Installation & Operation Manual

3204 1/32 DIN Autotune Temperature Controller





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Safety and Warranty Information

Installation



Designed for use:

UL873 - only in products where the acceptability is determined by Underwriters Laboratories Inc.

EN61010-1 - within installation Categories II and III environment and pollution degree 2.

To avoid possible hazards accessible conductive parts of final installation should be protectively earthed in accordance with EN61010 for Class 1 equipment. Output wiring should be within a grounded cabinet. Sensor sheaths should be bonded to ground or not be accessible. Live parts should not be accessible without use of a tool. It is the responsibility of the installation engineer to ensure that this equipment's compliance to EN61010 is not impaired when fitted to the final installation and to use this equipment as specified in this manual, failure to do so may impair the protection provided.

Ensure the installation is in compliance with appropriate wiring regulations.

Configuration

All functions are front selectable, it is the responsibility of the installing engineer to ensure that the configuration is safe. Use the program lock to protect critical functions from tampering.

Ultimate Safety Alarms

Do not use SP2 as the sole alarm where personal injury or damage may be caused by equipment failure.

Warranty and Returns Statement

These products are sold by Chromalox under the warranties set forth in the following paragraphs. Such warranties are extended only with respect to a purchase of these products, as new merchandise, directly from Chromalox or from a Chromalox distributor, representative or reseller and are extended only to the first buyer thereof who purchases them other than for the purpose of resale.

Warranty

These products are warranted to be free from functional defects in material and workmanship at the time the products leave Chromalox factory and to conform at that time to the specifications set forth in the relevant C instruction manuals sheet or sheets, for such products for a period of three years.

THERE ARE NO EXPRESSED OR IMPLIED WAR-RANTIES, WHICH EXTEND BEYOND THE WAR-RANTIES HEREIN AND ABOVE SET FORTH.

CHROMALOX MAKES NO WARRANTY OF MER-CHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE WITH RESPECT TO THE PRODUCTS.

Limitations

Chromalox shall not be liable for any incidental damages, consequential damages, special damages, or any other damages, costs or expenses excepting only the cost or expense of repair or replacement as described above. Products must be installed and maintained in accordance with Chromalox instructions. There is no warranty against damage to the product resulting from corrosion. Users are responsible for the suitability of the products to their application.

For a valid warranty claim, the product must be returned carriage paid to the supplier within the warranty period. The product must be properly packaged to avoid damage from electrostatic discharge or other forms of harm during transit.

Functions Menu

ription. If		s Models	r 56t	RESET		Quick Start Entry	, ,		5EE.2 bnd.2 [55.2	SP2 SETTINGS	AdjustSP2 PropSP2 CycleSP2Band/Gain/On/OffSetpointHystOn.off; 0.1+/- sensor0.1 degto 81 secfull scaleto 100%to 81 secorsensor f/sorfull scale(2°C/3.6°F)				
ider desc	. DIOC	ut Option:	- Lu Lu Lu Lu Lu Lu Lu Lu Lu Lu Lu Lu Lu L	Software	Consult unit	یہ د	RE INPUT	Select Display Units "F; bAr; PSi; Ph; rh; SEt	5oRt	TTINGS	Soak Time Off; 0 to 1440 min				
in red un		SSd Outpi jured.	LECh	DATA	Read Tune Data CtA; Ctb; Ct1; Ct2; Ct3; Ct3; Ct4; oS1; uS; oS2		CONFIGUR	Select Input Sensor nonE	SPrn	MMER SE	Ramp Off/ On; off; hold				
ent shown	settings s	and Dual { pre-confiț	r£8d	DRMANCE	Read Monitor VAr; hi; lo deg	Lo.5C	BING	Set Scale Min. 0.0 Sensor min to sensor full scale	5Prr	PROGRA	Setpoint Ramp Rate 0 to 9990 deg/hour				0
f Adjustme	le, ractory	ual Relay ir outputs	נאני	PERFO	Set Monitor Off, on	h 5C	RANG	Set Scale Max. 0.0 Sensor max to sensor full scale	5P.LY		Setpoint Lock (SP1) Off; on				NCTION
Range of	applicap	* Note: D have the	ZEro	ATION	Zero Adjust- ment 0.0 to 25% sensor full scale	d (5p	Display Resolu-	tion 1 or 0.1 degree	o ^F 5t		Offset (Manual Reset) 0 to 50% × bAnd (In.t = off)				IEW FUI
			5PRn	CALIBR	Span Adjust- ment 0.0 to 25% sensor f/s	5P2.b	ODES	Second SP2 Mode nonE; LtCH; hold; Lt.ho; nLin	C3C. Ł		Cycle Time or On/Off On.off; 0.1 to 81 sec (20 sec)				► TO V
dEr .S		Derivative Sensitivity 0.1 to 1.0 x dErt (0.5)	۲۴u.۲	ŝ	Reverse O/P LEDs 1n.2n; 1i.2n; 1n.2i; 1i.2i	5P2.8	SP2 M	Main SP2 Mode nonE; dV.hi; dV.Lo; bAnd; FS.hi; FS.hi;	ЯЧ	NGS	Derivative Approach 0.5 to 5.0 x bAnd (1.5)				<pre>KEY ▼ or</pre>
2.2 b	TTINGS	Display Averaging dir; 1 to 32 (6)	rEu.d	LY SETTING	Reverse Outputs 1r.2d; 1d.2d; 1r.2r; 1d.2r	2. 24		Limit SP2 Output % 100 to 0%	dEr.t	SP1 SETTI	Derivative Time (Rate) Off; 1 to 200 sec (25 sec)	dbuC		Tx/Rx Activity Off; on	
no . RL	ROTECTED SE	Disable -AL- Alarm Display Off; on	նսո	SAFEI	Sensor Burn-Out uP.SC; dn.SC; 1u.2d; 1d.2u	۲. ۱ ۲. ۱	DJUSTMENTS	Limit SP1 Output % 100 to 0%	nt.t		Integral Time (Reset) Off, 0.1 to 60 min (5 min)	dRt R	SETTINGS	Data Format 18n1:18E1:1801	
Pro[USER P	Disable Program Auto-Exit Auto; StAY	5P2.d	ΚΕ ΟUTPUT	SP2 Output Device n1Y (read only)	hRnd	MANUAL A	SP1 Manual Output % 0 to 100% proportional mode only	bRnd		SP1 Prop Band (gain)/hyst 0.1 deg to 25% sensor f/s (10°C/18°F)	bng	COMMS	Baud Rate 1200: 2400: 4800: 9600: 19k2	
Lott		Security Lock nonE; LEV 3; LEV 2; ALL	5P 1. d	CONFIGUR	SP1 Output Device NonE; rIV; SSd	5P 1, P		Read SP1 Output % 0 to 100% read only	μυξ		Autotune or Park oFF; on; tunE; ParK; At.Sp	Rddr		Instrument Address 0 to 255	
L EULY		CNI	LEUL3	40	רבעברס טע	5 1031					Program Entry	LEULC	Level C	only vis- ible when COMMS Option fitted.	

1



INSTRUMENT ADJUSTMENTS

To enter or exit program mode:	Press \blacktriangle \blacktriangledown together for 3 seconds
To scroll through functions :	Press ▲ or ▼
To change levels or options:	Press \star \blacktriangle together or \star $\mathbf{\nabla}$ together
To view setpoint:	Press ★
To increase setpoint:	Press \star \blacktriangle together
To decrease setpoint:	Press \star \blacksquare together
To reset an alarm or fault condition:	Press $\blacktriangle igvee$ together briefly

Notes: If experiencing difficulty by becoming "lost" in program mode, press \blacktriangle and ∇ together for 3 seconds to return to display mode, check the INSTRUMENT ADJUSTMENTS above and try again.

When in program mode, after 60 seconds of key inactivity the display will revert to either **nonE** or, if the initial configuration has been completed, the measured value. Any settings already completed will be retained.

Quick Start

After power-up the controller requires programming with the following information:

- Type of Sensor
- Operating unit
- Allocation of Output Device to SP1/SP2 (Relay or SSd)
- Temperature Setpoint eg. Degrees

When the above information has been programmed into the controller it will be operational with the following factory settings.

Proportional band/Gain	10°C/18°F
Integral time/Reset	5 mins
Derivative time/Rate	25 secs
Proportional cycle-time	20 secs
(Typical setting for relay output)	
DAC Derivative approach control	1.5
(Average setting for min_overshoot)	

TIP: Please note that in this manual, the functions are reversed out from a black background and the options are shown in bold italic:

eg. EunE and ParK

Note: In this manual the letter k is represented by the character

Note: During the following procedure the display will revert to alternating **mpb** and **nonE** after 60 seconds of key inactivity, but will retain any settings already completed. Should this occur, or in the event of becoming 'lost' in the program, please start again from the alternating **mpb** and **nonE** display.

Quick Start Set-Up

On power-up the controller will display the self test sequence followed by alternating **InPt** and **nonE**

1. Select input sensor

Press and hold \star and use the \blacktriangle or ∇ buttons to scroll through the sensor selection list until the correct sensor is displayed. Release the buttons.

The display now alternates selected sensor type (eg. אין and **Tc.S**)

Press ▲ once. The display will now alternate unt

2. Select unit.

Press and hold \star and use the \blacktriangle or ∇ buttons to scroll through the unit selection list until the correct unit is displayed.

Release the buttons. The display will now alternate selected unit (eg. unit and °C).

Press ▲ once. The display will now alternate

3. Select SP1 (Main setpoint output device)

Note: Dual Relay and Dual SSd Output Options Models have their outputs pre-configured. See Section: Factory Set Output Options.

Press and hold \star and use the \blacktriangle or ∇ buttons to select **SSd** or **rLY** as required. The controller will now alternate selected output device (e.g. **SPLd** and **SSd**).

4. To enter initial configuration into controller memory

Press and hold both ▲ and ▼ buttons for 3 seconds. The display will now alternate *ParK* and measured variable (temperature) (eg. 23) *ParK* is displayed because a setpoint has not yet been entered.

To display setpoint

Press and hold ★ The display will now alternate <u>*Q*</u> and *unit* (eg. °*C*)

To enter setpoint

Press and hold \star and use \blacktriangle button to increase or \blacktriangledown button to decrease the reading and scroll to required setpoint value. (The digit roll-over rate increases with time).

THE CONTROLLER IS NOW OPERATIONAL WITH FACTORY SETTINGS

Note: For precise control of an application the controller may need to be TUNED. Please study section headed FUNCTIONS and OPTIONS before moving to the section on AUTOTUNE.

Introduction

The Controller



The 3204 control can be optimized with a single shot autotune either on initial warm-up or at setpoint. A second setpoint can be configured in a variety of alarm modes or PID Heat-Cool strategy. A programmer offers a single ramp to setpoint with a choice of timed soak period before switching off the output.

Control of non temperature processes is achieved by the provision of linear input ranges and scaling in commonly used engineering units.

Serial communication is available as an option on the 3204, and the easy to use SOFT-3204 is a graphic WINDOWS[®] based software package designed for PC supervision of up to 32 instruments, for remote adjust-

Overview

Installation

The Model 3204 controller is designed to be mounted in a 1/32 DIN panel cutout. See the MECHANICAL INSTAL-LATION section.

Set-Up

After installation the controller is to be programmed with the following information:

- Type of Input Sensor
- Operating unit (°C or °F etc.)
- Type of Output Device
- Temperature Setpoint

Note: The controller will not be operational until this information is entered.

When the above information has been programmed into the controller it will be operational with the following factory PID (proportional band, integral time, derivative time) settings. ment, configuration, cloning, saving and retrieving settings to files and logging and charting in real time.

SOFT-3204 uses the MODBUS[®] protocol via either a fully isolated RS232 or RS485 link depending on the number of instruments and the transmission distances involved in the application.

A user's manual is supplied with the comms option. For more information, contact Chromalox. See contact information on the last page of this manual.

It is suggested that users read the OVERVIEW section of this manual before any installation or set-up procedures are undertaken.

Note: The controller will not be operational until either the **QUICK-START** or **SET-UP** procedure has been completed.

TIP: Please note that in this manual, the functions are reversed out from a black background and the options are shown in bold italic:

eg. EunE and ParK

- Proportional band/Gain..... 10°C/18°F
- Integral time/Reset.....5 mins
- Proportional cycle-time......20 secs
- Derivative time/Rate.....25 secs
- DAC Derivative approach control......1.5

Autotune

To precisely control an application, the controller will need to be 'tuned' using the built-in '**AUTOTUNE**' feature. Autotune 'teaches' the controller the main characteristics of the process and 'learns' by cycling the output on and off. The results are measured and used to calculate optimum PID values which are automatically entered in the controller memory.

During **AUTOTUNE**, the optimum cycle-time is calculated but is not automatically implemented. The cycletime requires manual acceptance unless pre-selected.

To ensure good control over a wide range of applications, two versions of the Autotune program are provided, **TUNE** and **TUNE AT SETPOINT**. The **TUNE** method normally achieves the best results. Starting with the load cool, tuning occurs during warmup preventing overshoot. This method of tuning is recommended.

The **TUNE AT SETPOINT** method is used for specialist applications, eg. Heat-cool, multizones and processes below 100°C/200°F. During the tuning cycle some overshoot occurs because the tuning cycle is at set point.

The **DAC** setting is not re-calculated.

Cycle-Time

The choice of cycle-time is influenced by the external switching device or load. e.g. contactor, SSR, Valve. A setting that is too long for the process will cause oscillation and a setting that is too short will cause unnecessary wear to an electro-mechanical switching device.

Cycle-Time Selection Methods

The following methods of cycle-time selection may be used:

Autotune Calculated

After **Autotune** has been run and completed, the calculated cycle-time can be manually accepted or adjusted to suit the switching device. For selection method see **Select Autotune Calculated Cycle-time.**

Pre-Select Autotune Cycle-Time

The controller can be programmed to automatically accept the calculated **Autotune** cycle-time. For selection method see **Pre-Select Automatic Acceptance of Any Autotune Cycle-time**.

Pre-Select Before Autotune

The controller can be programmed manually with any cycle-time between 0.1 and 81 sec. This cycle-time will not be changed by any **Autotune** functions. For selection method see **Pre-Select Cycle-time Before Autotune**.

Factory Set

To use the 20 sec factory set cycle-time, no action is needed whether Autotune is used or not.

Further information can be programmed into the controller. See SECOND SETPOINT, RANGING AND SET-POINT LOCK, IMPROVING CONTROL ACCURACY

Functions and Options

The facilities of the controller are selected from the multilevel menu using the front panel mounted buttons.

Note: It is advisable to study this section before any programming is undertaken.

Each level within the multi-level menu offers different functions, see **FUNCTIONS MENU** for menu of main functions. Each function has a range of user selections or options, see **FUNCTION LIST** for functions and options details.

TIP: Please note that in this manual, the functions are reversed out from a black background and the options are shown in bold italic:

eg. EunE and ParK

The controller has two modes, program mode and operating mode. When in program mode, the controller can be programmed with settings and functions to suit the application. When in operating mode, the controller uses the setting and functions entered in the program mode to control the application and also displays the process variable (temperature). For full details on how to program the controller, see **VIEWING AND SE-LECTING FUNCTIONS.**

Note: In this manual the letter k is represented by the character

Set-Up

This section gives details on:

- Power-up,
- how to select the input sensor,
- how to select the operating unit,
- how to select SP1 (the main output device),
- how to enter the initial configuration,
- how to set the main set point.

Power-Up

On power-up, the controller will display the self test sequence and brief display blanking and then alternately display and **nonE**

Select Input Sensor

Press and hold \star and use either the \blacktriangle or \lor buttons to scroll through the sensor selection (see **FUNCTION MENU**). When the correct sensor is displayed, release the buttons. The controller will now alternately display selected sensor type \square and eg. *tc.S*

To Select °C/°F

Press and release the \blacktriangle button, the controller will now alternately display unit and **nonE**.

Press and hold the \star button and using the \blacktriangle button select °C, °F, Bar, PSI, Ph, Rh or SEt as required. Release the buttons when the correct unit is displayed.

The controller will now alternately display selected range (eg. °C) and unit.

To Select Sp1 (Main setpoint output device)

Press and release the \blacktriangle button, the controller will now alternately display 5P i.d and **nonE**.

Press and hold the \star button and using the \blacktriangle button select **SSd** or *r***LY** as required. Release the buttons when the correct device is displayed.

The controller will now alternately display **SP1.d** and selected output device (eg. **SSd**).

To Enter Initial Configuration into Controller Memory

Press and hold both \blacktriangle and \blacktriangledown buttons for 3 seconds. The process temperature (e.g. **23°C**) and **ParK** will be alternately displayed as no setpoint has yet been selected.

To Set the Main Setpoint

To display the setpoint, press and hold the \star button. °C and 0 or °F and 32 will be alternately displayed.

Press and hold the \star button. Press \blacktriangle to increase or \blacktriangledown to decrease the setpoint.

The main setpoint LED will flash indicating that SP1 output is ON.

The controller will now be set with the factory PID settings.



Menu Navigation

The facilities of the controller are selected from the multilevel menu using the front panel mounted buttons. Each level within the multi-level menu offers different functions, see **FUNCTIONS MENU** for menu of main functions. Each function has a range of user select or input options, see **FUNCTION LIST** for functions and options details.

The controller has two modes, program mode and operating mode. When in program mode the controller can be programmed with settings and functions to suit the application. When in operating mode the controller uses the setting and functions entered in the program mode to control the application.

Using Program Mode

Note: The controller will auto-exit program mode after 60 seconds of inactivity.

To Enter Program Mode from Normal Operating Mode Press and hold both \blacktriangle and \blacktriangledown buttons for at least 3 seconds.

Release the buttons together when the function \underline{c} is displayed, this is the program entry point. The controller will now alternately display the function and option (setting of that function), e.g. \underline{c} and **oFF**.

To View Function on the Same Level

Press \blacktriangle or \triangledown button once to view the next function. Press and hold \blacktriangle or \triangledown buttons to scroll through functions.

To Display the Current Option or Value for a Function On release of \blacktriangle or \blacktriangledown buttons, option alternates with the function.

To Change an Option Value or Setting

Press and hold the \star button, then press \blacktriangle to increase or $\mathbf{\nabla}$ to decrease the value or select the next option.

Note: Check the new option value before moving to another function or exiting program mode.

To Change Levels

Press and hold \checkmark to scroll through the functions until **LEUL** is displayed. Release \checkmark to display current level. Press and hold the \star button, then press \blacktriangle to increase or \checkmark to decrease the level. Release buttons when required level is obtained.

Note: Control commences with any new instructions now entered in the memory.

To Exit Program Mode

Press and hold both \blacktriangle and \blacktriangledown buttons for at least 3 seconds.

REMINDER OF INSTRUMENT ADJUSTMENTS

- Press ▲ and ▼ together for 3 seconds for program entry or exit.
- Press ▲ or ▼ to scroll through functions.
- Press ★ ▲ together or ★ ▼ together to change levels or alter options.

Note: If experiencing difficulty by becoming "lost" in program mode, press ▲ and ▼ together for 3 seconds to return to display mode, check the Menu Navigation summary above and try again.

Autotune

Select the most appropriate method of Autotune, Tune or Tune at Setpoint, to suit the application.

Note: The proportional cycle-time can be preselected before starting Autotune, **see PROPOR-TIONAL CYCLE-TIME.**

The **TUNE** program should be run with the load cool. The output is cycled at 75% of the setpoint value to avoid any overshoot during the tuning cycle. The warm-up characteristics are monitored and set DAC which minimizes overshoot on subsequent warm-ups.

The **TUNE AT SETPOINT** program is recommended:

- when the setpoint is below 100°C/200°F, where TUNE's tuning cycle at 75% setpoint may be too close to ambient to produce good results;
- when the process is already hot and the cooling rate is slow;
- when controlling multi-zone or heat-cool applications;
- to re-tune if the setpoint is changed substantially from previous Autotune.

Note: dAC is not re-tuned by TUNE AT SETPOINT. **Tune Program** Temp Setpoint PID Tuning DAC եՍոե Cycle 75% SP New PID 1-1/4 on/off values tuning cycles entered Start ElloE Time (100% output)

Enter program mode and select

The controller will alternately display LunE and oFF.

Press and hold \star and press \blacktriangle once,

The controller will alternately display $\lfloor un \rfloor$ and **on**.

Exit program mode.

The **TUNE** program will now start. The controller will alternately display \underline{EunE} and the process temperature as it climbs to setpoint.

Note: During tuning, the main setpoint (SP1) LED will flash.

When the **TUNE** program is complete the alternating display stops and the process temperature is displayed. The PID values are entered automatically. The process temperature will rise to setpoint and control should be stable. If not, this may be because optimum cycle time is not automatically implemented. To set the cycle time see **PROPORTIONAL CYCLE-TIME.**

Tune at Setpoint Program



Enter program mode and select

The controller will alternately display LunE and oFF.

Select Lune At.SP.

The controller will alternately display **LunE** and **At.SP.**

Exit program mode.

The **TUNE AT SETPOINT** program will now start. The controller will alternately display **LunE** and the process temperature.

Note: During tuning, the main setpoint (SP1) LED will flash.

When the **TUNE AT SETPOINT** program is complete the alternating display stops and the process temperature is displayed. The PID values are entered automatically. The process temperature will rise to setpoint and control should be stable. If not, this may be because optimum cycle time is not automatically implemented. To set the cycle time see **PROPORTIONAL CYCLE-TIME.**

REMINDER OF INSTRUMENT ADJUSTMENTS

- Press ▲ and ▼ together for 3 seconds for program entry or exit.
- Press ▲ or ▼ to scroll through functions.
- Press ★ ▲ together or ★ ▼ together to change levels or alter options.

Note: If experiencing difficulty by becoming "lost" in program mode, press ▲ and ▼ together for 3 seconds to return to display mode, check the Menu Navigation summary above and try again.

Proportional Cycle-Time

The choice of cycle-time is influenced by the external switching device or load, eg. contactor, SSR, valve. A setting that is too long for the process will cause oscillation and a setting that is too short will cause unnecessary wear to an electro-mechanical switching device.

Cycle-Time Selection Methods

The following methods of cycle-time selection may be used:

Autotune Calculated

After Autotune has been run and completed, the calculated cycle-time can be manually accepted or adjusted to suit the switching device. For selection method see **Select Autotune Calculated Cycle-time**.

Pre-Select Autotune Cycle-Time

The controller can be programmed to automatically accept any calculated Autotune cycle-time. For selection method, see **Pre-Select Automatic Acceptance of Any Autotune Cycle-time**.

Pre-Select Before Autotune

The controller can be programmed manually with any cycle-time between 0.1 and 81 sec. This cycle-time will not be changed by any Autotune functions. For selection method, see **Pre-Select Cycle-time Before Autotune**.

Factory Set

To use the 20 sec factory set cycle-time no action is needed whether autotune is used or not.

Cycle-Time Recommendations

Output	Factory	Recomm.	Load Max.
Device	Setting	Minimum	(resistive)
Internal relay rLY/rLY1	20 seconds	10 seconds	2A/250 Vac
Internal relay rLY/rLY2	20 seconds	10 seconds	1A/250 Vac
Solid state drives SSd/SSd1/SSd2	20 seconds	0.1 seconds	Externally fitted SSR (n/a)

To Select AUTOTUNE CALCULATED CYCLE-TIME

On completion of Autotune enter program mode.

Select [46 . E

The controller will now alternately display **[]** and **20** (the factory setting).

To view the calculated optimum cycle-time press and hold the \star button then press and hold \blacktriangledown until indexing stops.

The controller will display the calculated cycle-time **Here** and eg. *A* 16. This indicates that the calculated cycle-time is 16 seconds. If this cycle-time is suitable press and hold both ▲ and ▼ buttons for 3 seconds to enter it into the controllers memory.

If the calculated cycle-time is not compatible with the switching device press and hold the \star button then press and hold \blacktriangle or ∇ until a more suitable cycle-time is displayed. Release the buttons, then press and hold both \blacktriangle and ∇ buttons for 3 seconds to enter it into the controllers memory.

Pre-Select Automatic Acceptance of any Autotune Cycle-time

Before selecting Autotune, enter program mode.

- 1. Select [][.]
- Press and hold the ★ button then press and hold ▼ until indexing stops and *A* - is displayed.
 Note: *A* - indicates that no cycle-time exists.
- **3.** Press and hold \checkmark to scroll to $\exists u \in \xi$

The controller will now alternately display $\underline{\mathsf{LunE}}$ and **oFF.** Press and hold the \star button and use \blacktriangle to select either **on** or **At.SP**. Release \blacktriangle .

The controller will now run Autotune and will accept the calculated cycle-time.

To Pre-Select Cycle-time Before Autotune

Before selecting Autotune, enter program mode.

Select [4[. E

Press and hold the \star button, then press \blacktriangle to increase or \blacktriangledown to decrease the displayed cycle-time. Release buttons when required value is displayed.

Select \underline{EunE} or index to another function then exit

program mode.



Programmer

Ramp-Soak

This feature enables the controller to ramp up or down from current temperature to a target setpoint at a predetermined rate. It then controls at the target setpoint for an adjustable soak period before switching off the heat output.

Set Ramp rate (0 to 9995 deg/hour)

- Press ▲ and ▼ buttons for 3 seconds to enter program entry point 上unE
- 2. Press s to scroll to SPrr
- Press and hold ★, then press ▲ or ▼ to scroll to required value.

Set Soak (if required) 0 to 1440 minutes

- **4.** Press \blacktriangle to scroll to **SoRE**
- Press and hold ★, then press ▲ or ▼ to scroll to required soak period.
- 6. Set Ramp On (Off) : On : hold
- 7. Press \blacktriangle to scroll to $5P_{\Box \Box}$
- 8. Press and hold \star , then press \blacktriangle to select **On**



Exit program to enter settings into memory and commence ramp to target setpoint.

Notes:

- In Ramp on configuration, if power is removed from the controller, the Ramp will re-start when power is restored.
- The **Ramp hold** option suspends the ramp at its last value.
- If no **Soak** period has been set, control at target setpoint continues indefinitely.

SP2 deviation alarms follow the ramp setpoint and can be used to alarm "out of limits" ramp rate.

WARNING

The Soak timer is triggered when the ramp setpoint reaches the target setpoint. If the ramp rate is set too fast for the process, the Soak timer will be triggered before the process temperature reaches the target setpoint.

Second Set-Point (SP2)

The second setpoint SP2 can be used to trigger an alarm or as a proportional control output.

To Configure SP2 as an Alarm

Enter program mode.

Select level 2 then **SP2. R**, followed by the required option below:



- *dV.hi* sets off alarm signal when temperature rises above a pre-set temperature above the set-point.
- *dV.Lo* sets off alarm signal when temperature falls below a pre-set temperature below the set-point.
- **bAnd** sets off alarm signal when temperature rises above or falls below a pre-set temperature above or below the setpoint.
- *FS.hi* sets off alarm signal when the temperature rises above setpoint to a pre-set temperature above scale minimum.
- **FS.Lo** sets off alarm signal when the temperature falls below setpoint to a pre-set temperature above scale minimum.

Select level 1 and select 5EE.2 and set the required setpoint value (y°).

If the factory set hysteresis $2.0^{\circ}C/3.6^{\circ}F$ is unsuitable:

Index to bod. 2 and adjust the setting.

Check [42.2] is set to **on.oF** (for alarm).

Exit program mode. SP2 is now operational as an alarm.

CooL see heat-cool configuration.

SUBSIDIARY SP2 MODE: 5P2 b Latch/sequence or non-linear cool.

Latch alarm LtCh

When activated, the alarm latches until manually reset, even though the alarm condition may have disappeared.

Sequence alarm *hoLd*

When *hoLd* is selected, in any alarm mode, it prevents an alarm signal on power-up. The alarm is enabled only when the process temperature reaches setpoint.



To Configure SP2 as a Proportional Control Output

In level 2 select **SP2_R**, then select the required option.

In level 1 select **bnd**. and then set the required proportional band.

In level 1 select **SEE.2** and then set the setpoint (SP2) value (y°) .

SP2 Output and LED Indication States - In Alarm Condition

Alarm Type	On-C Operatino	Off g Mode	Propor Operatin	tional g Mode
Deviation	SP2 Output State	SP2 LED State	SP2 Output State	SP2 LED State
<u>dü.h</u> ı				
dü.lo				·
bAnd			anna On-0	Off Mode Only
Full Scale				
FS.h.		*	_ _	*
FS.Lo				·
Eool	-	Temperature	e above setpoin	t
Strategy	-•	*		*
-•		•	<u> </u>	
Outp (Belay or S	ut ON Sd energized)	Outpu (Belay or SSc	ut OFF 1 de-energized)	LED ON

SP2 Alarm Annunciator

When an SP2 alarm mode is selected in SP2.A the alarm annunciator *-AL-* is displayed, alternating with the process temperature, during alarm condition.

Note: The annunciator may be disabled by selecting function **no**. **RL**, option on in level 4.

SP2 in Cool Strategy

(See heat-cool configuration in ADVANCED SETTINGS



Error Messages

Sensor Fault

Display flashing:	חוPt and <i>FaiL</i>
Indicates:	thermocouple burnout RTD/Pt100
	open or short circuit or negative
	over-range.
Action:	Check sensor/wiring

Non-Volatile Memory Error

Display flashing:	dHEH and FaiL
Action:	De-power briefly. Replace unit if
	problem persists

Manual Power Error

- Display flashing: dRLR and FaiL SP1 set to ON/OFF in CYC.t
- Action: Select proportional mode

Immediate Fail On Autotune Start

Display flashing:	(setpoint), <code>としロE and <i>FaiL</i></code>
	1. No setpoint entered
Action:	Enter setpoint
	2. SP1 set to ON/OFF in

Action: Select proportional mode

Note: To reset and clear error press $\blacktriangle \nabla$ together briefly to cancel message.

Fail Later During Autotune Cycle

The thermal characteristics of the load exceed the Autotune algorithm limits. The failure point indicated by any display 0.0 in **EECH** eg. Ctb = 0.0 see diagram below.

- Action: 1. Change the conditions. eg. raise setpoint
 - 2. Try Lun At.SP
 - 3. Check SP1.P percentage power
 - (see IMPROVING CONTROL ACCURACY)
 - 4. If the error message persists, call for advice.

Reading Autotune Tuning Cycle Results in

- 1. Index to **LEEh**, release ▲ or ▼, display will alternately display **LEEh** and **Ct.A**
- Press and hold ★, the display will alternate Ct.A and value (eg. 10.4)
- Keep ▲ pressed and press ▲ once, the display Ct.B and value (eg. 19.6)
- Repeat step 3 above to view:
 Ct 1, Ct 2, Ct 3, Ct 4, oS 1, uS and oS 2.

Autotune tuning data and limits



Improving Control Accuracy

The following functions are to assist engineers with machine development, commissioning and trouble-shooting.

SPLP Read Sp1 Output Percentage Power

Poor control may be due to incorrectly sized heaters.

5P1P (Level 2) constantly displays the output percentage power applied, which at normal setpoint should ideally be within 20 - 80% to achieve stable control.

EHEH Control Accuracy Monitor

This measures the control stability, to within 0.1 °C/°F.

The monitor is started using **[hEV** (Level 3) and the variance (deviation), maximum and minimum temperatures are displayed and constantly updated in **rERd**



Using the **Control accuracy monitor** To start the monitor select **Chee** on

Note: During monitoring either return to normal operation or remain in program mode.

To view monitor readings: index to **FERd**

The display will alternate between rERd and Var°

Press and hold \star , the display will alternate between *Var*° and the variance displayed in degrees (e.g. 0.6)

Press and hold \star and press \blacktriangle once, the display will alternate between *VAr*° and the maximum *hi*° displayed in degrees (e.g. 320.3)

Press and hold \star and press \blacktriangle once, the display will alternate between VAr° and the minimum *Lo*° displayed in degrees (e.g. 319.7)

EALT oFF stops monitor retaining readings

[h[] on resets readings.

On de-powering [h[] resets to *oFF* and r []

is zeroed.

Function List

The functions and options are available in four levels.

Note: A Functions Menu is shown on the cover fold-out

LEVEL 1

Function Options [Factory settings] shown in brackets

Select Autotune Eune [oFF] on ParK At.Sp

Used to switch the Autotune feature on and off, to select **ParK** or Autotune at setpoint.

ParK temporarily turns the output(s) off. To use select ParK and exit program mode. To disable re-enter program at Eun and select oFF.

SP1 Operating Parameters aHnd 0.1 to * °C/°F [10°C/18°F]

SP1 proportional band/Gain or Hysteresis

* 25% sensor maximum

Proportional control eliminates the cycling of on-off control. Heater power is reduced, by time proportioning action, across the proportional band.



SP1 Integral Time/Reset

տեւե

Auto-corrects proportional control offset error



oFF



[5.0]



Too long (slow warm up and response)



Too short

under corrects)



SP1 Derivate Time/Rate

Suppresses overshoot and speeds response to disturbances

(slow warm up and response,





SP1 Derivative Approach Control dAC

Tunes warm-up characteristics, independent of normal operating conditions, by controlling when derivative action starts during warm-up (smaller dAC value = nearer setpoint).



A- on.oF 0.1 - 81 sec L AL [20] -

SP1 Proportional Cycle-Time

Determines the cycle rate of the output device for proportional control. Select on.oF for ON/OFF mode.



SP1 Offset/Manual Reset

* ±50% **bAnd**. Applicable in proportional and ON/OFF mode with integral disable: Int.t oFF.



Lock Main Setpoint

Locks the setpoint preventing unauthorised adjustment.

PROGRAMMER SETTINGS

[] [0] to 9995 deg/hour Sets the ramp rate

SPrn on [oFF] hoLd

Switches the ramp on or off, or hold at last ramp value

5a유본 [oFF] 0 to 1440 min

Sets the soak time

SP2 OPERATING PARAMETERS

SEL.2 0 to * °C/°F

Adjust SP2 setpoint

* Deviation Alarms **DV.hi, DV.Lo, bAnd** 25% sensor maximum.

[0]

* Full scale alarms FS.hi, FS.Lo sensor range f/s

LEVEL 2

MANUAL CONTROL MODES

SPIP 0 to 100% 'read only' Read SP1 output percentage power

hRnd [oFF] 1 to 100 % (not in ON/OFF)

SP1 Manual Percentage Power Control For manual control should a sensor fail. Record typical **SP1.P** values beforehand.

PL.1

100 to 0% duty cycle [100]

Set SP1 power limit percentage Limits maximum SP1 heating power during warm-up

and in proportional band.

PL.2100 to 0 % duty cycle[100]Set SP2 percentage power limit (cooling)

SP2 OPERATING MODES

SP2.R [nonE] dV.hi dV.Lo bAnd FS.hi FS.Lo Cool Main SP2 operating mode

LEVEL 3 OUTPUT CONFIGURATION

Note: 'Read only' after initial configuration. *rSET ALL* full reset to factory settings required to change SPI.d subsequently.

Select SP1 output device

SP2.d [nonE] SSd rLY rLY2 rLY1 SSd2 Read SP2 output device (read only)

Dual Relay and **Dual SSd** output options Models are factory set. See **Factory Set Output Options.**

SP2.b [nonE] LtCh hoLd nLin Subsidiary SP2 mode: latch/sequence

Non-linear cool proportional band

INPUT SELECTION AND RANGING d 5P [1] 0.1 Select display resolution: for display of process tem-

perature, setpoint, **OFSt, Set.2, hi.SC, LoSC.**

h ISE sensor minimum [sensor maximum] °C/°F Set full scale

Lo.5 [sensor minimum] sensor maximum °C/°F Set scale minimum (default 0°C or 32°F)

(See SENSOR SELECTION table)

unit nonE °C °F bAr Psi Ph rh SEt Select °C/°F or process units

Note: (when in initial configuration only) Hold \star and \blacktriangle or $\mathbf{\nabla}$ for 10 seconds to move to or from output devices in shaded portion.

<u>ս</u>սո

Sensor burn-out/break protection

ACAUTION

Settings affect fail safe state.

	<u>SP1</u>	<u>SP2</u>
[uP.SC]	Upscale	Upscale
dn.SC	Downscale	Downscale
1u.2d	Upscale	Downscale
1d.2u	Downscale	Upscale

bnd.2 0.1 - * °C/°F [2.0 °C/3.6°F]

Adjust SP2 hysteresis or proportional band/gain (see **CyC.2** setting) * 25% sensor f/s

[4].2 [on.oFF] 0.1–81 seconds

Select SP2 ON/OFF or Proportional Cycle-Time Select on.oFF for ON/OFF mode, or the cycle rate of SP2 output device for proportional mode.

rEu.d

Select output modes: Direct/Reverse

ACAUTION

Settings affect fail safe state.

	<u>SP1</u>	<u>SP2</u>
[1r.2d]	Reverse	Direct
1d.2d	Direct	Direct
1r.2r	Reverse	Reverse
1d.2r	Direct	Reverse

Select **Reverse** on SP1 for heating and **Direct** for cooling applications.

rEu.L

Select SP1/2 LED indicator modes

	<u>SP1</u>	<u>SP2</u>
[1n.2n]	Normal	Normal
1i.2n	Invert	Normal
1n.2i	Normal	Invert
1 <i>i.2i</i>	Invert	Invert

SPRn [0.0] to ±25% sensor maximum

Sensor span adjust

For recalibrating to a remote standard e.g. External

LEVEL 4

Program Security Using Lock

Select from three Lock options:

Press and hold \star , press \blacktriangle to index.

- LEV.3 locks level 3 and 4 only- Technical Functions.
- *LEV.2* locks levels 2, 3 and 4 only Configuration and Technical Functions.
- ALL locks all functions (unrestricted LEVL, VEr,

Note: Locked functions and options may be read.

Meter, data logger. See **ADVANCED SETTINGS**.

Zero [0.0] to ±25% sensor f/s Zero sensor error, see SPAn

EALT [oFF] on Select control accuracy monitor

r E Rd [Var] hi Lo Read control accuracy monitor

EE [Ct A] CT b Ct 1 Ct 2 Ct 3 Ct 4 oS 1 uS oS 2

Read Autotune tuning cycle data

UEr

Software version number

다 5년는 [nonE] ALL

Resets all functions to factory settings

ACAUTION

Note current configuration before using this function, otherwise initial configuration and OEM settings must be re-entered.

Press $\mathbf{\nabla}$ to access following functions

Prol [Auto] StAY

Program mode auto-exit switch Auto-exit returns display to normal if 60 seconds of key inactivity, select **StAY** to disable

Disable SP2 alarm annunciator -AL Select on to disable -AL

d 5.5 dir 1 to 32 [6]

Display sensitivity

dir = direct display of input

1 = maximum, 32 = minimum sensitivity

IMPORTANT NOTE FOR OEM's: For safety and to protect settings from tampering, USE THE SOFTWARE SECURITY LOCK, THEN REMOVE THIS SECTION

Factory Set Output Options

Dual Relay or Dual SSd Output Models

The table below details the factory set output options. rLY2 is a 1A electromechanical relay, and SSd1/SSd2 is an identical second SSR drive output.

	Terminals				
Model Type	3	4	5	6	
Dual Relay	rLY1 (2A)		rLY2 (1A)		
Dual SSR	SSd1		SS	d2	
Drive	(+)	(-)	(+)	(-)	

QUICK START or SET-UP

Follow steps 1 and 2 ignore step 3 and proceed straight to step 4.

Advanced Settings

Before embarking on the Advanced Settings, please familiarize yourself with the basic operation of the controller as described in this manual. The following instructions assume that the user understands how to make the initial configuration, can navigate through the Function Menu and successfully Autotune the controller in heating mode.

Heat Cool Strategy Configuration

Using 502.8 Cool Option

Heat-Cool strategy is a feature that improves control of processes that need heating and cooling, depending on the conditions, for example:

- Environmental test chambers used in rooms where the ambient temperature swings above and below the test temperature.
- Plastics extruders where the material initially needs heating, then cooling, when it begins to heat itself exothermically due to pressure and friction applied by the process.

The purpose of cool strategy is to maintain smooth control of the process during transition from heating to cooling.

This is achieved by using PID control for heating and

Dual Relay Models preallocate SP1 to terminals 3 and 4.

Note:	Output device rLY/rLY1 is rated 2A
	Output device rLY2 is rated 1A

Dual SSR Drive Models offer the ability to change the allocation of SP1 to terminals 5 and 6.

To make this selection during the initial configuration in either QUICK START or SET-UP, start from step 3.

TO SELECT SP1 (Main setpoint output device) From the alternating display $\mathbf{SP1d}$ and *rLY1* press and hold \star button then press the \blacktriangle once to display *rLY2*.

cooling with the proportioning bands linked by an adjustable deadband.

From Cold (normal procedure on a new installation) Enter setpoint and allow the process to reach the setpoint using factory settings for **heating only**.

Autotune at Setpoint

Make the following pre-settings:

Level 1	set data to 1.0 [][] to 10
	and []].2 to 10
Level 2	set SP2_R to Cool
Level 1	set LunE to At.SP

Autotune will cause a temporary disturbance. Check that the temperature has stabilized in **heating** mode before running the process in cooling mode.

If regular temperature oscillations occur, change CYC.t to optimum value. To select Autotune Calculated Cycle-time

Further adjustments – Cooling

Autotune uses the same calculated band value for both *SP1* (heating) and *SP2* (cooling). In some processes, regular temperature oscillations occur when cooling.

Make the following manual adjustment: In level 1 double the value of bnd. 2

If no improvement, return to the original value and; In level 1 halve the value of

If the process hunts between heating and cooling, a deadband setting may be needed. Enter a small value, eg. 1 and observe the process. Increase the setting until hunting stops.

Level 1 adjust value

Water Cooled Applications

Water cooled applications operating at temperatures greater than 100°C may suffer from the non linear effect caused by water turning to steam. This can be countered by the non linear setting for SP2;

In level 2 set 5P2 b to nL in

Multi Zone Applications

When tuning multi zone applications like extruders, distortions due to thermal interaction between adjacent zones can be minimized by running autotune on all controllers at the same time.

Calibration to Other Instrument

If the controller and instrument readings are different, the **25ro** and/or **59An** function in Function Menu Level 3 will require adjustment.

Adjust **2Ero** to make an equal adjustment across the full scale of the controller and SPAN to make a correction when the error increases/decreases across the scale.

To adjust using the ZERO function

 Substitute measured values in the expression: Instrument reading – controller reading =

26ro

Example: Instrument reading = 396° Controller reading = 400° $396 - 400 = (-)4^{\circ}$

2. Adjust **2Ero** to (-) 4° to correct error. To make a correction when there are different errors across the scale.

Adjust using the SPRn Function

- 1. Choose a temperature near the bottom and another near the top of the scale.
- 2. Run the process at the lower temperature (T1). Note the error (E1) between the controller and the instrument readings.
- 3. Repeat at the upper temperature (T2) and note error (E2).
- **4.** Substitute the values for T1, T2, E1 and E2 in the expression below to calculate **5PRn**

For hi.SC settings see level 2.

Example:	Τ ₁	T^2
Instrument reading	58°	385°
Controller reading	60°	400°
Error	E ₁ (-) 2°	E ₂ (-) 15°

5. Therefore adjust SPAn to (-) 18 to correct error.

Notes:

- (1) After making the adjustment, the reading will immediately change. Allow time for the temperature to stabilize at T2 before making any further adjustment. At this point, a *ZEro* adjustment may be needed, refer to step 1 above.
- (2) Check that the temperature correctly stabilizes at T2 and then adjust setpoints to T1. If an error is present at T1 repeat from step 2.

Linear Input Calibration

In addition to the ten temperature inputs, the controller has five linear input ranges which can be calibrated to display a range of engineering units. This procedure involves making adjustments to the controller's **h .5. 2Ero** and **SPRn** adjustments found in function menu levels 2 and 3.

Note: The controllers linear inputs are in mV. If your transducer provides an output in mA this should be converted to mV by feeding the controller input via a high stability one ohm resistor, see Figure 1. Other low Vdc signals can be connected via a suitable voltage divider network to match the controller input requirements.

Figure 1



 Power up the controller, and in response to the prompt nonE select an appropriate Linear Range from the table below.

Ensure that the Nominal Signal Span chosen is wider than the transducer's actual signal span, and the Nominal Scale is wider than the full scale of the engineering units to be displayed.

<u>Linear</u>	<u>Nom.</u>	<u>Nom.</u>	Max. Scale
<u>Range</u>	<u>Signal Span</u>	<u>Scale Span</u>	<u>Settings</u>
Lin 1	0–20 mV	0 - 100	0 - 400
Lin 2	4–20 mV	0 – 100	-25 to 400
Lin 3	0–20 mV	0 – 1000	0 to 3000
Lin 4	4–20 mV	0 – 1000	-250 to 3000
Lin 5	0–20 mV	0 – 2000	0 to 3000

2. Select unit, or, or, or, Bar, PSI, Ph or rh. If the required unit is not shown select Set.

3. Allocate the output devices at function **SP1.d** as described in **SET-UP**, enter the configuration into the memory and proceed as follows:

Calculate the values for the controller settings for **h** <u>155</u> and <u>578</u> using the example below as a guide:

4 to 7mV input from transducer is required to display 0 - 110 units

Chose Linear Range Lin4 4-20mV = 0 to 1000 units.

$$\frac{1}{52} = \frac{\text{Nominal Signal Span} \times \text{required span}}{\text{actual signal span}} \times \frac{(20-4)}{(7-4)} \times (110-0) = 587$$
(7-4)
(7-4)
(7-4)
(7-4)

Nominal Scale Span

These settings should provide the correct scaling adjustment, but a value for 2 Ero may need to be established by applying the lowest and highest mV input signal and recording the display offset. Check that this is the same at each end, and enter this plus or minus value as a 2 Ero adjustment. Should there be a difference between the two readings, a further adjustment of the 5 PRn setting can be made.

Communications Installation/Cabling

RS232 Connections

RS232 is widely used for interfacing peripherals to PC's and is designed for serial communications with single instrument up to distances of 15 metres, in a low electrical noise environment.

Connection is via a screened two core cable where the voltage signal on each line is referenced to the screen which is grounded. Most PC's have one or two RS232 compatible ports fitted as standard.

Figure 2



RS485 Connections

RS485 is a half duplex serial communications link and is the standard most commonly used for industrial applications due to it's high noise immunity and multidrop capability. It enables a PC to communicate with up to 128 instruments over distances up to 1200 metres, and requires the addition of an RS485 interface card, or a separate RS232/485 converter.

Figure 3



Instrument Comms Settings

Immediately after power-up, both instrument, and PC comms settings need to be made compatible before communication between them is possible. Instrument defaults are shown below together with available options.

Rddr (Address) This is a unique identification number that must be allocated to each instrument connected to the network.

Default = 0. Options; 1 to 247

bRud (Baud rate) The setting determines the serial communication data transmission rate in bits/sec, and must match the PC settings. **Default = 9600.**

Options:

1200; 2400; 4800; 9600 and 19200

NOTE: If a comms board has been retro fitted the default baud rate is 1200.

HALA (Data) Sets the transmission format, and must match the PC settings.

Data Format Table

Settings	Start Bits	Data Bits	Parity	Stop Bits
Default	1	8	n (none)	1
Option 1	1	8	e (even)	1
Option 2	1	8	o (odd)	1

(Debug) Commissioning and troubleshooting aid. Display shows when the instrument is transmitting or receiving data by rapidly flashing the three horizontal segments of the first and last digit of the display. **First digit = Tx; last digit = Rx**

Default = Off. Options; off; on

Only use dbuG during commissioning or troubleshooting because it shares display segments and therefore corrupts the normal display.

Configuring Instrument Comms Settings

This should also be done immediately after powerup, and is only possible from the instrument front panel.

On power-up the controller will display the self test sequence followed by Alternating, and **none.**

Note: During the following procedure the display will revert to alternating **TABL** and **none** after 60 seconds of keying inactivity, but will retain any settings already completed. Should this occur, or in the event of becoming 'lost' in the program, please start again from the alternating **TABL** and none display.

To select Level C (communications settings) Press ▼ once display alternates LEUL and 5 Press and hold ★ and ▼ five times to reach level C display alternates LEUL and C

Note: Level C is only visible when the comms interface board is fitted to the unit

To set instrument comms address Press \blacktriangle once display alternates $\square d \square$ and 0Press and hold \star and \blacktriangle to index to chosen address number (1 to 247)

Note: In the absence of any conflicting information the following comms settings should be left as the default values.

To Read or Adjust Comms Settings

Baud Rate

Press ▲ once display alternates **bRud** and **9600** (Default setting)

Press and hold \star and use \blacktriangle or \triangledown keys to select preferred value.

Data Format

Press \blacktriangle once display alternates $\square \square \square \square$ and **18n1** (Default setting) **Press and hold** \star and use \blacktriangle or \lor keys to select preferred setting.

Debug Setting

Press ▲ once display alternates dbub and OFF (Default setting)
(Default setting)
Press and hold ★ and use ▲ or ▼ keys to select ON

To Enter Settings Into Memory

Press and hold \blacktriangle and \triangledown for 3 seconds display alternates \square and none

To check settings, repeat the above procedure

The unit is now ready to be configured from the PC.

Note: Where more than one instrument is connected to the system, it is useful at this point to list them by location, title and comms address. The list can then be used as a reference to ensure that the instruments are given the same identity when configuring the comms link from the PC.

Mechanical Installation

3204's are sleeve mounted with their front bezel assembly rated NEMA4/IP66 provided that:

- the panel is smooth and the panel cutout is accurate;
- the mounting instructions are carefully followed.



DIN Panel Cutout Size

1/32 DIN panel cutout size

45.0mm +0.6mm -0.0mm (1.77in. +0.02in. -0.0in.) wide 22.2mm +0.3mm -0.0mm (0.87in. +0.01in. -0.0in.) high 9.5mm (0.374in) maximum panel thickness.

Minimum Spacing



MOUNTING

To mount a Controller proceed as follows:

- **1.** Check that the controller is correctly orientated and then slide the unit into the cutout.
- 2. Slide the panel clamp over the controller sleeve pressing it firmly against the panel until the controller is held firmly.
- The controller front bezel and circuit board assembly can be unplugged from the sleeve. Grasp the bezel firmly by the recesses on each side and pull. A screwdriver can be used as a lever if required.
- 4. When refitting the bezel assembly it is important to press it firmly into the sleeve until the latch clicks in order to compress the gasket and seal to NEMA4X/ IP66.

Cleaning

Wipe down with damp cloth (water only).

Note: The controller should be isolated before removing or refitting it in the sleeve, and electrostatic precautions should be observed when handling the controller outside the sleeve.

Electrical Installation

Supply Voltage

The controllers are designed for use with the following supply voltages:

100-240V 50-60 Hz ±10% 4.0VA

12V-24V (AC/DC) ±20% 4.0VA

Polarity is not required.

The controllers are fitted with an internal 250mA time lag fuse.

Output Devices

Two output devices are fitted to the controllers.

- Solid state relay drive (SSd) 5Vdc +0/-15%, 15mA non-isolating. To switch a remote SSR (or logic)
- **2.** Miniature power relay (rLY) 2A/250V resistive, Form A/SPST contacts.

Output Device Allocation

Either output device may be chosen as the output device for the main setpoint (SP1), the remaining device being automatically allocated to the second setpoint (SP2). Choose the most suitable output device arrangement for the application and wire accordingly. Refer to factory set output options.

Wiring the Connector

Prepare the cable carefully, remove a maximum of 7mm (0.275in) insulation and ideally tin to avoid bridging. Prevent excessive cable strain. Maximum recommended wire size: 32/0.2mm 1.0mm2 (18AWG/0.04in2).

Inductive Loads

To prolong relay contact life and suppress interference, it is recommended engineering practice to fit a snubber (0.1uf/100 ohms).

ACAUTION

Snubber leakage current can cause some electromechanical devices to be held ON. Check with the manufacturers specifications.

EN61010 - /CSA 22.2 No 1010.1 92

Compliance shall not be impaired when fitted to the final installation.

Designed to offer a minimum of basic insulation only. The body responsible for the installation is to ensure that supplementary insulation suitable for Installation Category II or III is achieved when fully installed. To avoid possible hazards, accessible conductive parts of the final installation should be protectively earthed in accordance with EN6010 for Class 1 Equipment.

Output wiring should be within a protectively earthed cabinet.

Sensor sheaths should be bonded to protective earth or not be accessible.

Live parts should not be accessible without the use of a tool.

When fitted to the final installation, an IEC/CSA AP-PROVED disconnecting device should be used to disconnect both LINE and NEUTRAL conductors simultaneously.

A clear instruction shall be provided not to position the equipment so that it is difficult to operate the disconnecting device.

Typical Connection Diagram

The SSR driver output is allocated to SP1 and wired to switch the load (heater) using an SSR

- **F1 Fuse:** time lag type to IEC127. CSA/UL rating 1A 250Vac
- F2 Fuse:High Rupture Capacity (HRC) Suitable
for maximum rated load current
- **S1 Switch:** IEC/CSA/UL Approved disconnecting Device



Specifications

Thermocouple

9 types Standards: CJC Rejection: External Resistance:

IPTS/68/DIN 43710 20:1 (0.05°/°C) typical 100Ω maximum

Resistance Temperatrue Detector

RTD-2/Pt100 2 Wire Standards:

Bulb Current:

DIN 43760 (100Ω 0°C/138.5Ω 100°C Pt) 0.2mA maximum

Linear Process Inputs

0-20 mV, 4-20 mV 0-20 mA, 4-20 mA (must use 1Ω resistor)

Applicable to all Inputs SM = sensor maximum

Calibration Accuracy:	±0.25%SM ±1°C
Sampling Frequency:	input 10Hz, CJC 2 sec.
Common Mode Rejection:	Negligible effect up to
	140dB, 240V, 50-60Hz
Series Mode Rejection:	60dB, 50-60Hz
Temperature Coefficient:	150ppm/°C SM
Reference Conditions:	22°C ±2°C, rated voltage
	after 15 minutes settling
	time.
Output Devices	

SSd/SSd1/SSd2:	solid state relay driver: To
	switch a remote SSR 5Vdc
	+0/-15% 15mA non-isolated
Miniature power relay:	form A/SPST contacts
	(AgCdO)
rLY and rLY1:	2A/250ac resistive load
rLY2:	1A/250ac resistive load

General

Displays:

Main, 4 Digits high brightness green LED. 10mm (0.4") high. Digital range -199 to 9999 Hi-res mode -199.9 to 999.9 LED output indicators flashing SP1 square, green; SP2 round, red 3 elastomeric buttons

Keypad:

Environmental

Humidity: Altitude: Installation: Pollution: Protection: EMC emission:

EMC immunity: Ambient: Mouldings:

Weight:

Max 80% up to 2000M Categories II and III Degree II NEMA 4X, IP66 EN50081-1 FCC Rules 15 subpart J Class A EN50082-2 0-50°C (32-130°F) flame retardant polycarbonate 110g (3.9 oz)

Ordering Information

	3204 1/	32 DIN /	32 DIN Auto Tuning PID Controller					
3204	Compac couple, soak pro front pa 3 year v	ct 1/32 [RTD or ogram, la nel; large varranty.	DIN AutoTune PID controller with the following standard features: User selectable inputs (thermo- r 0-20, 4-20 mV or mA** linear process inputs), dual outputs for heat, cool and alarm; single ramp & latching alarm and limit control capabiliy, with user program security levels. Also, NEMA 4X / IEC IP66 ge 4-digit display. Optional features include RS-485 or RS-232 ModBus RTU digital communications. y. Approvals: UL, cUL, CE					
	Code	Output	Dutputs 1 and 2, Control Output or Alarm					
	11*	Two Re	lay Outpu	uts: Outp	out 1: 2 Amps at 250 VAC. Output 2: 1 Amp at 250 VAC. Both resistive loads			
	71	Two Ou	tputs: Ou	utput 1: S	olid State Relay Drive, 5 Vdc, 15mA. Output 2: Relay, 1 Amp at 250 VAC			
	77	Two So	lid State I	Relay Dri	ve Outputs: 5 Vdc, 15mA (X 2)			
		Code						
		0	Add to complete model number Special Configuration					
		9						
		1	Code	Option	S			
			0	None				
			1	RS-485	Digital Communications Interface			
			2	RS-232	Digital Communications Interface			
				Code	Power Supply			
				0	90-264 Vac			
				1	12-24 VDC/AC +/20%			
3204 -	71	0	0	0	Typical Model Number			

*2 Relay Output Code "11" is not available with the 12-24 VDC/AC Power supply option

**0-20 mA or 4-20 mA Linear input signal requires a 1Ω resistor

Sensor Selection

Option/Sen					
Thermoc	ouples		Linearity		
tc b	В	0 to 1800°C	32 to 3272°F	Pt-30%Rh/Pt-6%Rh	2.0*
tc E	Е	0 to 600°C	32 to 1112°F	Chromel/Con	0.5
tc J	J	0 to 800°C	32 to 1472°F	Iron/Constantan	0.5
tc K	K	-50 to 1200°C	-58 to 2192°F	Chromel/Alumel	0.25*
tc L	L	0 to 800°C	32 to 1472°F	Fe/Konst	0.5
tc n	Ν	-50 to 1200°C	-58 to 2192°F	NiCrosil/NiSil	0.25*
tc r	R	0 to 1600°C	32 to 2912°F	Pt-13%Rh/Pt	2.0*
tc s	S	0 to 1600°C	32 to 2912°F	Pt-10%Rh/Pt	2.0*
tc t	Т	-200 / 250°C	-273 / 482°F	Copper/Con	0.25*

Resistance Temperature Detector				
rtd	-200 / 400°C -273 / 752°F Pt100/RTD-2 0.2			

Linear Process Inputs (Input mV range: 0 to 50mV)				
Displays	0 - 20mV	4 - 20mV	setpoint limits	
Lin1	0 - 100		0 to 400	± 0.5%
Lin2		0 - 100	-25 to 400	± 0.5%
Lin3	0 - 1000		0 to 3000	± 0.5%
Lin4		0 - 1000	-250 to 3000	± 0.5%
Lin5	0 - 2000		0 to 3000	± 0.5%

Notes: 1 Linearity: 5-95% sensor range

2* Linearity B: 5° (70° - 500°C) K/N:1° >350°C exceptions: R/S: 5°<300°C T:1°

<- -25° >150°C RTD/Pt100: 0.5° <-100°C

Limited Warranty:

Please refer to the Chromalox limited warranty applicable to this product at http://www.chromalox.com/customer-service/policies/termsofsale.aspx.

Chromalox, Inc. 1347 Heil Quaker Boulevard Lavergne, TN 37086 (615) 793-3900 www.chromalox.com