

## Controls

## Automatic / Manual Control

By means of the digital input function you can set the controller in MAN (manual) and set the control output to a constant value changeable by means of communication.
When returning to AUTO (automatic), if the variable is within the proportional band, switching is bumpless.


* 400 to 600A Models only


## Manual Power Correction

With this function (available on models with CV diagnostics option), you can run a correction of power delivered in manual based on the reference line voltage (riF). The \% value of the (Cor) is freely settable and acts in inverse proportion.
The function is activated/deactivated by means of parameter SP.r.
Example: with the following settings: $\mathrm{Cor}=10 \%$; riF = 380; SP.r = value +8 ; instrument in manual; line voltage 380 VAC, manual power set at $50 \%$, following a $10 \%$ increase in line voltage, $380 \mathrm{~V}+10 \%(380 \mathrm{~V})=418 \mathrm{~V}$, there is a decrease in set manual power equal to the same \% of change: $50 \%-10 \%(50 \%)=45 \%$.
To use this function, the controller must have a CT (current transformer) and a VT (voltage transformer). N.B.: the \% change in manual power is limited to the value set in parameter "Cor".
The maximum manual power correction is limited to $\pm 65 \%$.

| 505 | RHF | R/W | $0.0 \ldots 999.9$ | 0.0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Compensation of the voltage transformer read to maintain output power at a constant level.

| 506 | FIR | R/W | Correction of manual power based on line voltage | 0.0 ... 100.0 \% |  |  | 0.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 18 \\ 136-249 \end{gathered}$ | 5PR | R/W | Remote setpoint (SET gradient for manual power correction) | Setpoint Table |  |  | 0 |
|  |  |  |  |  | Type of Remote Set | Absolute/Deviation |  |
|  |  |  |  | 0 | Digital (from serial line) | Absolute |  |
|  |  |  |  | 1 | Digital (from serial line) | Deviation local set (_SP o SP1 o SP2) |  |
|  |  |  |  | +4 set gradient in digit/sec. <br> +8 correction of manual power based on line voltage <br> +16 disable saving of local setpoint _SP <br> +32 disable saving of local manual power (at switchoff returns to last value saved) |  |  |  |

## Start Mode

$699 \mathrm{PanT}^{-1}$ R/W $\quad$ Start modes at Power-On

| $0^{*}$ | Function at previous state |
| :---: | :--- |
| 1 | Software shutdown |
| 2 | Software startup |

(*) digital input states always have priority

## Software Shutdown

Running the software shutdown procedure causes the following:

1) Reset of Autotuning, Selftuning and Softstart.
2) Digital input enabled only if assigned to SW shutdown function.
3) In case of switch-on after SW shutdown, any ramp for the set (set gradient) starts from the PV.
4) Outputs OFF: except for signals them of reference rL. 4 and rL. 6 that they come forced ON
5) Reset of HB alarm.
6) Reset of LBA alarm.
7) The Heat and Cool bit on the state word STATUS and POWER are reset.
8) At shutdown, the current power is saved. At switch-on, integral power is recalculated as the difference between saved power and proportional power; this calculation is defined as "desaturation at switch-on."
9) In case of Geflex, the state of alarms (AL1...AL4, ALHBTA1...ALHBTA3) is reset.
10) Alarms AL 1... AL 4 can be enable or disable through the parameter oFF.t.

| 140 | OH5 | R/W | Digital Input Function |  | See: Table of digital input functions | 0.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 618 | CHE | R/W | Digital Input 2 Function |  |  | 0.0 |
| $\begin{aligned} & 11 \\ & \text { bit } \end{aligned}$ | SOFTWARE <br> LAUNCH/SHUTDOWN |  | R/W | $\begin{aligned} & \mathrm{OFF}=\mathrm{ON} \\ & \mathrm{ON}=\mathrm{OFF} \end{aligned}$ |  |  |



* for 400 to 600A Models only

Read State


## Other Functions

## Fault Action Power (40 to 300A Only)

You can decide what power to supply in case of broken probe.
FAP is the reference power for parameter FAP.
Average power is the average power calculated in the last 300 sec.

The alarm reset and reference power update take place only at switch-on or after a setpoint change.

The alarm is not activated if the control (Ctr) is ON/OFF type, during Selftuning and in Manual.

| 265 | HBT | R/W | Select Specialized <br> Control Functions | See: Hot runners table - Setpoint Settings | 0 |  |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |
| 228 | FRP | R/W | Fault Action Power (supplied in <br> conditions of broken probe) | $-100.0 . .100 .0 \%$ |  | 0.0 |

## Read State

| 26 | HB ALARM STATE OR | R | OFF = Alarm off <br> ON = Alarm on |
| :---: | :---: | :---: | :---: |
| bit | POWER_FAULT |  | OFF = Alarm off |
| 80 | State of Power alarm | R | ON = Alarm on <br> bit |

## Power Alarm

The alarm signals any power changes (OuP) after the process variable (PV) has stabilized on the setpoint (SP). The time beyond which the process variable is considered stable is 300 sec .
The reference power update take place only at switchon or after a setpoint change.

If the process variable leaves the stabilization band after the first stabilization, this does not influence the alarm.

In case of SBR:

- if the PV has not yet stabilized, either the average power over the last 5 minutes or FAP power is supplied (depending on the setting of the HOT parameter).
- if the PV has stabilized the average power over the last 5 minutes is supplied.


## Function:

If necessary, assign an output (rL.2...6) for the power alarm.
Set the band (b.ST) within which the process variable is considered stable after 300 sec . have elapsed.
Set the band (b.PF) outside which the alarm is activated after time PF.t has elapsed.

The reference power is the active power after 300 sec. have elapsed.
The alarm reset and reference power update take place only at switch-on or after a setpoint change.

The alarm is not activated if the control（Ctr）is ON／OFF type，and in Manual．


The parameters for alarm power are：

| 261 | 85 | R／W | Stability Band（specialized control alarm power function） | 0.0 ．．．100．0 \％f．s． |  |  | 0.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 262 | BPF | R／W | Alarm Power Band（specialized control alarm power function） | 0.0 ．．． 100.0 \％ |  |  | 0.0 |
| 260 | PFT | R／W | Delay Time for alarm power activation（specialized controls） | $0 . . .999 \mathrm{sec}$ |  |  | 0 |
| 160 | RLI | R／W | Allocation of reference signal | See：Generic alarms－Table of reference signals | $\begin{gathered} 0 \\ \text { Zone } 1 \end{gathered}$ | Zone 2 | $\begin{gathered} 0 \\ \text { Zone } 3 \end{gathered}$ |
| ＊40 to 300A models only |  |  |  |  |  |  |  |
| 163 | R2己 | R／W | Allocation of reference signal |  | $\begin{gathered} 1 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 1 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 1 \\ \text { Zone } 3 \end{gathered}$ |
| ＊40 to 300A models only |  |  |  |  |  |  |  |
| 166 | R23 | R／W | Allocation of reference signal－OR output |  | $\stackrel{2}{2} \text { Zone } 1$ | $\stackrel{2}{\text { Zone } 2}$ | $\stackrel{2}{\text { Zone } 3}$ |
| 170 | 勋 4 | R／W | Allocation of reference signal－ AND Output |  | $\begin{gathered} 35 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 35 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 35 \\ \text { Zone } 3 \end{gathered}$ |
| 171 | RLS | R／W | Allocation of reference signal－OR output |  | $\begin{gathered} 4 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 4 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 4 \\ \text { Zone } 3 \end{gathered}$ |
| 172 | 勋 6 | R／W | Allocation of reference signal－ AND Output |  | $\begin{gathered} 160 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 160 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 160 \\ \text { Zone } 3 \end{gathered}$ |

## Heating Output (Fast cycle)

For outputs rL. 1 (Out 1) and rL. 2 (Out 2) you can set a fast cycle time ( $0.1 \ldots 20 \mathrm{sec}$ ) by setting the parameter to 64 (Heat) or 65 (Cool).

| 160 | R! | R/W | Allocation of reference signal | See: Generic alarms -Table of reference signals |  | $0$ <br> Zone 1 | $\begin{gathered} 0 \\ \text { Zone } 2 \end{gathered}$ | $0$ <br> Zone 3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 163 | RLコ | R/W | Allocation of reference signal |  |  | $1$ <br> Zone 1 | 1 <br> Zone 2 | $1$ <br> Zone 3 |
| $\begin{gathered} 152 \\ 9 \end{gathered}$ | ET. | R/W | OUT 1 (Heat) cycle time | $\begin{gathered} 1 . . .200 \mathrm{sec} \\ (0.1 \ldots 20 \mathrm{sec}) \end{gathered}$ | Set 0 for GTT function 2 See POWER CONTROL |  |  | 2 |

400 to 600A Models only.

## Operating Hour Meter

The device shows in OH . c (Operating Hours Counter) the number of operating hours (line voltage present and nonzero power); updating in non-volatile memory occurs every two hours and the disarming of the line voltage.


|  |  |  |  |  |  | $\begin{gathered} \text { DIP } 5 \text { = OFF } \\ \text { (Resistive load) } \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 152^{*} \\ 9 \end{gathered}$ | [7] | R/W | OUT 1 cycle time | $\begin{gathered} 1 . . .200 \mathrm{sec} \\ (0.1 \ldots 20.0 \mathrm{sec}) \end{gathered}$ | (*) | $\begin{gathered} 0 \\ \text { Zone } 1 \end{gathered}$ | 0 Zone 2 | 0 Zone 3 |
|  |  |  |  | *Set to 0 for BF/HSC functions See power management |  | DIP 5 = ON (Inductive load) |  |  |
|  |  |  |  |  |  | $\begin{gathered} 4 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 4 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 4 \\ \text { Zone } 3 \end{gathered}$ |

## Power Control

## SSR Control Modes

## On Modality:

The ACPC has the following power control modes:

- PA modulation via variation of phase angle
- ZC, BF, HSC modulation via variation of number of conduction cycles with zero crossing trigger.
PA phase angle: this mode controls power on the load via modulation of the phase angle.
ZC zero crossing: this type of operation reduces EMC emissions. This mode controls power on the load via a series of conduction ON and non conduction OFF cycles.
The cycle time is constant and can be set from 1 to 200 sec (or from 0.1 to 20.0 sec ).
BF burst firing: this mode controls power on the load via a series of conduction ON and non conduction OFF cycles. The ratio of the number of ON cycles to OFF cycles is proportional to the power value to be supplied to the load. The repeat period or cycle time is kept to a minimum for each power value.

Parameter bF.Cy defines the minimum number of conduction cycles, settable from 1 to 10.

In case of 3-phase load without neutral or closed delta, BF.Cy >= 5 has to be set to ensure correct operation (balancing of current in the 3 loads).

HSC Half Single Cycle: this mode corresponds to a BF that includes ON and OFF half-cycles. It is useful for reducing flicker with short-wave IR loads (and is applied only to single-phase or 3-phase with neutre or open delta loads).

Start mode is set with parameter Hd. 5
Control of maximum rms current (whose value is set in parameter Fu.tA) can always be enabled with parameter Hd. 5 in every power-on mode.
The cycle time can be set with two different resolutions in seconds or tenths of a second based on the type of heat or cool function assigned to outputs rL1 and rL2. The use of short cycle times ( $<2-3 \mathrm{sec}$ ) is always recommended in case of control with SSRs.)

(*) $\begin{aligned} & \text { Hd. } 5=133 \quad \text { For ACPC with Control Option = } \\ & 0 \text { Hd. } 5=141 \quad \text { Option for ACPC with current }\end{aligned}$
limit Control option =1 or 2 or 3

+ 32 only for ZC/BF modes: enable delay triggering
+ 64 linear phase Softstart in power
+128 phase Softstart for IR lamps
+ 256 phase Softstart for shutdown in software ON/OFF switching

Dip 5 - OFF
Resistive Load

| 133/141 | 133/141 | 133/141 |
| :---: | :---: | :---: |
| Zone 1 | Zone 2 | Zone 3 |


| Dip 5 |  |  |  | ON Inductive Load |
| :---: | :---: | :---: | :---: | :---: |
| 32 | 32 | 32 |  |  |
| Zone 1 | Zone 2 | Zone 3 |  |  |



## SOFTSTART or START RAMP

This type of start can be enabled either in phase control or pulse train mode and acts via control of the conduction angle. It is enabled with parameter Hd.5.
The softstart ramp starts from a zero conduction angle and reaches the angle set in parameter PS.HI in the time set in parameter PS.tm, from 0.1 to 60.0 sec.
With parameter Hd. 5 (+64), you can configure a linear softstart in power, i.e., starting from zero you reach the power value corresponding to the maximum conduction angle set in PS.HI. Softstart ends before the set time if power reaches the corresponding value set in manual control or calculated by PID.

Control of maximum peak current can be enabled with parameter Hd. 5 during the ramp phase; peak value is settable in parameter PS.tA. This function is useful in case of short circuit on the load of loads with high temperature coefficients to automatically adjust start time to the load.

The softstart ramp activates at the first start after pow-er-ON and after a software reboot. It can be reactivated via software control by writing bit 108 or automatically if there are OFF conditions for a time exceeding the one settable in PS.oF (if $=0$ the function is as if disabled).
The ramp can also be enabled with parameter Hd. 5 (+256) after a software shutdown, i.e., zero is reached in the set time from delivered power.

| 630* | P5H | R/W | Maximum phase of phase softstart ramp |  | 0.0 ...100.0\% |  |  |  | $\begin{aligned} & 100.0 \\ & \text { zone } 1 \end{aligned}$ |  | $\begin{aligned} & 100.0 \\ & \text { zone } 2 \end{aligned}$ | $\begin{gathered} 100.0 \\ \text { zone } 3 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 705* | PSTM | R/W | Duration of phase softstart ramp |  | 0.1 ...60.0 s |  |  |  | $\begin{gathered} 10.0 \\ \text { zone } 1 \end{gathered}$ |  | $\begin{gathered} 10.0 \\ \text { zone } 2 \end{gathered}$ | $\begin{gathered} 10.0 \\ \text { zone } 3 \end{gathered}$ |
| 629* | P50F | R/W | Min. non-conduction time to reactivate phase softstart ramp |  | $0 \ldots 999$ s |  |  |  | $\stackrel{2}{\text { zone } 1}$ |  | $\begin{gathered} 2 \\ \text { zone } 2 \end{gathered}$ | $\begin{gathered} 2 \\ \text { zone } 3 \end{gathered}$ |
| 706* | P57R | R/W | Maximum peak current limit | 0.0 ...999.9 A | Model 40A |  | 60A | 100A | 150A | 200A | A 250 A | 300A |
|  |  |  |  |  | $\begin{aligned} & \text { Default Zone } \\ & 1 . . .3 \text { ACPC } \end{aligned}$ | 110.0 | 170.0 | 280.0 | 420.0 | 560.0 | 0700.0 | 840.0 |
|  |  |  |  |  | $\begin{gathered} \text { Default Zone } \\ 1 \ldots 3 \\ \text { CFWxtra } \end{gathered}$ | 110.0 | 170.0 | 230.0 |  |  |  |  |


| 108* <br> bit | Restart of phase <br> softstart ramp | R/W | OFF = Restart not enabled <br> ON = Restart enabled |
| :---: | :---: | :---: | :---: |
| $106^{*}$ <br> bit | State of phase <br> softstart ramp | R | OFF = Ramp not active <br> ON = Ramp active |
| $107^{*}$ | State of phase <br> bit | R | OFF = Ramp not ended <br> Softstart ramp |

NB: In case of a 3-phase load, you can set a diferent value from parameter PS.tA for each zone (ex. to control an unbalanced 3-phase load).

## Delay Triggering

In firing modes $Z C$ and $B F$, with inductive loads, this function inserts delay triggering in the first cycle.
The delay is expressed in degrees settable in parameter dL.t, from 0 to 90 degrees. The function is enabled with parameter Hd. 5 (+32).

The function activates automatically if there are OFF conditions for a time exceeding the one settable in dL.oF (if $=0$ the function is as if disabled).

- Optimized Delay-Triggering value for transformer monophase: $60^{\circ}$
- Optimized Delay-Triggering value for 3-phase transformer: $90^{\circ}, 90^{\circ}, 40$

| 60 | 60 | 60 |
| :---: | :---: | :---: |
| zone 1 | zone 2 | zone 3 |



## Feedback Modes

The ACPC has the following power control modes:
V-voltage
V2-squared voltage
I-current
I2-squared current
P-power
A control mode is enabled with parameter Hd.6.

## Voltage feedback (V)

To keep voltage on the load constant, this compensates possible variations in line voltage with reference to the rated voltage saved in riF.V. (expressed in Vrms).
The voltage value maintained on the load is (ref.V*P\%_ pid_man/100) and is indicated in the Modbus 757 register.

## Voltage feedback (V2)

To keep voltage on the load constant, this compensates possible variations in line voltage with reference to the rated voltage saved in riF.V. (expressed in Vrms).
The voltage value maintained on the load is (rif.V* V ( $\mathrm{P} \%$ _pid_man/100)), and is indicated in the Modbus 757 register.
Current feedback (I)
To keep current on the load constant, this compensates possible variations in line voltage and/or variations in load impedance with reference to the rated current saved in riF.I. (expressed in Arms).
The current value maintained on the load is (rif.l* $\mathrm{P} \%$ _ pid_man/100), and is indicated in the Modbus 757 register.
Current feedback (I2)
To keep current on the load constant, this compensates possible variations in line voltage and/or variations in load impedance with reference to the rated current saved in riF.I. (expressed in Arms).
The current value maintained on the load is (rif.I* V (P\%_pid_man/100)), and is indicated in the Modbus 757 register.

## Power feedback $\mathbf{P}$

To keep power on the load constant, this compensates both variations in line voltage and variations in load impedance with reference to the rated power saved in riF.P. (expressed in kWatt).
The current value maintained on the load is (rif. $\mathrm{P}^{*} \mathrm{P} \%$ _ pid_man/100), and is indicated in the Modbus 757 register.


## IMPORTANT!

Feedback calibration can be activated from the digital input (parameters DIG and DIG.2) or by serial control (ref. bit113), and if requested MUST be activated only with Hd.6=0 (the required Hd. 6 value can be set only after calibration) and preferably with maximum power on the load (ex. P_man or P_pid at 100\%).

If you change function mode (PA, ZC, BF, HSC), you have to re-run the Feedback calibration procedure.

Voltage V (or current I or power P) feedback corrects the \% of conduction with a maximum settable value in parameter Cor. V (or Cor.I or Cor. P).

For non-linear loads (ex.: Super Kanthal or Silicon Carbide) the automatic calibration procedure is NOT NECESSARY. Set the value of parameters ref. $V$, ref. $I$, ref. $P$ based on the specific nominal of the load shown on the data-sheet (ref. ACPC Installation Guide).


Read State


## Heuristic Control Power

It is useful to be able to limit the delivery of total power to the loads in order to avoid input peaks from the sin-gle-phase power line.
This condition occurs during switch-on phases when the machine is cold; the demand for heating power is $100 \%$ until temperatures near the setpoint are reached. It is also useful to avoid simultaneity of conduction when there is ON-OFF modulation for temperature maintenance.
The cycle time must be identical for all zones; the power percentage for each zone is limited to that necessary to maintain current within set limits.
This function acts by enabling the control to search for the most appropriate input combinations.

## Example 1:

4 loads 380V- 32A (zone 1), 16A (zone 2), 25A (zone 3), 40A (maximum current is 73A in case of simultaneity of conduction).
Current limit I.HEU=50A.
The following combinations of conduction are possible: (to define the number of combinations, remember that the combinations without repetitions are $=n!/(k!*(n-$ k)! )
$11+\mid 2=48 \mathrm{~A}$
$11+13=57 A$
$12+I 3=41 A$
$11+12+13=73 A$

The combinations corresponding to current values below the limit value are:
$\mathrm{I} 1+\mathrm{I} 2=48 \mathrm{~A}$
$12+13=41 A$
The one with lower current is given by zone 2 \& zone 3. In the single cycle time for the enabled zones, the delivery of power may be reduced to respect the maximum current limit.

The time distribution for activation of the zones is calculated at the start of each cycle:
Ptot $=\mathrm{P} 1+\mathrm{P} 2$ (if P2>P3) + P3 (if P3>P2)
Simultaneity is allowed for zones 2 and 3 .

If $P 1=100 \%, P 2=100 \%, P 3=100 \%$
Ptot $=200 \%$; since Ptot $>100 \%$, the conduction time of the zone $x$ is obtained by Px * (100/Ptot)
P1,2,3 delivered $=100 \%{ }^{*} 0.5=50 \%$


If $\mathrm{P} 1=100 \%, \mathrm{P} 2=50 \%, \mathrm{P} 3=0 \%$
Ptot $=150 \%$; since Ptot $>100 \%$, the conduction time of the zone $x$ is obtained by Px * (100/Ptot)
$P 1$ delivered $=100 \% * 0.66=67 \%$
P 2 delivered $=50 \% * 0.66=33 \%$
P3 delivered $=0 \% * 0.66=0 \%$


| Table for enabling heuristic power |  |  |  |
| :---: | :---: | :---: | :---: |
|  | Zone 1 | Zone 2 | Zone 3 |
| 0 |  |  |  |
| 3 | X | X |  |
| 5 | X | X |  |
| 6 | X | X |  |
| 7 | X | X | X |

NOTE: Only for ACPC with CTs present and outputs OUT1...OUT3 with slow cycle time

681 HEU $\quad$ R/W | Maximum current for heuristic |
| :---: |
| power control |

| $0.0 \ldots 999.9 \mathrm{~A}$ |  | 0.0 |
| :---: | :---: | :---: |
| $(40$ to 300A Models $)$ |  |  |
| $0.0 \ldots 3275.0 \mathrm{~A}$ |  |  |
| $(400$ to 600A Models $)$ |  |  |

## Heterogeneous Power Control

This function matches that of a thermal cutout that disconnects the load based on instantaneous input. The load is disconnected based on a preset priority.

Zone 1 has priority: in case of overload, zone 3 is disconnected, followed by zone 2, etc.

| 682 | H84 | R/W | Enable hetergogeneous power control | Table for enabling heterogeneous power |  |  |  | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | Zone 1 | Zone 2 | Zone 3 |  |
|  |  |  |  | 0 |  |  |  |  |
|  |  |  |  | 1 | X |  |  |  |
|  |  |  |  | 2 | X |  |  |  |
|  |  |  |  | 3 | X | X |  |  |
|  |  |  |  | 4 | X |  |  |  |
|  |  |  |  | 5 | X | X |  |  |
|  |  |  |  | 6 | X | X |  |  |
|  |  |  |  | 7 | X | X | X |  |
| 683 | HET | R/W | Maximum current for hetergogeneous power control |  | $\begin{array}{r} . .999 . \\ 300 \mathrm{~A} \mathrm{M} \end{array}$ |  |  | 0.0 |
|  |  |  |  |  | $\begin{aligned} & .3275 \\ & \hline 600 \mathrm{~A} \\ & \hline \end{aligned}$ |  |  |  |

## Virtual Instrument Control

Virtual instrument control is activated by means of parameter hd.1.

By setting parameters S.In and S.Ou you can enable the writing of some parameters via serial line, set the value of inputs and the state of outputs.
You have to enable alarm setpoints AL1, ..., AL4 when write operations are continuous, and you don't have to keep the last value in eeprom.

Enabling the PV input means being able to exclude the local Tc or RTD acquisition and replace it with the value written in the register VALUE_F.
Enabling digital input IN lets you set the state of this input, for example to run MAN/AUTO switching with the writing of bit 7 in the register V_IN_OUT.
Likewise, you can set the on/off state of outputs OUT1, ..., OUT10 and of the LEDs by writing bits in the register V_IN_OUT.


| Parameter | Bit | Resource Enabled | Address of Image Register | Format | Name of Register |
| :---: | :---: | :---: | :---: | :---: | :---: |
| S.In | 0 | Alarm setpoint AL1 | 341 | word | AL1_RAM |
|  | 1 | Alarm setpoint AL2 | 342 | word | AL2_RAM |
|  | 2 | Alarm setpoint AL3 | 343 | word | AL3_RAM |
|  | 3 | Alarm setpoint AL4 | 321 | word | AL4_RAM |
|  | 4 | Input In. 1 | 347 | word | SERIAL IN1 |
|  | 6 | Input In. 2 | 348 | word | SERIAL IN2 |
|  | 7 | Input In. 3 | 578 | word | SERIAL IN3 |
|  | 8 | Input In. 4 | 579 | word | SERIAL IN4 |
|  | 9 | Input In. 5 | 580 | word | SERIAL IN5 |
|  | 10 | Input In.TA | 581 | word | SERIAL INA |
| $\mathrm{S} . \mathrm{Ou}$ | 0 | Output OUT 1 | 344 | word, bit 0 | V_IN_OUT |
|  | 1 | Output OUT 2 | 344 | word, bit 1 | V_IN_OUT |
|  | 2 | Output OUT 3 | 344 | word, bit 2 | V_IN_OUT |
|  | 4 | Output OUT 5 (relays) | 344 | word, bit 4 | V_IN_OUT |
|  | 4 | Output OUT 5 (continuous) | 639 | word | SERIAL_OUT5C* |
|  | 5 | Output OUT 6 (relays) | 344 | word, bit 5 | V_IN_OUT |
|  | 5 | Output OUT 6 (continuous) | 640 | word | SERIAL_OUT6C* |
|  | 6 | Output OUT 7 (relays) | 344 | word, bit 6 | V_IN_OUT |
|  | 6 | Output OUT 7 (continuous) | 641 | word | SERIAL_OUT7C* |
|  | 7 | Output OUT 8 (relays) | 344 | word, bit 7 | V_IN_OUT |
|  | 7 | Output OUT 8 (continuous) | 642 | word | SERIAL_OUT8C* |
|  | 8 | Output OUT 9 | 344 | word, bit 8 | V_IN_OUT |
|  | 9 | Output OUT 10 | 344 | word, bit 9 | V_IN_OUT |
| S.LI | 0 | Led RN | 351 | word, bit 0 | V_X_LEDS |
|  | 1 | Led ER | 351 | word, bit 1 | V_X_LEDS |
|  | 2 | Led D1 | 351 | word, bit 2 | V_X_LEDS |
|  | 3 | Led D2 | 351 | word, bit 3 | V_X_LEDS |
|  | 4 | Led O1 | 351 | word, bit 4 | V_X_LEDS |
|  | 5 | Led O2 | 351 | word, bit 5 | V_X_LEDS |
|  | 6 | Led O3 | 351 | word, bit 6 | V_X_LEDS |
|  | 7 | Led O4 | 351 | word, bit 7 | V_X_LEDS |
|  | 8 | Input D1 | 344 | word, bit 10 | V_IN_OUT |
|  | 9 | Input D2 | 344 | word, bit 11 | V_IN_OUT |

## Hardware \& Software Information (40 to 300A Models)

The following data registers can be used to identify the controller HW/SW and check its operation.

| 122 | UPE | R | Software version code |
| :---: | :---: | :---: | :---: |
| 85 | ERR | R | Self-diagnosis error code <br> for auxiliary input |
| 606 | ERE | R | Self-diagnosis error code <br> for auxiliary input 2 |
| 550 | ER3 | R | Self-diagnosis error code <br> for auxiliary input 3 |
| 551 | ER4 | R | Self-diagnosis error code <br> for auxiliary input 4 |
| 552 | ER5 | R | Self-diagnosis error code <br> for auxiliary input 5 |
| 190 | CHE | R | Hardware configuration codes |


|  | Table of main input errors |
| :---: | :--- |
| 0 | No Error |
| 1 | Lo (Process variable value < Lo.S) |
| 2 | Hi (Process variable value $>$ Hi.S) |
| 3 | ERR (third wire interrupted for PT100 or input val- <br> ues below minimum limits (ex. for TC with connec- <br> tion error) |
| 4 | SBR (Probe interrupted or input values beyond <br> maximum limits |

Table of hardware configuration codes

| bit |  |
| :---: | :--- |
| 0 | $=1$ OUTPUT COOL absent |
| 1 | $=1$ OUTPUT COOL relay |
| 2 | $=1$ OUTPUT COOL logic |
| 3 | $=1$ OUTPUT COOL continuous $0 . . .20 \mathrm{~mA} / 0 . . .10 \mathrm{~V}$ |
| 4 | $=1$ OUTPUT COOL triac 250Vac 1A |
| 5 | - |
| 6 | $=$ ACPC-M no power |
| 7 | $=1$ ACPC-M 40A |
| 8 | $=1$ ACPC-M 60A |
| 9 | $=1$ ACPC-M 100A |
| 10 | $=1$ ACPC-M 150A |
| 11 | $=1$ ACPC-M 200A |
| 12 | $=1$ ACPC-M 250A |
| 13 | $=1$ ACPC-M Xtra |

508 [HEH $\quad$ R $\quad$| Hardware configuration |
| :---: |
| codes 1 |

| Table of hardware configuration codes 1 |  |
| :--- | :--- |
| bit |  |
| 0 | $=1$ INPUT AUX absent |
| 1 | $=1$ INPUT AUX TC $/ 60 \mathrm{mV}$ |
| 2 | - |
| 3 | $=1$ FIELDBUS ETH4 (ProfiNet) |
| 4 | $=1$ FIELDBUS ETH5 (Ethernet IP) |
| 5 | $=1$ FIELDBUS ETH6 |
| 6 | $=1$ FIELDBUS absent |
| 7 | $=1$ FIELDBUS Modbus |
| 8 | $=1$ FIELDBUS Profibus |
| 9 | $=1$ FIELDBUS CanOpen |
| 10 | $=1$ FIELDBUS |
| 11 | $=1$ FIELDBUS Ethernet |
| 12 | $=1$ FIELDBUS Euromap66 |
| 13 | $=1$ FIELDBUS ETH3 |
| 14 | $=1$ FIELDBUS ETH2 (Ethercat) |
| 15 | $=1$ FIELDBUS ETH1 (Ethernet Real Time) |


| 543 | CHED | R | Hardware configuration codes 2 | Table of hardware configuration codes 2 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | bit |  |
|  |  |  |  | 0 | = 1 ACPC-E1 no power |
|  |  |  |  | 1 | = 1 ACPC-E1 40A |
|  |  |  |  | 2 | = 1 ACPC-E1 60A |
|  |  |  |  | 3 | = 1 ACPC-E1 100A |
|  |  |  |  | 4 | = 1 ACPC-E1 150A |
|  |  |  |  | 5 | = 1 ACPC-E1 200A |
|  |  |  |  | 6 | = 1 ACPC-E1 250A |
|  |  |  |  | 7 | = 1 ACPC-E1 Xtra |
|  |  |  |  | 8 | = 1 ACPC-E2 no power |
|  |  |  |  | 9 | = 1 ACPC-E2 40A |
|  |  |  |  | 10 | = 1 ACPC-E2 60A |
|  |  |  |  | 11 | = 1 ACPC-E2 100A |
|  |  |  |  | 12 | = 1 ACPC-E2 150A |
|  |  |  |  | 13 | = 1 ACPC-E2 200A |
|  |  |  |  | 14 | = 1 ACPC-E2 250A |
|  |  |  |  | 15 | = 1 ACPC-E2 Xtra |
| 543 | CHE3 | R | Hardware configuration codes 3 |  | Table of hardware configuration codes 3 |
|  |  |  |  | bit |  |
|  |  |  |  | 0 | $=1$ ACPC-M 300A |
|  |  |  |  | 1 | = 1 ACPC-E1 300A |
|  |  |  |  | 2 | = 1 ACPC-E2 300A |

## Hardware \& Software Information (400 to 300A Models)

The following data registers can be used to identify the controller HW/SW and check its operation.

| 122 | UP昂 | R | Software version code |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 190 | [HE | R | Hardware configuration codes |  | Table of hardware configuration codes |
|  |  |  |  | bit |  |
|  |  |  |  | 0 | = 1 OUTPUT AUX absent |
|  |  |  |  | 1 | = 1 OUTPUT AUX relay |
|  |  |  |  | 2 | = 1 OUTPUT AUX logic |
|  |  |  |  | 5 | $=1$ OUTPUT AUX continuous 12bit $20 \mathrm{~mA} / 10 \mathrm{~V}$ |
|  |  |  |  | 6 | = ACPC-M no power |
|  |  |  |  | 7 | $=1$ ACPC-M 200A |
|  |  |  |  | 8 | $=1$ ACPC-M 400A |
|  |  |  |  | 9 | $=1$ ACPC-M 600A |
|  |  |  |  | 10 | $=-$ |
|  |  |  |  | 11 | = - |
|  |  |  |  | 12 | = - |
|  |  |  |  | 13 | = - |
|  |  |  |  | 14 | = 1 EXTERNAL CT (for all models: $1 \mathrm{PH} / 2 \mathrm{PH} / 3 \mathrm{PH}$ ) |
|  |  |  |  | 13 | $=1$ ACPC-M Xtra |
|  |  |  |  | 12 | $=1$ ACPC-M 250A |


| 508 | [HEH | R | Hardware configuration codes 1 | Table of hardware configuration codes 1 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | bit |  |
|  |  |  |  | 2 | - |
|  |  |  |  | 3 | = 1 FIELDBUS ETH4 (ProfiNet) |
|  |  |  |  | 4 | = 1 FIELDBUS ETH5 |
|  |  |  |  | 5 | = 1 FIELDBUS ETH6 |
|  |  |  |  | 6 | = 1 FIELDBUS absent |
|  |  |  |  | 7 | = 1 FIELDBUS Modbus |
|  |  |  |  | 8 | = 1 FIELDBUS Profibus |
|  |  |  |  | 9 | = 1 FIELDBUS CanOpen |
|  |  |  |  | 10 | = 1 FIELDBUS DeviceNet |
|  |  |  |  | 11 | = 1 FIELDBUS Ethernet |
|  |  |  |  | 12 | = 1 FIELDBUS Euromap66 |
|  |  |  |  | 13 | = 1 FIELDBUS ETH3 |
|  |  |  |  | 14 | = 1 FIELDBUS ETH2 (Ethercat) |
|  |  |  |  | 15 | = 1 FIELDBUS ETH1 (Ethernet IP) |


| 543 | CHEC | R | Hardware configuration codes 2 | Table of hardware configuration codes 2 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | bit |  |
|  |  |  |  | 0 | = 1 ACPC-E1 no power |
|  |  |  |  | 1 | = 1 ACPC-E1 200A |
|  |  |  |  | 2 | = 1 ACPC-E1 400A |
|  |  |  |  | 3 | $=1$ ACPC-E1 600A |
|  |  |  |  | 4 | = - |
|  |  |  |  | 5 | = - |
|  |  |  |  | 6 | = - |
|  |  |  |  | 7 | = - |
|  |  |  |  | 8 | = 1 ACPC-E2 no power |
|  |  |  |  | 9 | = 1 ACPC-E2 200A |
|  |  |  |  | 10 | = 1 ACPC-E2 400A |
|  |  |  |  | 11 | = 1 ACPC-E2 600A |
|  |  |  |  | 12 | = - |
|  |  |  |  | 13 | = - |
|  |  |  |  | 14 | = - |
|  |  |  |  | 15 | $=-$ |


| $\begin{aligned} & 693 \\ & 697 \end{aligned}$ | UPDF | R | Fieldbus software version |
| :---: | :---: | :---: | :---: |
| 695 | COHF | R | Fieldbus node |
| 696 | BRHLF | R | Fieldbus baudrate |


| Profibus |  | Canopen |  | Eithernet |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| bAu.F | baudrate | bAu.F | baudrate | bAu.F | baudrate |
| 0 | $12.00 \mathrm{Mbit} / \mathrm{s}$ | 0 | $1000 \mathrm{Kbit} / \mathrm{s}$ | 0 | $100 \mathrm{Mbit} / \mathrm{s}$ |
| 1 | $6.00 \mathrm{Mbit} / \mathrm{s}$ | 1 | $800 \mathrm{Kbit} / \mathrm{s}$ | 1 | $10 \mathrm{Mbit} / \mathrm{s}$ |
| 2 | $3.00 \mathrm{Mbit} / \mathrm{s}$ | 2 | $500 \mathrm{Kbit} / \mathrm{s}$ |  |  |
| 3 | $1.50 \mathrm{Mbit} / \mathrm{s}$ | 3 | $250 \mathrm{Kbit} / \mathrm{s}$ |  |  |
| 4 | $500.00 \mathrm{Kbit} / \mathrm{s}$ | 4 | $125 \mathrm{Kbit} / \mathrm{s}$ |  |  |
| 5 | $187.50 \mathrm{Kbit} / \mathrm{s}$ | 5 | $100 \mathrm{Kbit} / \mathrm{s}$ |  |  |
| 6 | $93.75 \mathrm{Kbit} / \mathrm{s}$ | 6 | $50 \mathrm{Kbit} / \mathrm{s}$ |  |  |
| 7 | $45.45 \mathrm{Kbit} / \mathrm{s}$ | 7 | $20 \mathrm{Kbit} / \mathrm{s}$ |  |  |
| 8 | $19.20 \mathrm{Kbit} / \mathrm{s}$ | 8 | $10 \mathrm{Kbit} / \mathrm{s}$ |  |  |
| 9 | $9.60 \mathrm{Kbit} / \mathrm{s}$ |  |  |  |  |



| 622 | 185 | R/W | Function of LED O1 | Table of OUT LED functions |  | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | 0 | Disabled |  |
| 623 | L.56 | R/W | Function of LED O2 | 1 | Repetition of state OUT 1 |  |
|  |  |  |  | 2 | Repetition of state OUT 2 | 2 |
|  |  |  |  | 3 | Repetition of state OUT 3 |  |
| 624 | Lワ7 | R/W | Function of LED O3 | 4 | State key | 3 |
|  |  |  |  | 5 | Repetition of state OUT 5 |  |
| 625 |  |  | Function of LED Button | 6 | Repetition of state OUT 6 |  |
|  | 1.88 | R/W |  | 7 | Repetition of state OUT 7 |  |
|  |  |  |  | 8 | Repetition of state OUT 8 | 4 |
|  |  |  |  | 9 | Repetition of state OUT 9 |  |
|  |  |  |  | 10 | Repetition of state OUT 10 |  |
|  |  |  |  | + 16 | LED flashing if active |  |

## LED status refers to the corresponding parameter,

 with the following special cases:- LED RN (green) on: hotkey functionality
- LED RN (green) + LED ER (red) both flashing rapidly: autobaud in progress
- LED ER (red) on: error in one of main inputs (Lo, Hi, Err, Sbr)
- LED ER (red) flashing: temperature alarm ((OVER_ HEAT or TEMPERATURE_SENSOR_BROKEN) or alarm of SHORT_CIRCUIT_CURRENT or SSR_ SAFETY or FUSE_OPEN (only for singlephase configuration).
- LED ER (red) + LED Ox (yellow) both flashing: HB alarm or POWER_FAIL in zone $x$
- All LEDs flashing rapidly: ROTATION123 alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED DI1: jumper configuration not provided
- All LEDs flashing rapidly except LED DI2: 30\%_UNBALANCED_ERROR alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED O1: SHORT_ CIRCUIT_CURRENT alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED O2: TRIPHASE_MISSING_LINE_ERROR alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED O3: SSR_ SAFETY alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED BUT: FUSE_ OPEN alarm (only for threephase configuration)
$\left.\begin{array}{|c|c|c|}\hline \text { 305* } & \text { R/W } & \text { Current state (STATUS_W) } \\ \hline 698 & & \text { R }\end{array} \begin{array}{c}\text { State saved in eeprom } \\ \text { (STATUS_W_EEP) }\end{array}\right]$

| $\|c\| c\|c\| c \mid$ | 0 |  |  |  |
| :---: | :--- | :---: | :---: | :---: |
| Table of state settings |  | Zone 1 | Zone 2 | Zone 3 |
| Bit |  | 0 | 0 | 0 |
| 0 | - | Zone 1 | Zone 2 | Zone 3 |


| $467^{*}$ | $R$ | State (STATUS) |
| :--- | :--- | :--- |


|  | Table of State |
| :---: | :--- |
| bit |  |
| 0 | AL. 1 or AL. 2 or AL. 3 or AL. 4 or ALHB.TA1 or ALHB. |
| 1 | TA2 or ALHB.TA3 or Power Fault |
| 2 | Input Lo |
| 3 | Input Hi |
| 4 | Input Sbr |
| 5 | heat |
| 6 | cool |
| 7 | LBA |
| 8 | AL. 1 |
| 9 | AL. 2 |
| 10 | AL.3 |
| 11 | AL. 4 |
| 12 | ALHB or Power Fault |
| 13 | ON/OFF |
| 14 | AUTO/MAN |
| 15 | LOC/REM |
|  |  |


| $469^{*}$ | $R$ | State 1 (STATUS 1) |
| :--- | :--- | :--- |


| Table of State 1 |  |
| :---: | :--- |
| bit |  |
| 0 | AL. 1 or AL. 2 or AL.3 or AL.4 or ALHB.TA1 or ALHB. |
| 1 | TA2 or ALHB.TA3 or Power Fault |
| 2 | Input Lo Hi |
| 3 | Input Err |
| 4 | Input Sbr |
| 7 | LBA |
| 8 | AL. 1 |
| 9 | AL.2 |
| 10 | AL.3 |
| 11 | AL.4 |
| 12 | ALHB.TA1 |
| 13 | ALHB.TA2 |
| 14 | ALHB.TA3 |
| 15 | Selftuning active |
| 14 | AUTO/MAN |
| 15 | LOC/REM |



## Functional Diagram



LED BUT (yellow) off
3-phase configuration
All LEDs flash rapidly except for
LED BUT (yellow) FUSE_OPEN alarm
oppure
LED 01 (yellow)SHORT_CIRCUIT_CURREN T alarm

|  |  |
| :---: | :--- |
| bit |  |
| 0 | frequency_warning |
| 1 | 10\% unbalanced_line_warning |
| 2 | 20\% unbalanced_line_warning |
| 3 | $30 \%$ unbalanced_line_warning |
| 4 | rotation123_error |
| 5 | three-phase_missing_line_error |
| 6 | 60 Hz |

## Instrument Configuration Sheet (40 to 300A Models)

## Programmable Parameters

| Definition of Parameter | Note | Assigned Value |
| :---: | :---: | :---: |

Installation of Modbus Serial Network


## Analog Input



## Main Input

| 400 | Tup | R/W | Probe, signal, enable, custom linearization and main input scale |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 403 | np5 | R/W | Decimal point position for input scale |  |  |
| 401 | 105 | R/W | Min. scale limit for main input |  |  |
| 402 | HH5 | R/W | Max. scale limit for main input |  |  |
| 519 23 | OFS | R/W | Main input offset correction |  |  |
| $\underset{470}{0}$ | PV | R/W | Read of process variable (PV) engineering value |  |  |
| 349 | DPV | R | Read of engineering value of process variable (PV) filtered by FLd |  |  |
| 85 | ERR | R | Self-diagnosis error code for main input |  |  |
| 24 | FLT | R/W | Iow pass digital filter for input signal |  |  |


| 179 | FLB | R/W | Digital filter on oscillations of input signal |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 86 | 5.00 | R/W | Engineering value attributed to Point 0 (min. value of input scale) |  |  |
| 87 | 5.01 | R/W | Engineering value attributed to Point 1 |  |  |
| 88 | 5.02 | R/W | Engineering value attributed to Point 2 |  |  |
| 89 | 5.83 | R/W | Engineering value attributed to Point 3 |  |  |
| 90 | 5.84 | R/W | Engineering value attributed to Point 43 |  |  |
| 91 | 5.05 | R/W | Engineering value attributed to Point 5 |  |  |
| 92 | 5.06 | R/W | Engineering value attributed to Point 6 |  |  |
| 93 | 5.07 | R/W | Engineering value attributed to Point 7 |  |  |
| 94 | 5.08 | R/W | Engineering value attributed to Point 8 |  |  |
| 95 | 5.09 | R/W | Engineering value attributed to Point 9 |  |  |
| 96 | 5.16 | R/W | Engineering value attributed to Point 10 |  |  |
| 97 | 5.11 | R/W | Engineering value attributed to Point 11 |  |  |
| 98 | 5.12 | R/W | Engineering value attributed to Point 12 |  |  |
| 99 | 5.13 | R/W | Engineering value attributed to Point 13 |  |  |
| 100 | 5.14 | R/W | Engineering value attributed to Point 14 |  |  |
| 101 | 5.15 | R/W | Engineering value attributed to Point 15 |  |  |
| 102 | 5.16 | R/W | Engineering value attributed to Point 16 |  |  |
| 103 | 5.17 | R/W | Engineering value attributed to Point 17 |  |  |
| 104 | 5.18 | R/W | Engineering value attributed to Point 18 |  |  |
| 105 | 5.19 | R/W | Engineering value attributed to Point 19 |  |  |
| 106 | 5.20 | R/W | Engineering value attributed to Point 20 |  |  |
| 107 | 5.라 | R/W | Engineering value attributed to Point 21 |  |  |


| 108 | 5.2己 | R/W | Engineering value attributed to Point 22 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 109 | 5.23 | R/W | Engineering value attributed to Point 23 |  |  |
| 110 | 5.24 | R/W | Engineering value attributed to Point 24 |  |  |
| 111 | 5.25 | R/W | Engineering value attributed to Point 25 |  |  |
| 112 | 5.26 | R/W | Engineering value attributed to Point 26 |  |  |
| 113 | 5.27 | R/W | Engineering value attributed to Point 27 |  |  |
| 114 | 5.28 | R/W | Engineering value attributed to Point 28 |  |  |
| 115 | 5.29 | R/W | Engineering value attributed to Point 29 |  |  |
| 116 | 5.30 | R/W | Engineering value attributed to Point 30 |  |  |
| 117 | 5.31 | R/W | Engineering value attributed to Point 31 |  |  |
| 118 | 5.32 | R/W | Engineering value attributed to Point 32 (max. value of input scale) |  |  |
| 293 | 5.33 | R/W | Engineering value attributed to minimum value of the input scale |  |  |
| 294 | 5.34 | R/W | Engineering value attributed to maximum value of the input scale. |  |  |
| 295 | 5.35 | R/W | Engineering value of input signal corresponding to temp. of $50^{\circ} \mathrm{C}$. |  |  |

## Load Current Value

| 746＊ | LTH | R | Minimum limit of CT ammeter input scale（phase 1） |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 747 | LTRE | R | Minimum limit of CT ammeter input scale（phase 2） |  |  |
| 748 | －TRコ | R | Minimum limit of CT ammeter input scale（phase 3） |  |  |
| 405 | HTH | R | Minimum limit of CT ammeter input scale（phase 1） |  |  |
| 413 | HTRE | R | Minimum limit of CT ammeter input scale（phase 2） |  |  |
| 414 | HTらコ | R | Minimum limit of CT ammeter input scale（phase 3） |  |  |
| 220 | 明㫛 | R／W | Offset correction CT input （phase 1） | 0.0 zone 2 | $\begin{gathered} 0.0 \\ \text { zone } 3 \end{gathered}$ |
| 415 | ロTRE | R／W | Offset correction CT input （phase 2） |  |  |
| 416 | 口TR3 | R／W | Offset correction CT input （phase 3） |  |  |


| 227 |
| :---: | :---: | :---: | :---: | :---: |
| $473-139$ | 隹

Value of Load Voltage

| 751＊ | LT．V | R | Voltage on load |
| :---: | :---: | :---: | :---: |
| 710＊ | LR．V5 | R | Load voltage instantaneous |
| 711＊ | LI．VAF | R | Load voltage with output activated |
| 752 | L－\％ | R | Voltage on 3－phase load |

## Line Voltage Value



Power On Load

| 719* | LIP | R | Power on load |
| :---: | :---: | :---: | :---: |
| 720 | L APT | R | Power on Load 3-Phase |
| 749* | LR | R | Impedance on load |
| 750 | L明 | R | Impedance on load 3-phase |
| 531 | LIEE | R | Energy on load |
| 541 | L 847 | R | Energy on 3-phase load |
| 510 | LnEE | R | Energy on load |
| 541 | LDAT | R | Energy on 3-phase load |
| 114 bit** $^{\text {a }}$ | LDEt | R/W | ```OFF = - ON = Reset Ld.E1``` |
| 115* bit | LDEC | R/W | $\begin{aligned} & \text { OFF = - } \\ & \text { ON = Reset Ld.E1 } \end{aligned}$ |

Digital Input


Generic Alarms AL1, AL2, AL3 and AL4



LBA Alarm（Loop Break Alarm）

| 195 | RLP | R／W | Select number of enabled alarms |  |
| :---: | :---: | :---: | :---: | :---: |
| 44 | L8T | R／W | Delay time for LBA alarm activation |  |
| 119 | L | R／W | Limit of supplied power in presence of LBA alarm |  |
| $\begin{aligned} & 81 \\ & \text { bit } \end{aligned}$ | Reset LBA alarm |  | R | OFF＝－ <br> ON＝Reset alarm LBA |
| $\begin{gathered} 8 \\ \text { bit } \end{gathered}$ | State of LBA alarm |  | R | OFF＝LBA off ON＝LBA alarm on |

Heater Break Alarm


| $\underset{\text { bit }}{112^{*}}$ | Calibration HB alarm setpoint |  | R | $\begin{aligned} & \text { OFF = Calibration n } \\ & \text { ON = Calibration } \end{aligned}$ | enabled nabled |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 742＊ | H87R | R／W | CT read in HB calibration |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 452＊ | H8TV | R／W | TV read in HB calibration |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 743＊ | HAP w | R／W | Ou．P power in calibration |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 758＊ | RTR日 | R／W | HB calibration with IR lamp current at 100\％conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 759＊ | IRTR | R／W | HB calibration with IR lamp current at $50 \%$ conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 760＊ | RTRE | R／W | HB calibration with IR lamp current at $30 \%$ conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 761＊ | 促明 | R／W | HB calibration with IR lamp current at $20 \%$ conduction |  |  | 0.0 <br> Zone 1 | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 767＊ | RTR4 | R／W | HB calibration with IR lamp current at $15 \%$ conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 1 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 768＊ | RTR5 | R／W | HB calibration with IR lamp current at $10 \%$ conduction |  |  | 0.0 Zone 1 | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |


| 769＊ | IRTH6 | R／W | HB calibration with IR lamp <br> （only in mode PA） <br> current at 5\％conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | 0.0 Zone 3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 382＊ | 快T月7 | R／W | HB calibration with IR lamp <br> （only in mode PA） current at 3\％conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | 0.0 Zone 3 |
| 383＊ | IRT月8 | R／W | HB calibration with IR lamp <br> （only in mode PA） current at 2\％conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | 0.0 <br> Zone 3 |
| 384＊ | IRTR9 | R／W | HB calibration with IR lamp （only in mode PA） current at 1\％conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | 0.0 Zone 3 |
| 445＊ | RT VB | R／W | HB calibration with IR lamp Voltage at $100 \%$ conduction |  |  |  |  |
| 446＊ | RT V | R／W | HB calibration with IR lamp Voltage at 50\％conduction |  |  |  |  |
| 447＊ | RT VE | R／W | HB calibration with IR lamp Voltage at $30 \%$ conduction |  |  |  |  |
| 448＊ | IRT V3 | R／W | HB calibration with IR lamp Voltage at $20 \%$ conduction |  |  |  |  |
| 449＊ | 隹T V | R／W | HB calibration with IR lamp Voltage at 15\％conduction |  |  | $\begin{array}{\|c\|} \hline 0.0 \\ \text { Zone } 2 \end{array}$ | 0.0 <br> Zone 3 |
| 450＊ | 敉TV5 | R／W | HB calibration with IR lamp Voltage at $10 \%$ conduction |  |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 3 \\ \hline \end{gathered}$ |
| 451＊ | 取T VE | R／W | HB calibration with IR lamp <br> （only in mode PA） <br> Voltage at 5\％conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | 0.0 Zone 3 |
| 390＊ | IRTV1 | R／W | HB calibration with IR Iamp （only in mode PA） <br> Voltage at $100 \%$ conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | 0.0 Zone 3 |
| 391＊ | 敉T VB | R／W | HB calibration with IR lamp （only in mode PA） <br> Voltage at $100 \%$ conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | 0.0 Zone 3 |
| 392＊ | 粚 V9 | R／W | HB calibration with IR lamp <br> （only in mode PA） <br> Voltage at 1\％conduction |  |  | $\begin{gathered} 0.0 \\ \text { Zone } 2 \end{gathered}$ | $\begin{gathered} 0.0 \\ \text { Zone } 3 \end{gathered}$ |
| 744 | HRTR |  |  | HB alarm setp function of powe | t as <br> load |  |  |
| $\underset{\text { bit }}{26^{*}}$ | Stare of HB alarm or POWER＿Fault |  | R／W | $\begin{aligned} & \mathrm{OFF}=\text { Alarm } \\ & \mathrm{ON}=\text { Alarm } \end{aligned}$ |  |  |  |
| $\begin{gathered} 76^{*} \\ \text { bit } \end{gathered}$ | State of HB Alarm phase 1 |  | R |  |  |  |  |
| $77$ | State of HB Alarm phase 2 |  | R | with 3－phase load |  |  |  |
| $\begin{aligned} & 78 \\ & \text { bit } \end{aligned}$ | State of HB Alarm phase 3 |  | R | with 3－phase load |  |  |  |
| 504 |  | R S | States of alarm HB ALSTATE＿HB （for 3－phase loads） |  |  |  |  |
| 512＊ |  | R | States of alarm ALSTATE （for single－phase loads） |  |  |  |  |
| 318 |  | R | State of alarm ALSTATE IRQ |  | 76 |  |  |

Alarm SBR - ERR (Probe in short or connection error)


Power Fault ALARMS (SSR_SHORT, NO_VOLTAGE and NO_CURRENT)


## Alarm due to overload

$\left.\begin{array}{|c|c|c|}\hline 655^{*} & & R\end{array}\right]$ INNTC_SSR

## Fuse Open and Short Circuit Current Alarms

| 456 | FR\% | R/W | Number of restarts in case of FUSE_OPEN / SHORT_CIRCUIT_CURRENT |  |  |  | 0.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & 109 \\ & \text { bit } \end{aligned}$ | RESET FUSE_OPEN /SHORT CIRCUIT_CURRENT ALARMS |  |  | R/W | $\begin{aligned} & \text { OFF =- } \\ & \text { ON = Reset FUSE_OPEN } \end{aligned}$ | ORT_CIRCUIT_CURRENT alarms |  |
| $\begin{aligned} & 116 \\ & \text { bit } \end{aligned}$ | $\begin{aligned} & \text { RESETTING } \\ & \text { FOG } \end{aligned}$ |  |  | R/W | ```OFF = - ON = Reset count FO.c1``` |  |  |
| *Address 116 bit is 40-300A Only |  |  |  |  |  |  |  |
| 634* |  | R | State 4 (STATUS4) |  |  | Table of Instrument state 4 |  |
| 434* | FOI | R | Counter 1: FUSE_OPEN events |  |  |  |  |
| 436* | FDEC | R | Counter 2: FUSE_OPEN events |  |  |  |  |

*Address 434 \& 436 bit are 40-300A Only

## Outputs



| $\begin{aligned} & 308 \\ & 319 \end{aligned}$ | R | State rL.x MASKOUT |  |
| :---: | :---: | :---: | :---: |
| $\frac{12^{*}}{\text { bit }}$ | STATE rL. 1 | R | OFF = Output off ON = Output on |
| ${ }_{\text {bit }}{ }^{*}$ | STATE rL. 2 | R | OFF = Output off ON = Output on |
| ${ }_{\text {bit }}^{14^{*}}$ | STATE rL. 3 | R | OFF = Output off ON = Output on |
| $15^{15^{*}}$ | STATE rL. 4 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| ${ }_{\text {bit }}^{16^{*}}$ | STATE rL. 5 | R | OFF = Output off <br> ON = Output on |
| $\begin{gathered} 17^{*} \\ \text { bit } \end{gathered}$ | STATE rL. 6 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |

## Allocation of Physical Outputs



| 85 <br> bit | State of output OUT4 | R |  |
| :--- | :--- | :--- | :--- |
| 86 <br> bit | State of output OUT5 | R |  |
| 87 <br> bit | State of output OUT6 | R |  |
| 88 <br> bit | State of output OUT7 | R |  |
| 89 <br> bit | State of output OUT8 | R |  |
| 90 <br> bit | State of output OUT9 | R |  |
| 91 <br> bit | State of output OUT10 | R |  |
| 664 |  | R | State outputs (MASKOUT_OUT) |

## Automatic/Manual Control



## Hold Funtion

| 140 | DHE | R/W | Digital input function |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| 618 | RHE | R/W | Digital input function 2 |  |  |
| 64 <br> bit | HOLD | R/W | OFF $=$ hold off <br> ON $=$ hold on |  |  |

## Manual Power Correction

| $505^{*}$ | RHF | R/W | Line voltage |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $506^{*}$ | CRR | R/W | Manual power correction based <br> on line voltage |  |  |
| 18 <br> $136-249$ | $5 P R$ | R/W | Remote setpoint (SET Gradient <br> for power correction |  |  |

## Software Shutdown



## Software Power On



Fault Action Power


## Power Alarm



## Operating Hour Meter



## Trigger Modes



## Soft Start



Delay Triggering


## Feedback Modes



## Heuristic Power Control



## Heterogeneous Power Control



Virtual Instrument Control

| 191 | HEH | R/W | Enable multiset instrument <br> control via serial |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| $224^{*}$ | SHI | R/W | Control Inputs from Serial |  |  |
| 225 | SGU | R/W | Control Outputs from Serial |  |  |
| 628 | SLI | R/W | Control LEDs and digital inputs <br> from serial |  |  |



| $305^{*}$ |  | R/W | State (STATUS_W) |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| $467^{*}$ |  | R | State (STATUS) |  |  |
| $469^{*}$ |  | R | State 1 (STATUS1) |  |  |
| $632^{*}$ |  | R | State 2 (STATUS2) |  |  |
| $633^{*}$ |  | R | State 3 (STATUS3) |  |  |
| $634^{*}$ |  | R | State 4 (STATUS4) |  |  |
| 702 |  | R | Voltage Status |  |  |

## Instrument Configuration Sheet (400 to 600A Models)

| Definition of Parameter | Note | Assigned Value |
| :---: | :---: | :---: |

Installation of Modbus Serial Network


Analog Input

| 573 | TPR | R/W | Analog Input 1 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 837 | TPRE | R/W | Analog Input 2 |  |  |
| 844 | TPR3 | R/W | Analog Input 3 |  |  |
| 574 | L5R | R/W | Minimum scale limit analog input |  |  |
| 838 | L5RE | R/W | Minimum scale limit analog input 2 |  |  |
| 845 | LSR3 | R/W | Minimum scale limit analog input 3 |  |  |
| 575 | H5RH | R/W | Maximum scale limit analog input 1 |  |  |
| 839 | HSRE | R/W | Maximum scale limit analog input 2 |  |  |
| 846 | H5R3 | R/W | Maximum scale limit analog input 3 |  |  |
| 577 | OFSR | R/W | Offset correction for analog input 1 |  |  |
| 841 | OFSRE | R/W | Offset correction for analog input 2 |  |  |
| 848 | 㫙5R3 | R/W | Offset correction for analog input 3 |  |  |



## Main Input



## Load Current Value

| $746^{*}$ | LTRH | R | Minimum limit of CT ammeter <br> input scale (phase 1) |
| :---: | :--- | :--- | :---: |
| 747 | LTRE | R | Minimum limit of CT ammeter <br> input scale (phase 2) |
| 748 | LTRE | R | Minimum limit of CT ammeter <br> input scale (phase 3) |
| $405^{*}$ | HTRt | R | Minimum limit of CT ammeter <br> input scale (phase 1) |
| 413 | HTRE | R | Minimum limit of CT ammeter <br> input scale (phase 2) |
| 414 | HTG3 | R | Minimum limit of CT ammeter <br> input scale (phase 3) |
| $220^{*}$ | 日TR | R/W | Offset correction CT input <br> (phase 1) |
| 415 | 日TRE | R/W | Offset correction CT input <br> (phase 2) |


| 416 | RTRコ | R/W | Offset correction CT input <br> (phase 3) |
| :---: | :--- | :--- | :--- | :--- |
| 393 | RTR | R/W | Offset correction for <br> external CT input |
| 227 <br> $485-139-755$ | ITR | R | Instantaneous CT input <br> value (phase 1) |
| 490 | ITRE | R | Instantaneous CT input <br> value (phase 2) |
| 494 |  |  |  |

Value of Load Voltage

| 751* | LR. V | R | Voltage on load |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 710* | 1-L.V5 | R | Load voltage instantaneous |  |  |  |  |
| 711* | LT. VIF | R | Load voltage with output activated |  |  |  |  |
| 752* | L-1 | R | R Voltage on 3-phase load |  |  |  |  |
| 439* | LT. V! | R | Minimum limit of TV_LOAD voltmeter input scale |  |  |  |  |
| 443* | HT. VL | R | Maximum limit of TV_LOAD voltmeter input scale |  |  |  |  |
| 444 | ПT. Vi | R/W | Offset correction voltmeter transformer input TV_LOAD |  |  |  |  |
| 442 | FT.T VL | R/W | Digital filter voltmeter input TV_LOAD | 0.0 ..20.0 sec | $0.1$ <br> zone 1 | 0.1 <br> zone 2 | 0.1 <br> zone 3 |

## Line Voltage Value

| $453^{*}$ | LTV | R | Minimum limit of TV voltmeter <br> input scale (phase 1) |
| :---: | :---: | :---: | :---: | :---: |
| 454 | LTVE | R | Minimum limit of TV voltmeter <br> input scale (3-phase, 2-leg) |
| 455 | LTVE | R | Minimum limit of TV voltmeter <br> input scale (3-phase, 3-leg) |
| 410 | HTV | R | Maximum limit of TV voltmeter <br> input scale (phase 1) |
| 417 | HTVE | R | Minimum limit of TV voltmeter <br> input scale (3-phase, 2-leg) |
| 418 | HTVE | R | Minimum limit of TV voltmeter <br> input scale (3-phase, 3-leg) |
| $412^{*}$ | FTTU | R/W | Digital filter TV auxiliary input <br> (phase 1,2,3) |

Power on Load

| $\begin{gathered} 880 \\ 719 \text { LSW } \end{gathered}$ | LRP | R | Power on load |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} 882 \\ 720 \mathrm{LSW} \end{gathered}$ | LDPT | R | Power on Load 3-Phase |
| 749* | - | R | Impedance on load |
| 750 | L | R | Impedance on load 3-phase |
| 531* | L HE\| | R | Energy on load |
| 541 | 1847 | R | Energy on 3-phase load |
| $510^{*}$ | LDEC | R | Energy on load |
| 541 | L 84 | R | Energy on 3-phase load |
| 114 bit | LDEt | R/W | $\begin{aligned} & \text { OFF = - } \\ & \text { ON = Reset Ld.E1 } \end{aligned}$ |
| 115 bit | LDEC | R/W | $\begin{aligned} & \text { OFF = - } \\ & \text { ON = Reset Ld.E1 } \end{aligned}$ |

Digital Inputs


| 356 | PumT1 | R/W | Timeout for input PWM 1 |
| :---: | :---: | :---: | :---: |
| 357 | PUPTE | R/W | Timeout for input PWM 2 |
| 362 | Pumpe | R/W | Timeout for input PWM 3 |
| 438 | FTPLM | R/W | Digital low pass filter input PWM 1 |
| 372 | FTPLITP | R/W | Digital low pass filter input PWM 2 |
| 373 | FTPLTE | R/W | Digital low pass filter input PWM 3 |
| $68$ | State of Digital Input 1 |  | R OFF = Digital input 1 off <br> ON $=$ Digital input 1 on |
| $\begin{aligned} & 92 \\ & \text { hit } \end{aligned}$ | State of Digital Input 2 |  | R OFF $=$ Digital input 2 off <br> ON $=$ Digital input 2 on |
| $\begin{aligned} & 67 \\ & \text { bit } \end{aligned}$ | State of Digital Input 3 |  | R OFF = Digital input 3 off <br> ON = Digital input 3 on  |
| $\begin{aligned} & 66 \\ & \text { bit } \end{aligned}$ | State of Digital Input 4 |  | $\begin{array}{l\|l} \hline \text { R } & \text { OFF = Digital input } 4 \text { off } \\ \text { ON }=\text { Digital input } 4 \text { on } \end{array}$ |
| 317 |  | R S | State of digital inputs INPUT DIG |
| 518 | In.PWM 1 | R | PWM 1 input value |
| 435 | In.PWM 2 | R | PWM 2 input value |
| 457 | In.PWM 3 | R | PWM 3 input value |

Alarms




Heater Break Alarm

| $195^{*}$ | RLR | R/W | Select number of enabled alarms |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| $57^{*}$ | HBF | R/W | HB alarm function |  |  |
| $56^{*}$ | HBT | R/W | Delay time for HB alarm activation |  |  |


| $112^{*}$ |
| :---: | :---: | :---: | :---: |
| bit | | Calibration HB |
| :---: |
| alarm setpoint |$\quad \mathrm{R} \quad$| OFF = Calibration not enabled |
| :---: |
| ON = Calibration enabled |



| 743＊ | HEP w | R／W | Ou．P power in calibration |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 758＊ | RTRE | R／W | HB calibration with IR lamp current at 100\％conduction |  |  |  |  |
| 759＊ | IRTR | R／W | HB calibration with IR lamp current at $50 \%$ conduction |  |  |  |  |
| 760＊ | RTRE | R／W | HB calibration with IR lamp current at $30 \%$ conduction |  |  |  |  |
| 761＊ | 怾阴 | R／W | HB calibration with IR lamp current at $20 \%$ conduction |  |  |  |  |
| 767＊ | RTR4 | R／W | HB calibration with IR lamp current at $15 \%$ conduction |  |  |  |  |
| 768＊ | RTR5 | R／W | HB calibration with IR lamp current at 10\％conduction |  |  |  |  |
| 769＊ | RTRE | R／W | HB calibration with IR lamp current at 5\％conduction |  |  |  |  |
| 382＊ | RTR7 | R／W | HB calibration with IR lamp current at 3\％conduction |  |  |  |  |
| 383＊ | RTR日 | R／W | HB calibration with IR lamp current at 2\％conduction |  |  |  |  |
| 384＊ | RTRS | R／W | HB calibration with IR lamp current at 1\％conduction |  |  |  |  |
| 445＊ | 隹 V V | R／W | HB calibration with IR lamp Voltage at 100\％conduction |  |  |  |  |
| 446＊ | IRT V | R／W | HB calibration with IR lamp Voltage at $50 \%$ conduction |  |  |  |  |
| 447＊ | RT Ve | R／W | HB calibration with IR lamp Voltage at $30 \%$ conduction |  |  |  |  |
| 448＊ | 隹 V3 | R／W | HB calibration with IR lamp Voltage at $20 \%$ conduction |  |  |  |  |
| 449＊ | 隹 V－1 | R／W | HB calibration with IR lamp Voltage at $15 \%$ conduction |  |  |  |  |
| 450＊ | RTV5 | R／W | HB calibration with IR lamp Voltage at $10 \%$ conduction |  |  |  |  |
| 451＊ | 隹 V 6 | R／W | HB calibration with IR lamp （only in mode PA） <br> Voltage at 5\％conduction |  |  |  |  |
| 390＊ | $\operatorname{RTT}^{7} \mathrm{~V}$ | R／W | HB calibration with IR lamp （only in mode PA） <br> Voltage at 100\％conduction |  |  |  |  |
| 391＊ | RT VB | R／W | HB calibration with IR lamp （only in mode PA） <br> Voltage at $100 \%$ conduction |  |  |  |  |
| 392＊ | 㰨 Vg | R／W | HB calibration with IR lamp （only in mode PA） <br> Voltage at 1\％conduction |  |  |  |  |


| $744^{*}$ | HRTR | R | HB alarm setpoint as <br> function of power on load |
| :---: | :---: | :---: | :---: |
| $26^{*}$ <br> bit | Stare of HB alarm <br> or POWER_Fault | R/W |  |
| 76* <br> bit | State of HB Alarm <br> phase 1 TA | R |  |
| 77 | State of HB Alarm <br> phase 2 TA | R |  |
| bit |  |  |  | | phe |
| :---: |

Power Fault ALARMS (SSR_SHORT, NO_VOLTAGE and NO_CURRENT)


| ${ }_{9}^{96^{*}}$ | State of alarm SSR_SHORT phase 1 | R |  |
| :---: | :---: | :---: | :---: |
| $97$ | State of alarm SSR_SHORT phase 2 | R |  |
| $\underset{\text { bit }}{98}$ | State of alarm SSR_SHORT phase 3 | R |  |
| $\underset{\text { bit }}{99^{*}}$ | State of alarm NO_VOLTAGE phase 1 | R |  |
| $\begin{gathered} 100 \\ \text { bit } \end{gathered}$ | State of alarm NO_VOLTAGE phase 2 | R |  |
| $\begin{aligned} & 101 \\ & \text { bit } \end{aligned}$ | State of alarm NO_VOLTAGE phase 3 | R |  |
| $\begin{gathered} 102 \\ \mathrm{bit} \end{gathered}$ | State of alarm <br> NO_CURRENT phase 1 | R |  |
| $\begin{gathered} 103 \\ \text { bit } \end{gathered}$ | State of alarm NO_CURRENT phase 2 | R |  |
| $\begin{gathered} 104 \\ \text { bit } \end{gathered}$ | State of alarm NO_CURRENT phase 3 | R |  |

## Alarm due to overload



Fuse Open and Short Circuit Current Alarms


Allocation of Reference Signal


## Allocation of Physical Outputs



| $\begin{aligned} & 82 \\ & \text { bit } \end{aligned}$ | State of output OUT1 | R | OFF = Output off <br> ON = Output on |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & 83 \\ & \text { bit } \end{aligned}$ | State of output OUT2 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| $\begin{aligned} & 84 \\ & \text { bit } \end{aligned}$ | State of output OUT3 | R | OFF = Output off <br> ON = Output on |
| $\begin{aligned} & 85 \\ & \text { bit } \end{aligned}$ | State of output OUT4 | R | OFF = Output off <br> ON = Output on |
| $\begin{aligned} & 86 \\ & \text { bit } \end{aligned}$ | State of output OUT5 | R | OFF = Output off <br> ON = Output on |
| $87$ | State of output OUT6 | R | OFF = Output off ON = Output on |
| $\begin{aligned} & 88 \\ & \text { bit } \end{aligned}$ | State of output OUT7 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| $\begin{aligned} & 89 \\ & \text { bit } \end{aligned}$ | State of output OUT8 | R | OFF = Output off <br> ON = Output on |
| $\begin{aligned} & 90 \\ & \text { bit } \end{aligned}$ | State of output OUT9 | R | OFF = Output off ON = Output on |
| $\begin{aligned} & 91 \\ & \text { bit } \end{aligned}$ | State of output OUT10 | R | $\begin{aligned} & \text { OFF = Output off } \\ & \text { ON = Output on } \end{aligned}$ |
| 664 | R Sta | ou | (MASKOUT_OUT) |

## Analog Output



| 727 | SERIAL_OUTA1 | R/W | Serial line value for analog <br> output 1 |
| :--- | :--- | :--- | :---: |


| 728 | SERIAL_OUTA2 | R/W | Serial line value for analog <br> output 2 |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| 729 | SERIAL_OUTA3 | R/W | Serial line value for analog <br> output 3 |  |  |



Control

| 617 | GPU | R/W | Power reference |  |
| :---: | :---: | :---: | :---: | :---: |
| $2^{*}$ <br> $132-471$ | 日UP | R | Value control outputs |  |
| $765^{*}$ | PPER | R/W | Percentage of output power |  |
| $766^{*}$ | PGF5 | R/W | Offset of output power |  |


| $763^{*}$ | GOUT | R/W | Gradient for output control |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $764^{*}$ | LGP | R/W | Minimum ignition output |  |  |

## Automatic/Manual Control



## Manual Power Correction

| 505 | RIF | R/W | Line Voltage |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 506 | ᄃRR | R/W | Correction of manual power <br> based on line voltage |  |  |
| 18 <br> $136-249$ | gPR | R/W | Remote setpoint (SET gradient <br> for manual power correction) |  |  |

Start Mode


Software Shutdown

| 140 | R/G | R/W | Digital Input Function 1 |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 618 | RGE | R/W | Digital Input Function 2 |  |  |
| 694 | RGE | R/W | Digital Input Function 3 |  |  |



## Heating Output (Fast Cycle)



## Operating Hour Meter

$\square$

## SSR Trigger Mode

| $703^{*}$ | HB5 | R/W | Enable Trigger Modes |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| $707^{*}$ | FUTR | R/W | Max. limit of RMS <br> current in normal operation |  |  |  |
| $704^{*}$ | RFFU | R/W | Minimum number of cycles of BF <br> modes |  |  |  |

## Soft Start Trigger Mode



| 107* |
| :---: | :---: | :---: | :---: |
| bit | | State of phase |
| :---: |
| softstart ramp |$\quad \mathrm{R} \quad$| OFF $=$ Ramp not ended |
| :---: |
| ON $=$ Ramp ended |

Delay Triggering


Feedback Modes


| $113^{*}$ |
| :---: | :---: | :---: | :---: |
| bit | | Calibration of voltage |
| :---: |
| feedback reference |$\quad$ R/W | OFF = Calibration not enabled |
| :---: |
| ON = Calibration enabled |


| $886^{*}$ |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $757^{*}$ | RRF | $R$ | Feedback |  |  |
| LSW only |  |  |  |  |  |

## Heuristic Power Control



## Heterogeneous Power Control

| 682 | H54 | R/W | Enable heterogeneous power control |  |
| :---: | :---: | :---: | :---: | :---: |
| 683 | HET | R/W | Maximum current for heterogeneous power control |  |

## Virtual Instrument Control

| 191 | HRH | R/W | Enable multiset instrument <br> control via serial |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| $224^{*}$ | SHf | R/W | Control Inputs from Serial |  |  |
| 225 | SAL | R/W | Control Outputs from Serial |  |  |
| 628 | SLI | R/W | Control LEDs and digital inputs <br> from serial |  |  |

HW/SW Data



Limited Warranty:
Please refer to the Chromalox limited warranty applicable to this product at http://www.chromalox.com/customer-service/policies/termsofsale.aspx.

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[^0]:    *Address 434 \& 436 bit are 40-300A Only

